

# Understanding the Search Behaviour of Greedy Best-First Search

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# Introduction

# Open Questions

- Which states is GBFS **guaranteed** to expand?
- Which states is GBFS guaranteed **not** to expand?
- Which states may GBFS **potentially** expand?

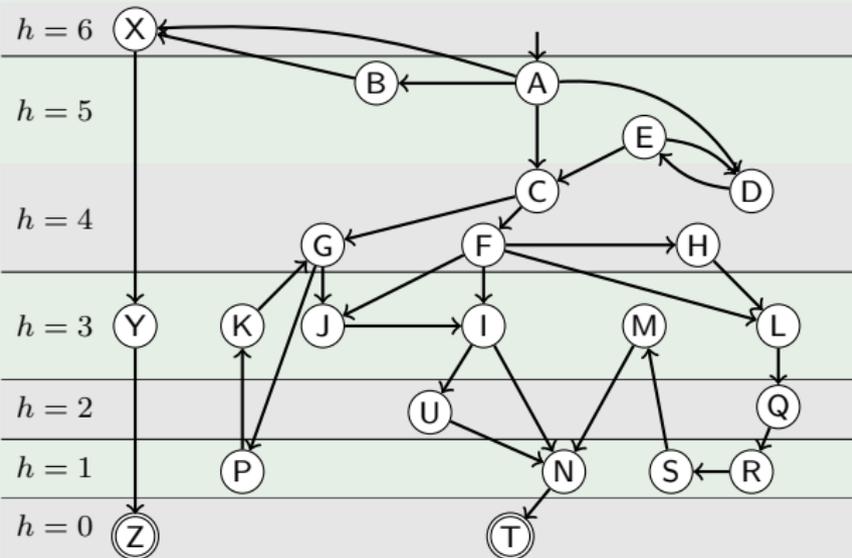
**Note:** Partly answered for  $A^*$  (based on  $f$ -value) and for GBFS (based on high-water mark).

# State Space Topology

- **state space**: generative model with **initial state**, **goal states** and **successor** function
- **heuristic**: assigns non-negative values to states
- **state space topology**: **state space** + **heuristic**

# State Space Topology

## Example



# Greedy Best-First Search

- **expansion** : generates **successors** of a state
- **greedy best-first search**: iteratively **expands** states with lowest **heuristic** value
- **tie-breaking**: selects a state among states with equal **heuristic** values

