



AUTOMATIC INSTANCE GENERATION FOR CLASSICAL PLANNING

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EVALUATION IN CLASSICAL PLANNING

Usually, the evaluation in Planning follows the ICAPS/IPC way:

- Measure coverage.
- Time limit 5 or 30 minutes.
- Memory limit 2-8 GB.
- Use the benchmarks from the **International Planning Competition**.

Why? Having a standard evaluation setting is beneficial:

- *Reproducibility.*
- *Interpretability.*
- *Avoid hand picking results.*

Benchmarks are an important part of evaluation in Planning

But... The IPC benchmark set has some flaws

- Different number of instances per domain.
- **Instance scaling:** On some domains, IPC benchmarks do not show differences between planners even if they exist.

	IPC			
	#	L	D	O
Grid	5	5	5	5
Driverlog	20	20	20	20
Rovers	40	40	40	40
Snake	20	5	15	12
Total	85	70	80	77

Coverage of LAMA (L), DUAL-BFWS(D) and OLCFF (O)

AUTOSCALE'21: THE BENCHMARK SET

New set of benchmarks for Optimal and Satisficing Planning:

- Uniform number of instances (30 instances)
- Includes almost all IPC STRIPS domains
- Optimization based on IPC'11, IPC'14 AND IPC'18 planners → Useful to evaluate current and future planners.
- Example of Evaluation using Autoscale'14 (which didn't use IPC'18 planners):

	IPC				Autoscale			
	#	L	D	O	#	L	D	O
Grid	5	5	5	5	30	17	14	16
Driverlog	20	20	20	20	30	15	10	25
Rovers	40	40	40	40	30	30	23	28
Snake	20	5	15	12	30	6	19	16
Total	85	70	80	77	120	68	66	85

Coverage of LAMA (L), DUAL-BFWS(D) and OLCFF (O)

AUTOSCALE: AN AUTOMATIC TOOL TO SELECT INSTANCES

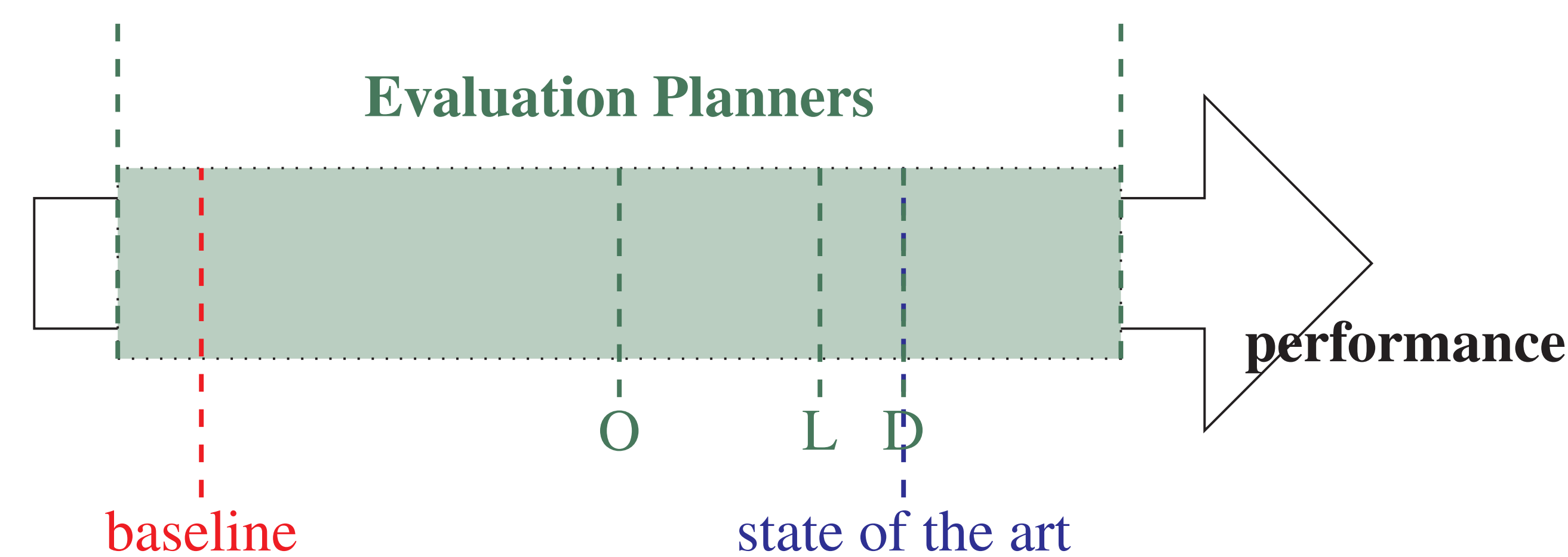
Principles:

- Useful to evaluate current planners.
- Avoid bias.
- Keep the Spirit of the Domain.

