# **SEQUENT CALCULI OF FIRST-ORDER LOGICS OF PARTIAL PREDICATES WITH EXTENDED RENOMINATIONS AND COMPOSITION OF PREDICATE COMPLEMENT**

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Досліджено нові класи програмно-орієнтованих логік – чисті першопорядкові логіки часткових квазіарних предикатів з розширеними реномінаціями та композицією предикатного доповнення. Описано відношення логічного наслідку в таких логіках, для цих відношень побудовано числення секвенційного типу. Наведено базові секвенційні форми цих числень та умови замкненості секвенцій. Для пропонованих числень доведено теореми коректності, теореми про існування контрмоделей та теореми повноти.

Ключові слова: логіка, частковий предикат, логічний наслідок, секвенційне числення, коректність, повнота.

Исследованы новые классы программно-ориентированных логик – чистые первопорядковые логики частичных квазиарных предикатов с расширенными реноминациями и композицией предикатного дополнения. Описаны отношення логического следствия в таких логиках, для этих отношений построены исчисления секвенциального типа. Приведены базовые секвенциальные формы этих исчислений и условия замкнутости секвенций. Для предложенных исчислений доказаны теоремы корректности, теоремы о существовании контрмоделей и теоремы полноты.

Ключевые слова: логика, частичный предикат, логическое следствие, секвенциальное исчисление, корректность, полнота.

We study new classes of program-oriented logical formalisms – pure first-order logics of quasiary predicates with extended renominations and a composition of predicate complement. For these logics, various logical consequence relations are specified and corresponding calculi of sequent type are constructed. We define basic sequent forms for the specified calculi and closeness conditions.

The soundness, completeness, and counter-model existence theorems are proved for the introduced calculi.

Key words: logic, partial predicate, logical consequence, sequent calculus, soundness, completeness.

### **Introduction**

Many different logic systems have been created (see, for example, [1]), which are used with success in computer science and programming. Usually, the classical logic of predicates [2] and special logics based on it are employed for this purpose. However, classical logic has fundamental limitations, which complicates its use. This brings to the fore the problem of building new, software-oriented logics. Such are the logics of partial quasiary predicates, built on the basis of a compositional-nominative approach common to logic and programming [3]. A number of different classes of quasiary predicate logics are described, in particular, in [3–6].

To solve a number of problems that arise in information and software systems, it is necessary to develop efficient proof searching procedures. Such procedures are provided by Gentzen-style sequent calculi. These calculi formalize the fundamental concept of logical consequence. A number of sequent calculi for different classes of program-oriented logics have been developed (see, e.g., [4–6]). The purpose of this work is to construct sequent calculi for new classes of such logics — pure first-order logics of quasiary predicates with extended renominations and the composition of the predicate complement. A characteristic feature of these logics is the presence of a special nonmonotonic operation (composition) of the predicate complement  $\Box$ . Operations of this type have been used in extensions of Floyd-Hoare program logics [7, 8] in the case of partial pre- and post-conditions. The logics of partial predicates with the composition of the predicate complement are proposed in [9], they are called LC. Propositional LCs are described in detail in [9], renominative and pure first-order LCs are considered in [10] and [11], various relationships of logical consequence in LC are investigated in [12].

Pure first-order logics of quasiary predicates are called  $L^{\bar{Q}}$  (logics of quantifier level). Their defining feature is the presence of quantification compositions.  $L^{\mathcal{Q}}$  with extended renominations and predicate-indicators of the presence of value for variables is called  $L_{\perp}^Q$ ,  $L_{\perp}^Q$  with the composition of the predicate complement is called  $L_{\perp}^Q$ . A number of sequent calculi in  $L_1^Q$  and in  $L_1^Q$ <sup>C</sup> are constructed in the paper, and the theorems of soundness and completeness are proved for such calculi. The main emphasis is on the construction of sequential numbers in  $L_{\perp}^{QC}$ .

Concepts that are not defined in this paper are interpreted in the sense of [6, 9, 12]. To facilitate reading, we provide the necessary definitions for further presentation.