# Greedy Best-First Search

## Example

$h = 6$

$h = 5$

$h = 4$

$h = 3$

$h = 2$

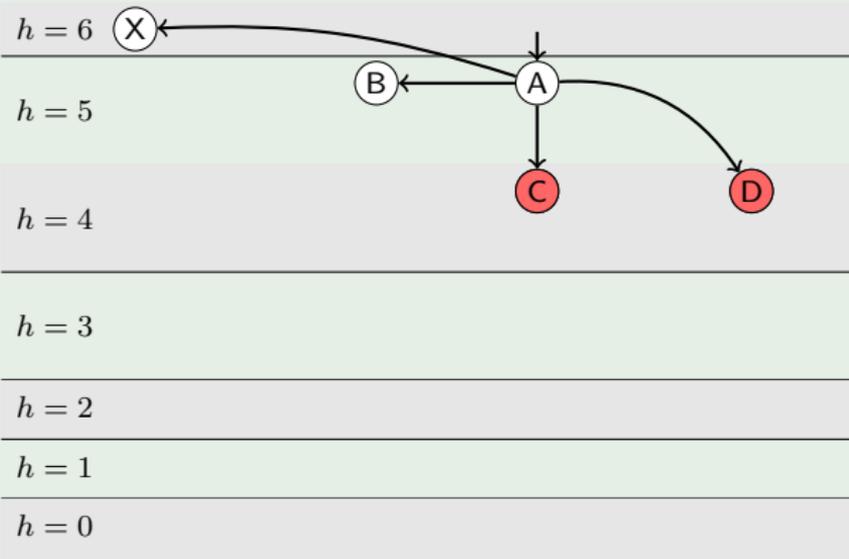
$h = 1$

$h = 0$



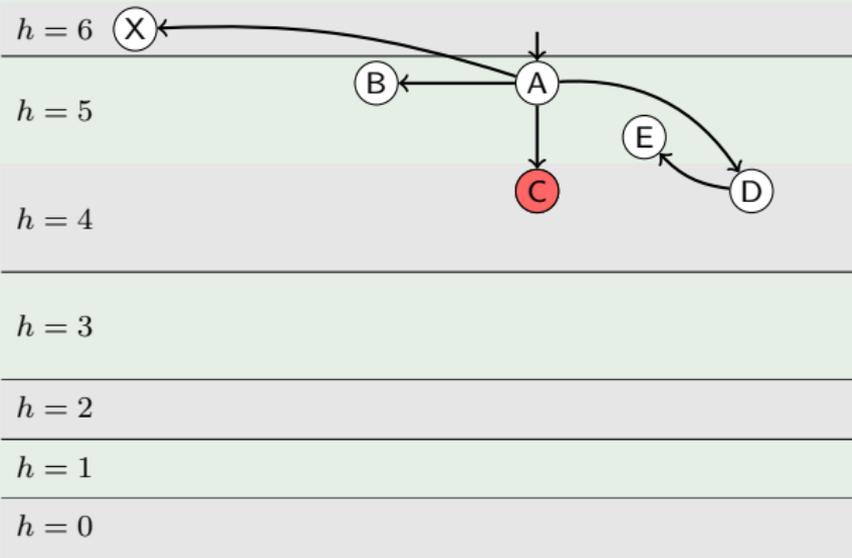
# Greedy Best-First Search

## Example



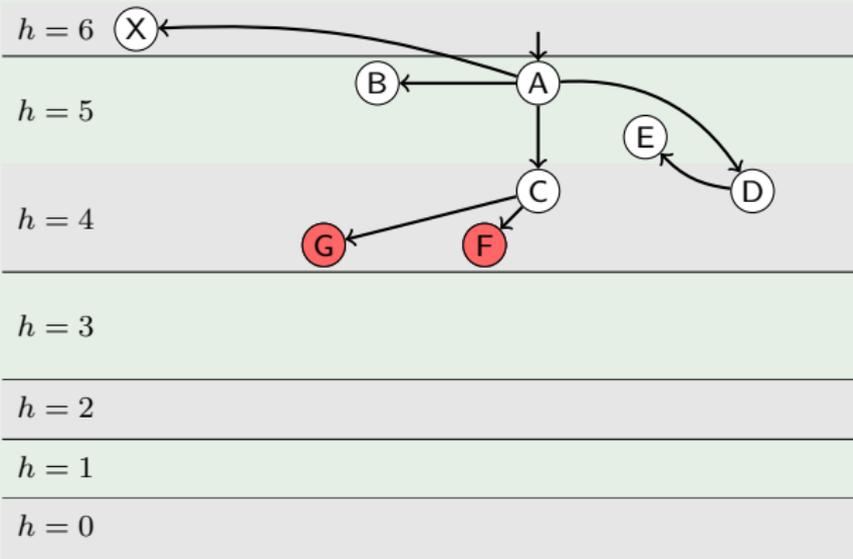
# Greedy Best-First Search

## Example



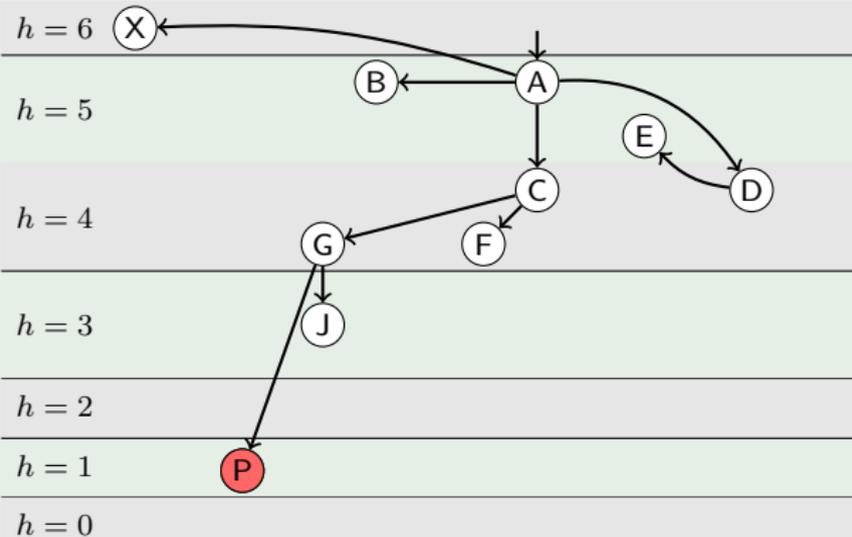
# Greedy Best-First Search

## Example



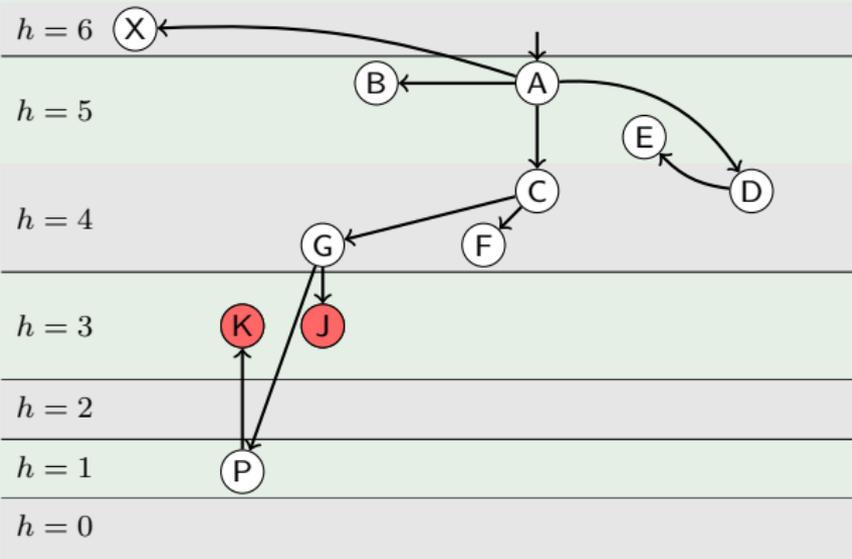
# Greedy Best-First Search

## Example



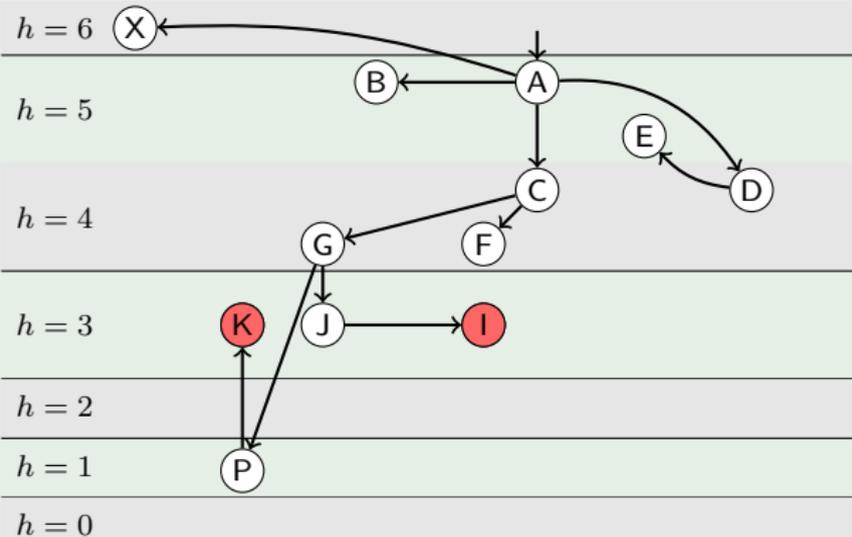
