ARTEFACT DETECTION AND SEGMENTATION BASED ON A DEEP LEARNING SYSTEM

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ABSTRACT

This paper presents the results of detection and segmentation of artefact from endoscopic video frames for EAD2020 competition. In this competition, a deep learning based system is applied, which is built upon RetinaNet. Since RetinaNet employs a one-stage method that lacks facilitating masks of segmented objects, inspired by the work of real-time instance segmentation, this system accomplishes object segmentation through two parallel branches to generate a set of prototype masks and to predict per-object mask coefficients respectively. Overall, top 7 (out of 32 entries) position was achieved in this competition on the leaderboard.

1. METHODS

Figure 1 illustrates the network system applied in this competition [1, 2, 3, 4, 5, 6, 7, 8, 9] built upon RetinaNet. It accomplishes object segmentation through two parallel strands (Prototype and Prediction coefficient), which are to generate a set of prototype masks and to predict per-object mask coefficients respectively. The backbone model of Resnet101 is applied for all three tasks.

2. RESULTS

Table 1 presents the final results submitted from this work whereas Table 2 gives the mAP for segmentation when 95% the overall classification accuracy was 63%. Although the results remain on the top 7, it is felt more enhancement is needed to further improve this model to improve its robustness.

3. REFERENCES

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Model parameters	\mathbf{Score}_d	Rank
Epoch = 412,	0 2020 0 0768	18
Threshold $= 0.17$	0.2020 0.0708	10
Epoch = 226,	0 2205 0 0843	7
Threshold = 0.13	0.2205 0.0845	

Table 1. Leaderborad scores for the two submissions put inin the EAD2020 competition.

Region type	mAP at IoU thresholds				
	0.50	0.70	0.95	All	
box	77.85	61.64	0.99	47.42	
mask	76.91	61.51	0.87	46.17	

Table 2	2. The	mAP	values	for	segmentation
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Fig. 1. The network applied in competition.

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