## **1. Composition systems and languages of pure first-order logics**

Let <sup>V</sup>A be a set of all V-A-nominative sets and  $\{T, F\}$  is a set of Boolean values. We define V-A-quasiary predicate as a partial many-valued function  $Q: {}^V A \otimes {}^{\{T, F\}}$ . The set of values which many-valued predicate  $Q$  yields on argument (data)  $d \in \mathcal{A}$  is denoted  $Q[d]$ .

Let *V* be a set of names (variables) and *A* be a set of values. *V*-*A*-nominative set is defined as a partial singlevalued function d:  $V \otimes A$ . Nominative sets can be presented in the form  $[v_1 \mapsto a_1,...,v_n \mapsto a_n,...]$ , where  $v_i \in V$ ,  $a_i \in A$ ,  $v_i \neq v_i$ when  $i \neq j$ .

For nominative sets we define the parametric operation  $\|_{Z}$  of deleting components with names from  $Z \subseteq V$  as follows:  $d||_Z = \{v \mapsto a \in d | v \notin Z\}.$ 

The parametric operation of extended renomination  $\mathbf{r}_{x_1,\dots,x_n,1}^{v_1,\dots,v_n,u_1}$  $r_{x_1,...,x_n,\perp,...,\perp}^{v_1,...,v_n,u_1,...,u_m}$ : *v*<sub>1</sub>,...,*v*<sub>n</sub>,*u*<sub>1</sub>,...,*u*<sub>m</sub> : *V*<sub>A</sub>  $\mathbb{R}$  *V*<sub>A</sub>, where *v*<sub>i</sub>, *x*<sub>i</sub>, *u<sub>j</sub>*  $\in$  *V*, is specified [5] as

 $x_1,...,x_n, u_1$ <br> $x_n, \perp$  $r_{x_1,...,x_n,\perp,...,\perp}^{v_1,...,v_n,u_1,...,u_m}(d)$  $\lim_{x_1,\dots,x_n,\mu_1,\dots,\mu_m} (d) = d \big\|_{-\{v_1,\dots,v_n,\mu_1,\dots,\mu_m\}} \cup [v_1 \mapsto d(x_1),...,v_n \mapsto d(x_n)].$  In particular,  $r_{\perp}^x(d) = d \big\|_{-x}$ .

We use a special symbol  $\perp \notin V$  that denotes the absence of the variable value;  $d(x_i)$ <sup>†</sup> means that a component with the name  $v_i$  is absent.

A simpler notation for sequences  $y_1, ..., y_n$  will be used:  $\overline{y}$ . Thus, instead of  $r_{x_1,...,x_n,1}^{y_1,...,y_n, u_1}$  $\Gamma_{x_1,...,x_n,\perp,...,\perp}^{v_1,...,v_n,u_1,...,u_m}$  $\lim_{x_1,\dots,x_n,\perp,\dots,\perp}$ , we will write  $\mathbf{r}_{\overline{x},\perp}^{\overline{v},\overline{u}}$ .

Traditional renomination  $r_{\overline{x}}^{\overline{v}}$  [2–4] is a special case of extended renomination  $r_{\overline{x},\perp}^{\overline{v},\overline{u}}$ .

**Statement 1.** Given  $d(z)$  **f**, we obtain  $\mathbf{r}_{\overline{x},\perp,z}^{\overline{v},\overline{u},y}(d) = \mathbf{r}_{\overline{x},\perp,z}^{\overline{v},\overline{u},y}(d)$  and  $\mathbf{r}_{\overline{x},\perp,z}^{\overline{v},\overline{u},z}(d) = \mathbf{r}_{\overline{x},\perp}^{\overline{v},\overline{u}}(d)$ .