# Greedy Best-First Search

## Example



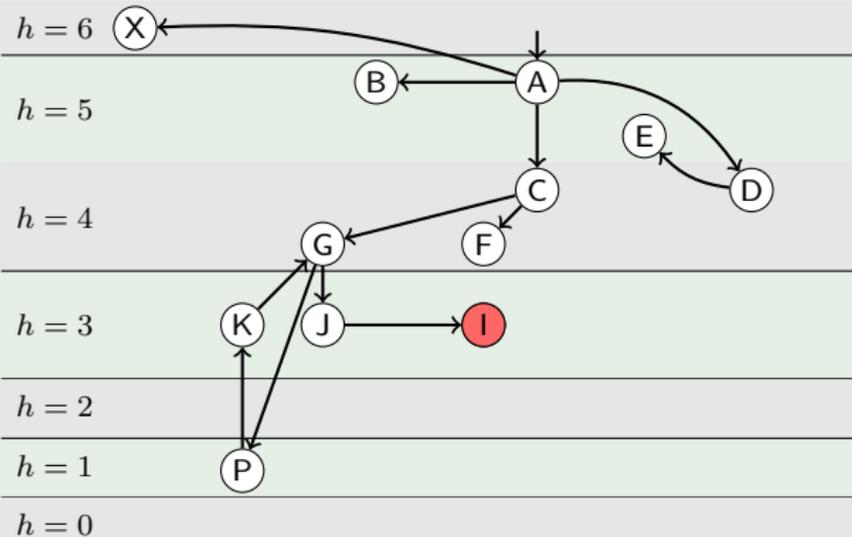
# Greedy Best-First Search

## Example



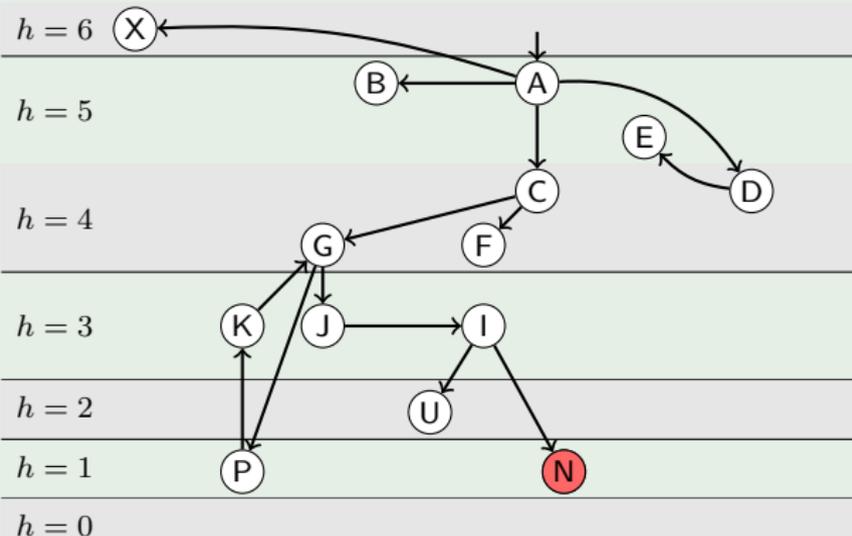
# Greedy Best-First Search

## Example



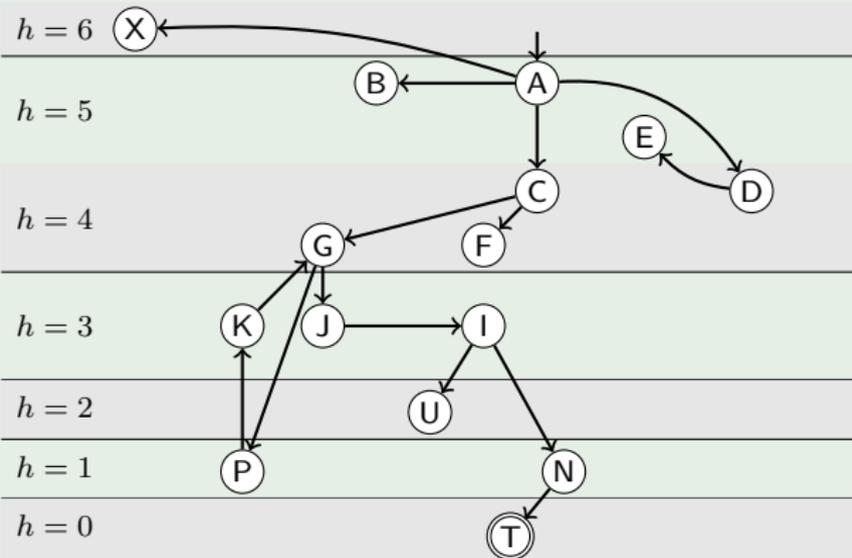
# Greedy Best-First Search

## Example



# Greedy Best-First Search

## Example



# High-Water Marks

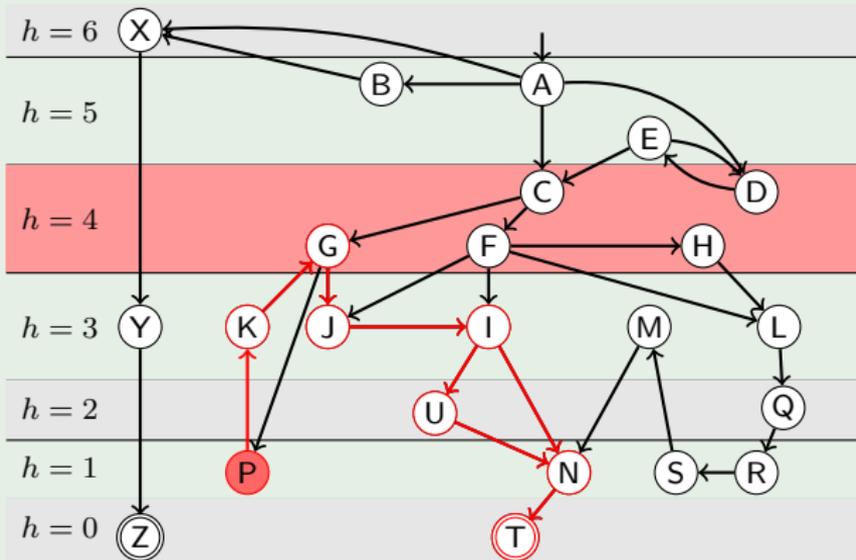