Rules:

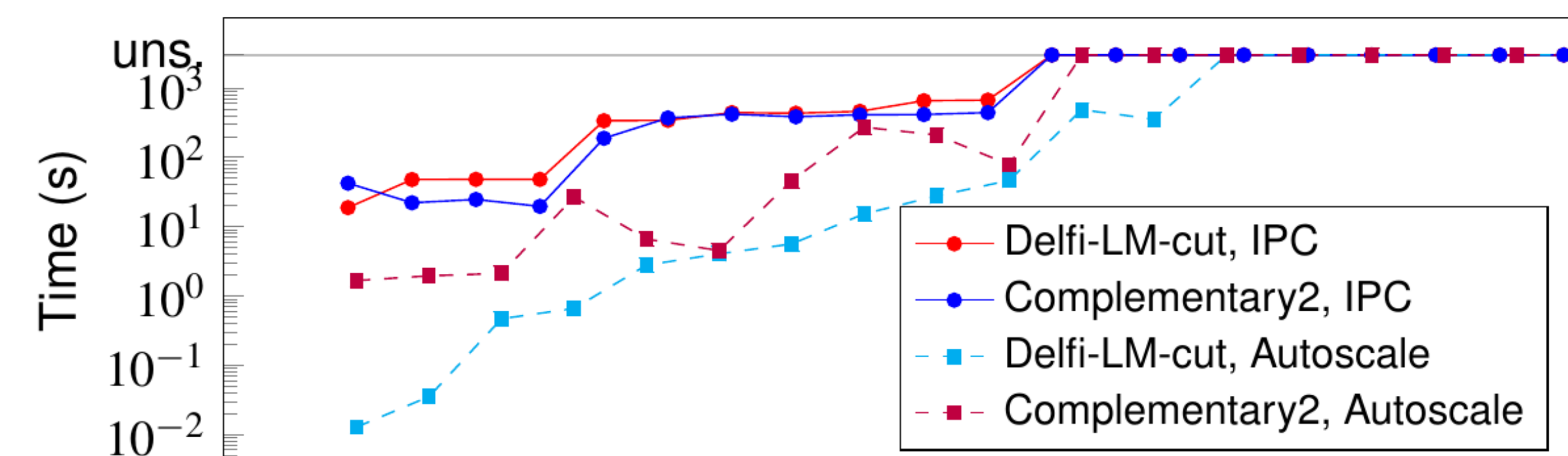
1. **Agnostic to individual Planner Performance:**

Don't consider the individual results of all planners available for the optimization (only the best and the worst per instance).



2. **Smooth Scaling:** The instance set should have:

- Easy instances
- Hard instances
- Scale smoothly



3. **Parameter-based Selection:** Avoid selecting the random seed.

4. **Sequence-based Selection:** The parameter configurations can be organized in one or more sequences.

5. **User Constraints:** The domain designer specifies guidelines on which parameters to scale.

Optimization Process

- Generate candidate sequences with smooth scaling (using SMAC)
- Choose sub-sequences including easy, hard and diverse instances

C	S	I	time(s)	C	S	I	time(s)	C	S	I	time(s)	C	S	I	time(s)
5	6	3	10.1	1	3	2	1.8	1	5	4	4.2	1	3	5	2.8
6	7	3	25.6	1	4	2	2.2	1	6	4	21	1	4	5	3.7
7	8	3	101.7	1	5	2	2.9	1	7	4	62	1	5	5	6.1
9	10	3	300	1	6	2	4.5	1	8	4	250	1	6	5	16
10	11	3	900	1	7	2	8.3	2	10	4	990	1	7	5	62
11	12	3	2700	1	8	2	26	2	11	4	4000	2	9	5	200
13	14	3	8100	1	9	2	120	2	12	4	16000	2	10	5	660

HOW TO USE AUTOSCALE TO GENERATE INSTANCE SETS?

```
generator_command = "nomystery -l {locations}
-p {packages} -n {edgefactor} -m {edgeweight}
-c {constrainedness} -s {seed} -e 0"
parameters = [
  LinearParam("locations", lower_b=3, upper_b=10,
  lower_m=0.1, upper_m=1),
  LinearParam("packages", lower_b=2, upper_b=20, lower_m=1),
  ConstantParam("edgefactor", "1.5"),
  ConstantParam("edgeweight", "25"),
  EnumParam("constrainedness", [1.1, 1.5, 2.0])]
```

EXPERIMENTS

How evaluate the quality of a benchmark set?

- **Coverage range:**
 - Some instances are solved by all planners
 - No planner solves all instances
- **Comparisons:** pairs (X,Y) of planners with different coverage

Comparison between Autoscale'14 and IPC:

- Instance Selection: 6 planners up to IPC'14
- Evaluation: 8 planners from IPC'18

Domain	#IPC	OPT	AGL	Domain	#IPC	OPT	AGL
Barman	34/40	+12	+19	Nomystery	20	+10	+4
Blocksworld	35	+6	+26	Openstacks	70	-17	+25
Childsnack	20	+8	+1	Parking	40	-2	+5
Data-Network	20	-2	+2	Rovers	40	-4	+20
Depots	22	0	+25	Satellite	36	+5	+2
Driverlog	20	+5	+25	Scanalyzer	50	0	+8
Elevators	50	-3	+11	Snake	20	-1	0
Floortile	40	-3	+7	Storage	30	+6	+1
Grid	5	+7	+21	TPP	30	+2	+11
Gripper	20	0	+7	Transport	70	-8	+14
Hiking	20	+4	+3	Visitall	40	0	+17
Logistics	63	-3	+4	Woodworking	50	+5	+14
Miconic	150	0	0	Zenotravel	20	+4	+22

CONCLUSIONS

1. A tool to automatically select instances which:

- Create useful benchmarks
- Is based on sequences of parameters
- Avoids bias with respect of the planners used
- Keeps the spirit of the domain

2. **Autoscale'21:** New benchmark set: **TRY IT OUT!**

<https://github.com/AI-Planning/autoscale>
<https://github.com/AI-Planning/autoscale-benchmarks>