Successive renominations  $r_{\overline{x},\overline{a},\perp,\perp}^{\overline{u},\overline{s},\overline{v},\overline{t}}$  an be represented [5] by one renomination denoted  $r_{\overline{x},\overline{a},\perp,\perp}^{\overline{u},\overline{s},\overline{z},\overline{t}}$ we call it the *convolution* of  $\mathbf{r}_{\overline{x},\overline{a},\perp,\perp}^{\overline{a},\overline{s},\overline{w},\overline{t}}$  and  $\mathbf{r}_{\overline{y},\overline{c},\perp,\perp}^{\overline{v},\overline{s},\overline{z},\overline{t}}$ . For any  $d \in M$  we get  $\mathbf{r}_{\overline{x},\overline{a},\perp,\perp}^{\overline{a},\overline{s},\overline{w},\overline{t}}[\overline{y},\overline{s$ 

In this paper we study many-valued predicates of relational type – *R-*predicates [3, 6], denoted as mappings from *VA* to the set of Boolean values  $\{T, F\}$ . Each *R*-predicate *Q* can be defined by its truth domain  $T(Q) = \{d \mid T \in Q[d]\}$  and falsity domain  $F(Q) = \{d \mid F \in Q[d]\}$ . We specify the undefinedness domain of *R*-predicate *Q* as  $\perp (Q) = \overline{T(Q) \cup F(Q)}$ . We call *R*-predicate *Q* monotone if  $d_1 \subseteq d_2 \Rightarrow Q[d_1] \subseteq Q[d_2]$ .

A name  $x \in V$  is unessential for *R*-predicate Q, if for any  $d_1, d_2 \in V$  we have:  $d_1 ||_{-x} = d_2 ||_{-x} \Rightarrow Q[d_1] = Q[d_2]$ .

*Q* is a partial single-valued *R*-predicate (*P*-predicate), if  $T(Q) \cap F(Q) = \emptyset$ ;

Q is a total *R*-predicate (*T*-predicate), if  $T(Q) \cup F(Q) = {}^{V}A$ ;

*Q* is a total single-valued *R*-predicate (*TS*-predicate), if  $T(Q) \cap F(Q) = \emptyset$  and  $T(Q) \cup F(Q) = {}^V A$ .

We can define 4 constant  $R$ -predicates  $T$ ,  $F$ ,  $K$ ,  $\Upsilon$  as follows:

 $T(F) = F(T) = T(K) = F(K) = \emptyset$ ;  $T(T) = F(F) = T(\Upsilon) = \Upsilon A$ .

*Q* is a partial constant *P*-predicate, if  $F(Q) = \emptyset$  or  $T(Q) = \emptyset$ .

We will denote classes of *V-A*-quasiary *R*-predicates, *P*-predicates, *T*-predicates, and *TS*-predicates  $Pr^{V-A}$ ,  $Pr^{V-A}$ ,  $Pr^{V-A}$ , and  $Pr^{V-A}$  respectively. The class  $Pr^{V-A}$  is degenerate: all *TS*-predicates, excep non-monotonic.

**Basic compositions.** Basic compositons of  $L_{\perp}^Q$  are negation  $\neg$ , disjunction  $\nvee$ , extended renomination  $R_{\bar{x},\perp}^{\bar{v},\bar{u}}$ existential quantifier  $\exists x$ , and 0-ary variable assignment predicate *Ez*. Basic compositons of  $L_1^Q$  additionally contain the composition of predicate complement  $\Box$ .

Logical connectives  $\rightarrow$  are  $\vee$  defined by the truth and falsity domains of the respective predicates:

 $T(-P) = F(P);$   $F(-P) = T(P);$   $T(P \vee Q) = T(P) \cup T(Q);$   $F(P \vee Q) = F(P) \cap F(Q).$ 

We specify the composition of extended renomination  $\mathbb{R}_{\overline{x},\perp}^{\overline{v},\overline{u}} : Pr^{V-A} \otimes Pr^{V-A}$  as  $\mathbb{R}_{\overline{x},\perp}^{\overline{v},\overline{u}}(P)[d] = P[r_{\overline{x},\perp}^{\overline{v},\overline{u}}(d)]$ .

The predicate *Ez* indicates whether a component  $z \in V$  has a value in a given data:

 $T(Ez) = \{d | d(z) \}$ ;  $F(Ez) = \{d | d(z) \}$ .

Predicates *Ez* are total, sinle-valued, and non-monotonic.