# High-Water Marks

## Definition (high-water mark)

The **high-water mark** is the largest **heuristic** value of a state that **GBFS** starting from a state (or a set of states) must **expand** before reaching a **goal state**.

# High-Water Mark of State

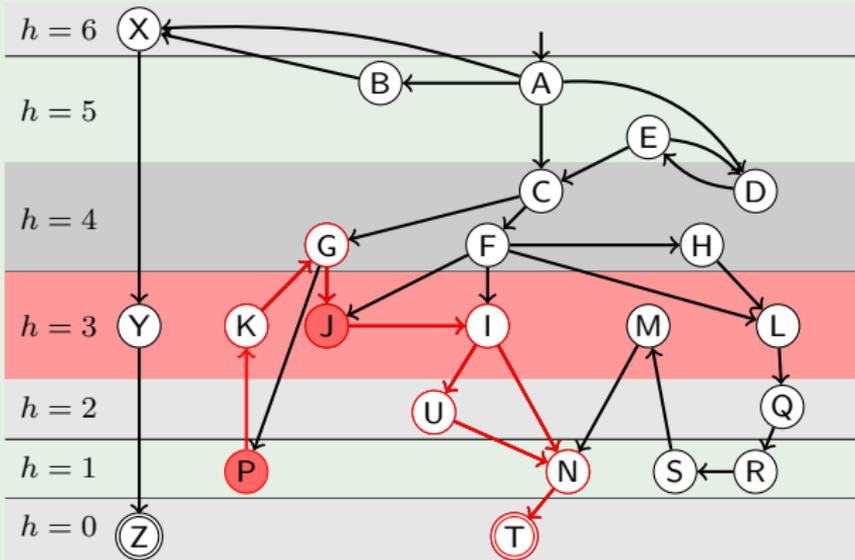
## Example



high-water mark of state  $P$ : 4

# High-Water Mark of State Set

## Example



high-water mark of state set  $\{J, P\}$ : 3

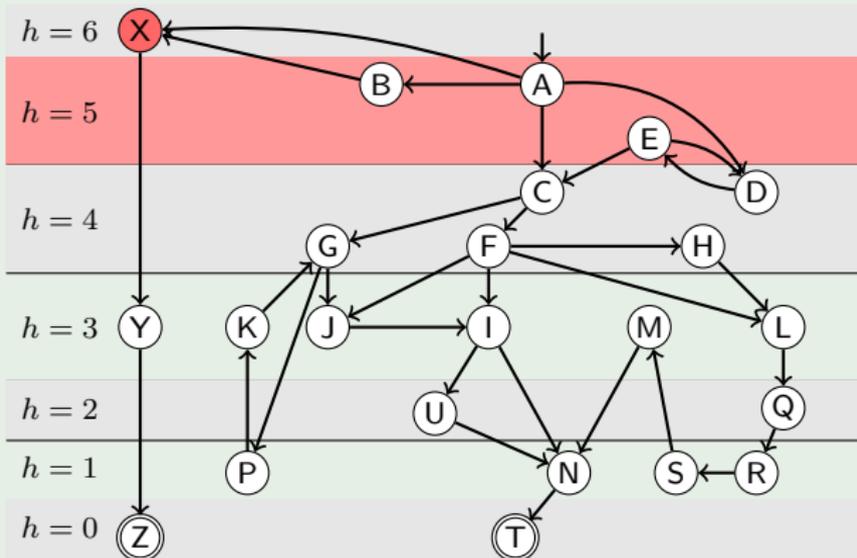
# Earlier Result

Theorem (Wilt & Ruml, SoCS 2014)

*GBFS is guaranteed to not expand a state whose heuristic value is larger than high-water mark of initial state.*

# Earlier Result

## Example



never expanded states:  $\{X\}$

# Benches

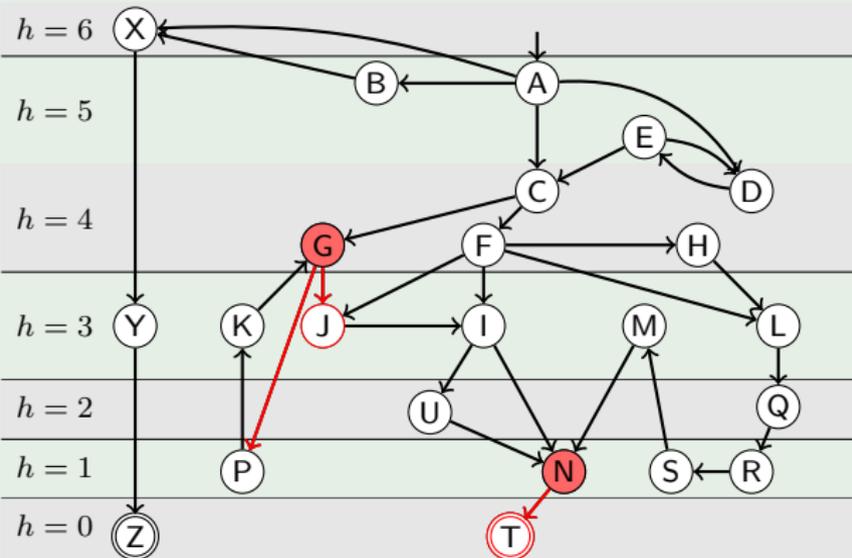
# Bench Exit States

## Definition (bench exit state)

**Bench exit state** is a state which has a **successor** that has lower **high-water mark** or that is a **goal state**.

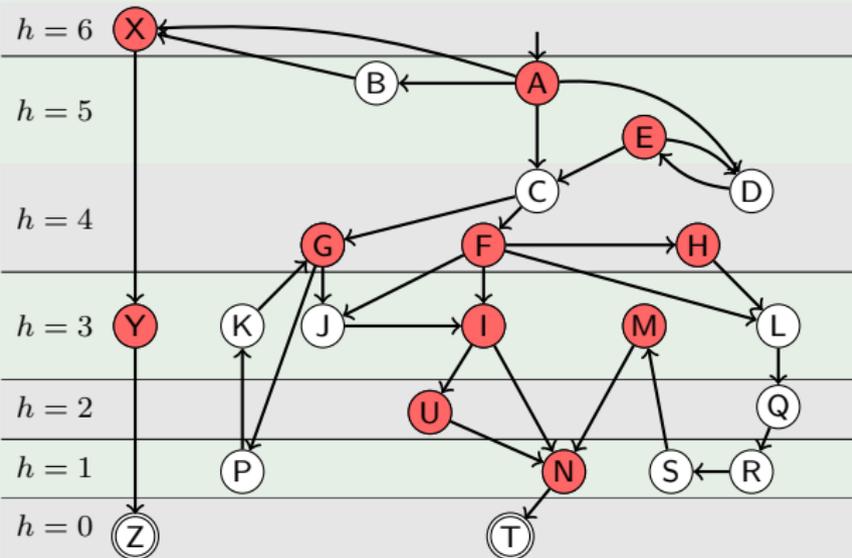
# Bench Exit States

## Example



# Bench Exit States

## Example



# Bench Exit Property

## Theorem (bench exit property)

*Whenever GBFS expands a bench exit state, all previously generated states will never be expanded for the rest of the algorithm run.*

Note: GBFS makes **progress** when bench exit state is expanded.

# Bench Exit Property

## Example

$h = 6$



$h = 5$

$h = 4$

$h = 3$

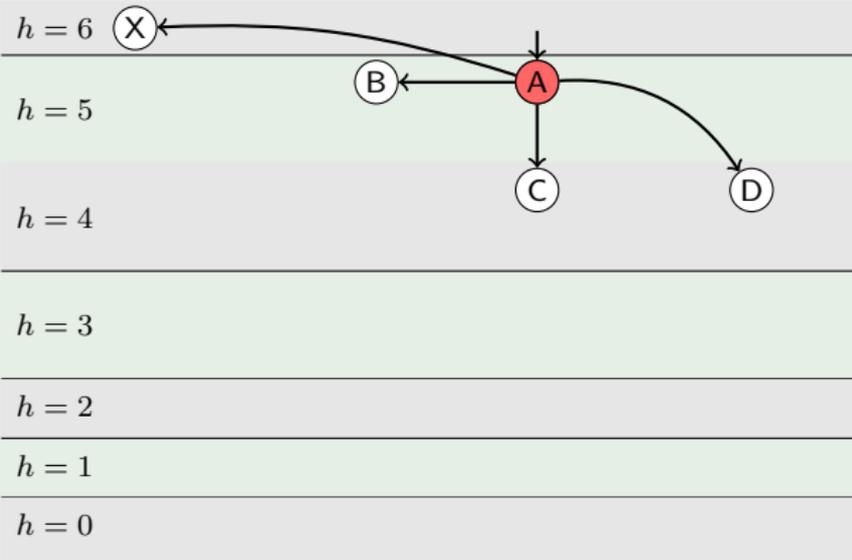
$h = 2$

$h = 1$

$h = 0$

# Bench Exit Property

## Example



# Bench Exit Property

## Example

$h = 6$  (X)