We define the quantifier  $\exists x P : Pr^{V-A} \otimes Pr^{V-A}$  as follows:

$$
T(\exists x P) = \bigcup_{a \in A} \{d \mid d \mid_{-x} \cup x \mapsto a \in T(P)\}; \ F(\exists x P) = \bigcap_{a \in A} \{d \mid d \mid_{-x} \cup x \mapsto a \in F(P)\}.
$$

Specific non-monotonic 1-ary composition of predicate complement  $\Box$  is specified as:

 $T(\Box P) = \bot (P) = \overline{T(P) \cup F(P)} = \overline{T(P)} \cap \overline{F(P)}$ ;  $F(\Box P) = \emptyset$ .

Thus, the sets of basic compositions for  $L_{\perp}^Q$  and  $L_{\perp}^{Q}$  are  $C_{\perp Q} = \{\neg, \vee, R_{\overline{x}, \perp}^{\overline{y}, \overline{u}}, \exists x, Ex\}$  and  $C_{\perp QC} = \{\neg, \vee, R_{\overline{x}, \perp}^{\overline{y}, \overline{u}}, \exists x, Ex\}$  $\Box$ *Ex*} respectively.

**Statement 2.** Compositions  $\neg, \vee, R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}, \exists x P$  preserve totality and monotonicity of predicates.

Therefore, classes  $Pr^{V-A}$ ,  $Pr^{V-A}$ ,  $PrTS^{V-A}$  are closed under compositions  $C_{\perp Q}$ . At the same time, we have **Statement 3.**  $Q \in Pr^{V-A} \Rightarrow \Box Q \in Pr^{V-A};$   $Q \in PrT^{V-A} \Rightarrow \Box Q = K$ .

Classes  $PrT^{V-A}$  and  $PrTS^{V-A}$  are not closed under  $\Box$ . Therefore, *LC do not make sense* for *T*-predicates and *TS*predicates. Due to nonclosedness of  $PrTS^{V-A}$  and  $PrT^{V-A}$  under  $\Box$ , duality [6] of classes  $PrP^{V-A}$  and  $PrT^{V-A}$  and degeneration of *PrTS<sup>V</sup>*–*<sup>A</sup>* , we will further consider only logics of *R-*predicates and *P-*predicates.

We obtain composition systems  $(^{V}A, Pr^{V-A}, C_{\perp Q})$ ,  $(^{V}A, Pr^{V-A}, C_{\perp Q})$ ,  $(^{V}A, Pr^{V-A}, C_{\perp QC})$ ,  $(^{V}A, Pr^{V-A}, C_{\perp QC})$ . They define pure first order composition algebras  $A_{\perp}^Q = ({}^V A, P r^{V-A}, C_{\perp Q}), A_{\perp}^{QC} = ({}^V A, P r^{V-A}, C_{\perp QC}), A_{\perp}^{QP} = ({}^V A, P r P^{V-A}, C_{\perp Q}),$  $A_{\perp}^{QCP} = {V \choose A}$ , *PrP*<sup>V–*A*</sup>,  $C_{\perp QC}$ ); here  $A_{\perp}^{QP}$  and  $A_{\perp}^{QCP}$  are subalgebras of algebras  $A_{\perp}^{Q}$  and  $A_{\perp}^{QC}$ .

The main properties of propositional compositions and quantifiers, unrelated to renominations, correspond to those of classical logical connectives and quantifiers (see [3]).

**Theorem 1.** The operation of extended renomination has the following basic properties:

 $R$ )  $R(P) = P$ ;

 $R_{\perp}I$ )  $R_{z,\bar{x},\perp}^{z,\bar{v},\bar{u}}(P) = R_{\bar{x},\perp}^{\bar{v},\bar{u}}(P)$  – identical renomination can be eliminated;

 $R_{\perp}$ U)  $R_{y,\overline{x},\perp}^{z,\overline{y},\overline{u}}(P) = R_{\overline{x},\perp}^{\overline{y},\overline{u}}(P)$  for unessential for predicate *P* name  $z \in V$ ;