$h = 5$

(B)

$h = 4$

(C)

(D)

$h = 3$

$h = 2$

$h = 1$

$h = 0$

# Bench Exit Property

## Example

$h = 6$  (X)

$h = 5$

$h = 4$

$h = 3$

$h = 2$

$h = 1$

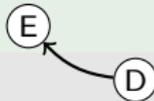
$h = 0$

(B)

(C)

(E)

(D)



# Bench Exit Property

## Example

$h = 6$  (X)

(B)

$h = 5$

(E) ← (D)

$h = 4$

(G) ← (C) → (F)

$h = 3$

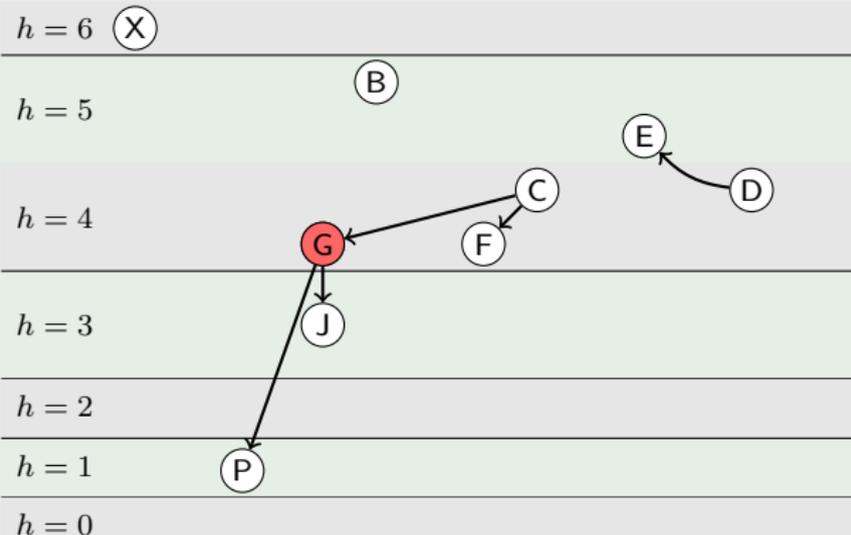
$h = 2$

$h = 1$

$h = 0$

# Bench Exit Property

## Example



# Bench Exit Property

## Example

$h = 6$

---

$h = 5$

$h = 4$

---

$h = 3$

ⓐ

$h = 2$

---

$h = 1$

ⓑ

$h = 0$

# Bench Exit Property

## Example

$h = 6$

---

$h = 5$

---

$h = 4$

---

$h = 3$



$h = 2$

---

$h = 1$



$h = 0$

---

# Bench Exit Property

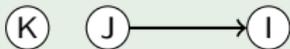
## Example

$h = 6$

$h = 5$

$h = 4$

$h = 3$



$h = 2$

$h = 1$



$h = 0$

# Bench Exit Property

## Example

$h = 6$

$h = 5$

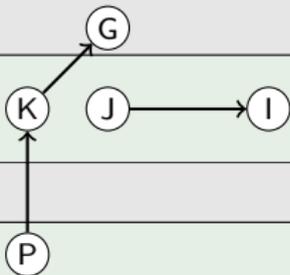
$h = 4$

$h = 3$

$h = 2$

$h = 1$

$h = 0$



# Bench Exit Property

## Example

$h = 6$

$h = 5$

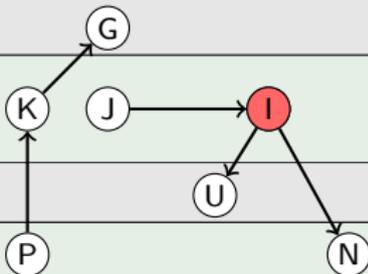
$h = 4$

$h = 3$

$h = 2$

$h = 1$

$h = 0$



# Bench Exit Property

## Example

$h = 6$

---

$h = 5$

$h = 4$

---

$h = 3$

$h = 2$

U

$h = 1$

N

$h = 0$

# Bench Exit Property

## Example

$h = 6$

---

$h = 5$

$h = 4$

---

$h = 3$

$h = 2$

---

U

$h = 1$

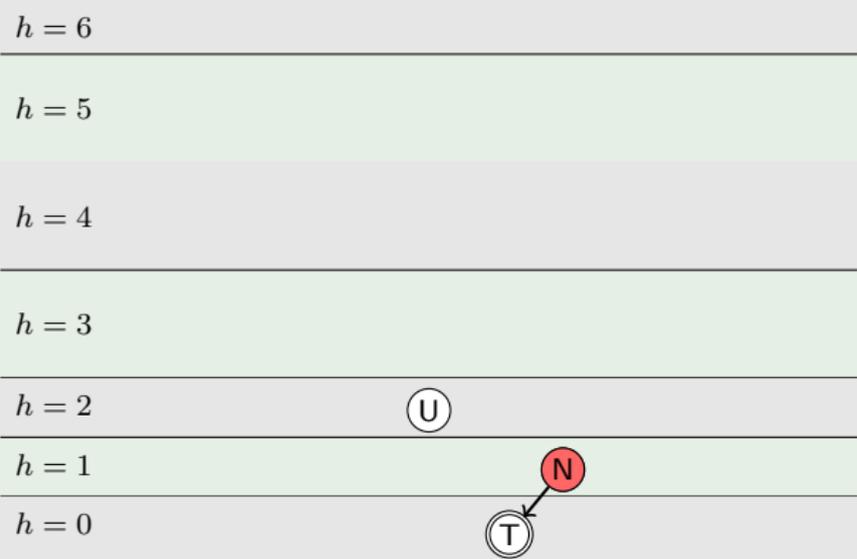
---

N

$h = 0$

---

T



# Bench Exit Property

## Example

$h = 6$

---

$h = 5$

$h = 4$

---

$h = 3$

$h = 2$

---

$h = 1$

$h = 0$



# Benches

## Definition (bench)

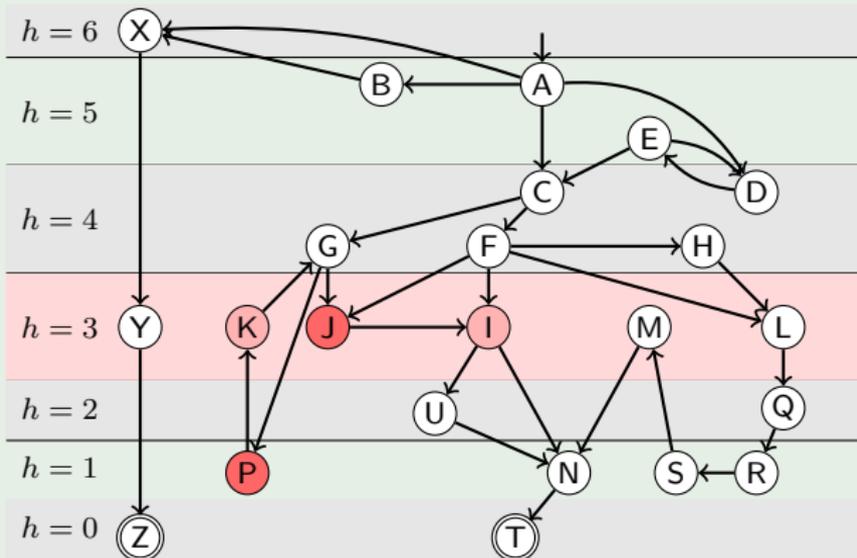
A **bench** contains all states that **GBFS** starting with a given set of states can **expand** until **expansion** of a **bench exit state**.

It is empty if the given set of states contains a **goal state**.

It is associated with **high-water mark** of the given set of states.

# Benches

## Example



states on bench defined by  $\{J, P\}$ :  $\{I, J, P, K\}$

# Bench Transition Systems

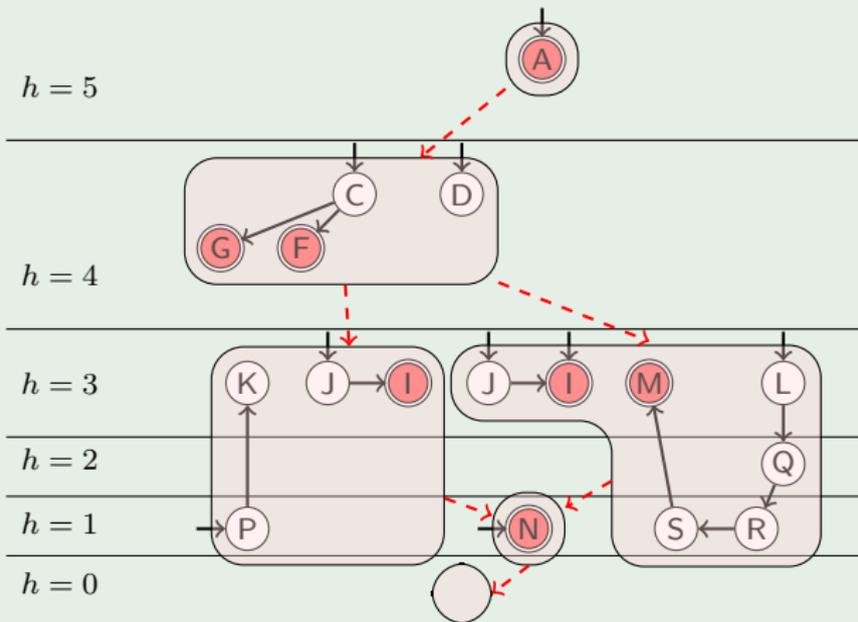
## Definition (bench transition system)

A **bench transition system** contains all benches which are reachable from the bench that starts with the initial state.

A **successor bench** is defined by the successor states of a bench exit state.

# Bench Transition Systems

## Example



# Results

## Theorem

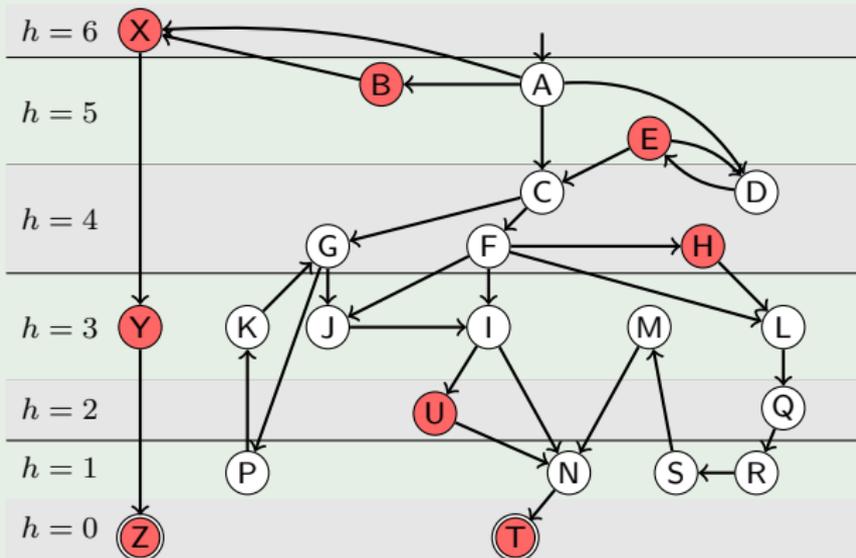
*GBFS potentially expands a state if it is on at least one bench from bench transition system.*