 $R_{\perp}$ **f**) if  $d(z)$ **f** then  $R_{\bar{x},\perp,z}^{\bar{v},\bar{u},y}(P)(d) = R_{\bar{x},\perp,\perp}^{\bar{v},\bar{u},y}(P)(d)$  and  $R_{\bar{x},\perp,\perp}^{\bar{v},\bar{u},z}(P)(d) = R_{\bar{x},\perp}^{\bar{v},\bar{u}}(P)(d)$ ;

 $R_{\perp}R$ )  $R_{\bar{y},\perp}^{\bar{v},\bar{z}}(R_{\bar{x},\perp}^{\bar{u},\bar{t}}(P)) = R_{\bar{y},\perp}^{\bar{v},\bar{z}} \circ_{\bar{x},\perp}^{\bar{u},\bar{t}}(P)$  – convolution of renominations; here  $R_{\bar{y},\perp}^{\bar{v},\bar{z}} \circ_{\bar{x},\perp}^{\bar{u},\bar{t}}(P)(d) = P(r_{\bar{x},\perp}^{\bar{u},\bar{t}}[{\$ 

 $R_{\perp}$ )  $R_{\overline{x},\perp}^{\overline{v},\overline{u}}(-P) = -R_{\overline{x},\perp}^{\overline{v},\overline{u}}(P) - R$ -distributivity;

 $R_{\perp} \vee$ )  $R_{\overline{x},\perp}^{\overline{v},\overline{u}}(P \vee Q) = R_{\overline{x},\perp}^{\overline{v},\overline{u}}(P) \vee R_{\overline{x},\perp}^{\overline{v},\overline{u}}(Q) - R \vee$ - distributivity;

 $R_{\perp} \Box$ )  $R^{\overline{v},\overline{u}}_{\overline{x},\perp}(\Box Q) = \Box R^{\overline{v},\overline{u}}_{\overline{x},\perp}(Q) - R_{\perp} \Box$  - distributivity.

**Theorem 2.** The properties related to renomination and quantification compositions are the following:

Ren) if name *z* is unessential for *P*, then  $\exists yP = \exists z R_z^y(P)$  – renaming of a quantifier name;

 $R_{\perp}$   $\exists$ s)  $\exists y R_{\overline{x},\perp}^{\overline{y},\overline{u}}(P) = R_{\overline{x},\perp}^{\overline{y},\overline{u}}(\exists yP)$  if  $y \notin {\overline{v}, \overline{x}, \overline{u}}$  – simple (limited) R $\exists$ - distributivity;

 $R_{\perp} \exists$ )  $R_{\overline{x},\perp}^{\overline{v},\overline{u}}(\exists yP) = \exists z R_{\overline{x},\perp}^{\overline{v},\overline{u}} \circ_z^y(P)$ , if name *z* is unessential for *P* and  $z \notin {\overline{v}, \overline{x}, \overline{u}}$  –  $\exists$ - distributivity;

 $UR_{\perp}$ )  $\exists y R_{z,\overline{x},\perp}^{y,\overline{y},\overline{u}}(P) = R_{z,\overline{x},\perp}^{y,\overline{y},\overline{u}}(P)$  if  $y \notin \{z,\overline{x}\}\$  – unessentiality of upper names in renominations.

**Statement 4.** Properties of renomination of variable assignment predicates:

 $R^{\bar{\nu}, \bar{u}, z}_{\bar{x},\perp,\perp}(Ez) = F; \ \ R^{\bar{\nu}, \bar{u}, z}_{\bar{x},\perp,\bar{y}}(Ez) = Ey; \ \ R^{\bar{\nu}, \bar{u}}_{\bar{x},\perp}(Ez) = Ez, \ \text{if } z \notin \{\bar{\nu}, \bar{u}\}.$ 

Quantifier elimination is based on the next properties:

**Theorem 3.**  $T(\mathbf{R}_{\overline{v},\perp,y}^{\overline{u},\overline{w},x}(P)) \cap T(Ey) \subseteq T(\mathbf{R}_{\overline{v},\perp}^{\overline{u},\overline{w}}(\exists xP))$  and  $F(\mathbf{R}_{\overline{v},\perp}^{\overline{u},\overline{w}}(\exists xP)) \cap T(Ey) \subseteq F(\mathbf{R}_{\overline{v},\perp,y}^{\overline{u},\overline{w},x}(P))$ .

**Languages of**  $L_1^{\mathcal{Q}C}$ **.** An alphabet of the language of  $L_1^{\mathcal{Q}C}$  consists of a set of names (variables) *V*, a set of predicate symbols *Ps*, and a set of basic compositions' symbols  $Cs = \{\text{---}, \text{---}, R_{\overline{x},\perp}^{\overline{v},\overline{u}}, \square \square \exists x, Ex\}$ . We define inductively the set of formulas (denoted *Fr*):

– each  $p \in Ps$  and each *Ex* is a formula; formulas of such forms are called atomic;

 $-i\mathbf{f}\Phi, \Psi \in \mathbf{F}r$ , then  $\neg \Phi \in \mathbf{F}r$ ,  $\neg \Phi \Psi \in \mathbf{F}r$ ,  $R_{\overline{x},\perp}^{\overline{v},\overline{u}}\Phi \in \mathbf{F}r$ ,  $\exists x\Phi \in \mathbf{F}r$ ,  $\Box \Phi \in \mathbf{F}r$ .

We specify a set  $V_T \subseteq V$  of total unessential names (unessential for any  $p \in Ps$ ) and extend it [3, 6] to formulas:  $v: Fr \rightarrow 2^V$ .

If  $x \in v(\Phi)$ , then (see [3, 6]) *x* is unessential for  $\Phi$ . Tuple  $\Sigma = (V, V_T, C_s, Ps)$  is called the extended logic signature.

We call a formula primitive, if it is atomic or has a form  $R_{\overline{x},\perp}^{\overline{y},\overline{u}}p$ , where  $p \in Ps$ , there are no identical renominations in  $R_{\bar{x},\perp}^{\bar{v},\bar{u}}$  and  $\{\bar{v},\bar{u}\}\cap v(p)=\varnothing$ .  $\Phi$  is a *CF*-formula (constant free), if  $\Phi$  does not contain symbols of 0ary compositions (*Ex* in the case of the language of  $L_1^{\mathcal{Q}C}$ ). Formulas of the form  $R_{\bar{x},\perp}^{\bar{y},\bar{u}}\Phi$  are called *R*-formulas.

**Interpretations.** We interpretate the language of the  $L_{\perp}^{OC}$  on composition systems CS = ( $\chi^V A$ ,  $P r^{V-A}$ ,  $C_{\perp OC}$ ). Symbols in *Cs* are interpretated as corresponding compositions, symbols *Ex* – as variable assignment predicates *Ex*. We specify a total single-valued mapping *I* :  $P_S \otimes P r^{V-A}$  and extend it to formulas: *I* :  $Fr \otimes Pr^{V-A}$ :

 $I(\neg \Phi) = \neg(I(\Phi)), \ I(\vee \Phi \Psi) = \vee(I(\Phi), I(\Psi)), \ I(R^{\overline{v}, \overline{u}}_{\overline{x}, \perp} \Phi) = R^{\overline{v}, \overline{u}}_{\overline{x}, \perp}(I(\Phi)), \ I(\exists x \Phi) = \exists x (I(\Phi)), \ I(\Box \Phi) = \Box(I(\Phi)).$ 

Let the tuple  $J = (CS, \Sigma, I)$  be an interpretation of the language of  $L_{\perp}^Q$  (further shorten to  $J = (A, I)$ ).

Given interpretation *J* and formula  $\Phi$ , we define value of  $\Phi$  in *J* (denoted  $\Phi$ <sub>*J*</sub>) by induction on the structure of

Name  $x \in V$  is unessential for a formula $\Phi$ , if it is unessential for  $\Phi_J$  for any interpretation *J*.

Classes of interpretations of the language are called semantics. For  $L_{\perp}^{OC}$  we have a general class of *R*interpretations – semantics *RС*. Specifying of subalgebras of *P-*predicates leads to a subclass of *P*-interpretations – semantics *PС*.

 $\Phi$ .