## Theorem

*GBFS is guaranteed to not expand a state that is not on a bench of the bench transition system.*

# Results

## Example



never expanded states:  $\{B, E, H, T, U, X, Y, Z\}$

# Craters

# Surfaces

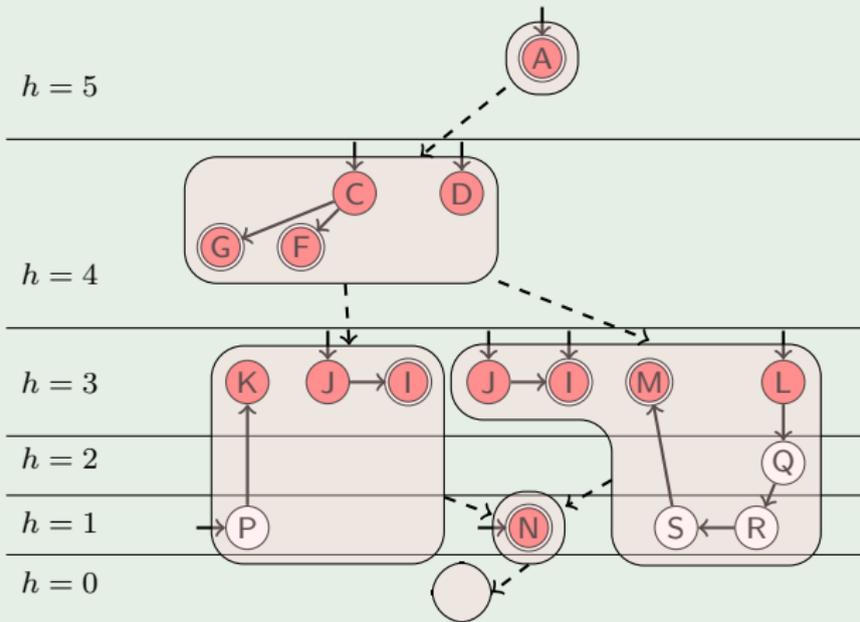
## Definition (surface)

A state is on the **surface** of a **bench** if its **heuristic** value is the **high-water mark** of the **bench**.

**Note:** Is often called **heuristic plateau** or **uninformed heuristic region**.

## Surfaces

## Example



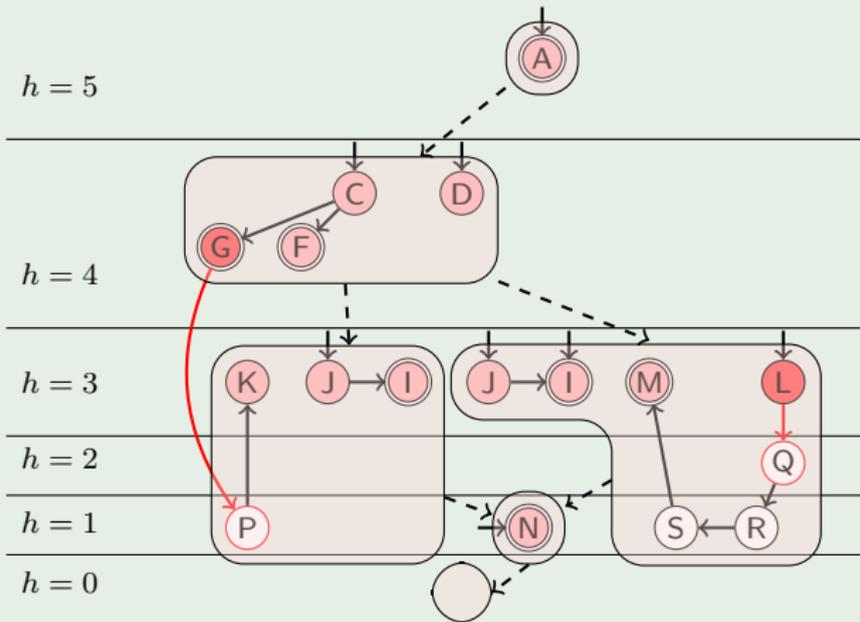
# Crater Entry States

## Definition (crater entry state)

A **crater entry state** is a state that is on the **surface** of a **bench** and that has a **successor** which is on a **bench** but not on a **surface**.

# Crater Entry States

## Example



# Craters

## Definition (crater)

A **crater** contains all states that **GBFS** starting with a given **crater** entry state expands until expansion of a state from the **surface**.

**Note:** Is often called **local minimum** or **uninformed heuristic region**.



# Result

## Theorem

*Whenever GBFS expands a crater entry state  $s$ , then GBFS is guaranteed to expand all states in the crater defined by  $s$ .*

# Conclusion

# Conclusion

- exact **characterization** of potentially expanded and never expanded states
- **characterization** of surely expanded states given some conditions
- better **understanding of search behaviour** and **search progress**