For  $L_{\perp}^Q$  we have a general class of *R*-interpretations – semantics  $_{\perp}$ *R*. For subalgebras of *P*-predicates, *T*predicates, *TS*-predicates we obtain semantics  $_{\perp}P$ ,  $_{\perp}T$ ,  $_{\perp}TS$ . Only semantics  $_{\perp}P$  will be considered.

Let us call *constant* formulas that are always interpreted as constant predicates. We can distinguish  $_T$ -formulas,  $F_F$ - formulas,  $\perp$ - formulas. For example,  $Ex \vee \neg Ex$  is a  $_T$ - formula,  $R_{\overline{x},\perp,\perp}^{\overline{y},\overline{u},z}(E_z)$  is a  $_F$ - formula,  $\Box Ez$  is a  $\perp$ - formula.

Let formulas that are always interpreted as total predicates (in particular,  $E_z$ ,  $_T$ - formulas and  $_F$ - formulas) be denoted  $\varnothing$ ; formulas with  $F(\Phi) = \varnothing$  for any *J* (in particular, all formulas  $\Box \Phi$ ) be denoted  $\varnothing$ <sub>F</sub>; formulas with  $T(\Phi_J) = \emptyset$  for any *J* (in particular, all formulas  $-\Box \Phi$ ) be denoted  $\emptyset_T$ .

The language of  $L_{\perp}^Q$  is defined similarly (omitting everything related to symbols  $\Box$ ).

*Un*-formulas. Let  $R_{\overline{x},\overline{y},\overline{t},L,\perp}^{\overline{x},\overline{y},\overline{u},\overline{w}}$  ( $\Phi$ ) be *R*-formula such as  $\{\overline{u},\overline{w}\}\subseteq v(\Phi)$ , and  $\Phi$  is not a symbol *Ez*. Let us call *Rs*-

*form* of an *R*-formula  $R_{\overline{x},\overline{y},\overline{t},1,1}^{\overline{x},\overline{y},\overline{u},\overline{w},\overline{z}}$  ( $\Phi$ ) the *R*-formula obtained from  $R_{\overline{x},\overline{y},\overline{t},1,1}^{\overline{x},\overline{y},\overline{u},\overline{w},\overline{z}}$  ( $\Phi$ ) by all possible simplifications of external renomination based on properties  $R_1$ ,  $R_1$ ,  $R_1$ ,  $R_2$ ,  $U$ . We will call *Rs-formulas Rs*-forms of *R*-formulas.

**Statement 5.** If  $\Xi$  is a *Rs*-form of an *R*-formula  $\Psi$ , then  $\Xi$ <sub>*J*</sub> =  $\Psi$ <sub>*J*</sub> for all interpretations *J*.

Let  $Un \subseteq V$  be a set of indefinite names. Each *Rs*-formula can be presented in the form of  $R_{\bar{s},\bar{v},\bar{y},\perp,\perp}^{\bar{r},\bar{z},\bar{x},\bar{u},\bar{w}}\Phi$ , where

 $\{\overline{r}, \overline{s}, \overline{y}, \overline{u}\} \subseteq Un, \ \{\overline{x}, \overline{v}, \overline{w}\} \cap Un = \emptyset$ . Let us call  $R_{\overline{v}, \perp, \perp}^{\overline{z}, \overline{x}, \overline{w}}\Phi$  an *Un-form* of the formula  $R_{\overline{s}, \overline{v}, \overline{y}, \perp, \perp}^{\overline{r}, \overline{z}, \overline{x}, \overline{w}}\Phi$ .

Primitive Un-formulas have a form of  $R_{\overline{v},\perp}^{\overline{z},\overline{x}} p$ , where  $\{\overline{x},\overline{v}\}\cap Un = \emptyset$ ,  $p \in Ps$ .

Let us call formulas  $\Psi$  and  $\Xi$  *Un-equivalent* (denoted  $\Psi \sim_{U_n} \Xi$ ), if for any  $J = (A, I)$  and  $d \in \mathscr{A}||_{-U_n}$  we have  $\Psi_{J}(d) = \Xi_{J}(d)$ .

**Statement 6.** If  $\Psi$  is an *Un*-form of a formula  $\Phi$ , then  $\Phi \sim_{U_n} \Psi$ .

*Un*-form  $R_{\overline{v},\perp,\perp}^{\overline{z},\overline{x},\overline{w}}\Phi$  can be obtained transforming an *Rs*-formula  $R_{\overline{s},\overline{v},\overline{y},\perp,\perp}^{\overline{r},\overline{z},\overline{x},\overline{w}}\Phi$  according to R<sub>⊥</sub>1. Hence

**Statement 7.** Given  $z \in Un$ , then  $R_{\overline{x},\perp,z}^{\overline{y},\overline{u},y} \Phi \square_{Un} R_{\overline{x},\perp,z}^{\overline{y},\overline{u},y} \Phi$  and  $R_{\overline{x},\perp,z}^{\overline{y},\overline{u},z} \Phi \square_{Un} R_{\overline{x},\perp}^{\overline{y},\overline{u}} \Phi$ .

#### **2. Logical consequence relation**

A number of various logical consequence relations can be defined on the sets of formulas of the languages of  $L_{\perp}^Q$  and  $L_{\perp}^{QC}$ . Among them are the relations defined in the languages of  $L^Q$  [12, 6]:  $P|_{\equiv_{IR}}$ ,  $P|_{\equiv_{I}}$ ,  $P|_{\equiv_{IF}}$ ,  $P|_{\equiv_{IF}}$ ,  $P|_{\equiv_{IF}}$ ,  $P|_{\equiv_{IF}}$ ,  $P|_{\equiv_{IF}}$ ,  $P|_{\equiv_{IF}}$ 

For the simplicity sake, we will omit symbol  $\vert$  in the names of relations.

Firstly, let us specify a logical consequence relation for two sets of formulas in interpretation *J*.

Let  $\Sigma$ ,  $\Gamma$ ,  $\Delta \subset Fr$  and *J* be an interpretation. We denote:

$$
\bigcap_{\theta \in \Sigma} T(\theta_J) \text{ as } T^{\cap}(\Sigma_J), \bigcap_{\theta \in \Sigma} F(\theta_J) \text{ as } F^{\cap}(\Sigma_J), \bigcup_{\theta \in \Sigma} T(\theta_J) \text{ as } T^{\cup}(\Sigma_J), \bigcup_{\theta \in \Sigma} F(\theta_J) \text{ as } F^{\cup}(\Sigma_J).
$$

 $\Delta$  is an *IR*-consequence of  $\Gamma$  in interpretation *J* (denoted  $\Gamma$ <sub>*J*|=*R*</sub> $\Delta$ ), if  $T^{\cap}(\Gamma_J) \cap F^{\cap}(\Delta_J) = \emptyset$ .

 $\Delta$  is a *T*-consequence of  $\Gamma$  in interpretation *J* (denoted  $\Gamma$   $\parallel$  $\equiv$   $\tau$  $\Delta$ ), if  $T$ <sup> $\cap$ </sup> $(\Gamma) \subseteq T$ <sup> $\cup$ </sup> $(\Delta)$ .

 $\Delta$  is an *F*-consequence of  $\Gamma$  in interpretation *J* (denoted  $\Gamma$ <sub>*J*|=*F* $\Delta$ ), if  $F^{\gamma}(\Delta_J) \subseteq F^{\gamma}(\Gamma_J)$ .</sub>

 $\Delta$  is *TF*-consequence of  $\Gamma$  in interpretation *J* (denoted  $\Gamma$ <sub>J</sub> $\models$  $T<sub>F</sub>\Delta$ ), if  $\Gamma$ <sub>J</sub> $\models$  $T<sub>F</sub>\Delta$  and  $\Gamma$ <sub>J</sub> $\models$  $F<sub>F</sub>\Delta$ .

The corresponding logical  $\tau$ -consequence relations in semantics  $\alpha$  are defined as follows:

 $\Gamma^{\alpha}$ |=<sub>τ</sub> $\Delta$ , if  $\Gamma_J$ |=<sub>τ</sub> $\Delta$  for arbitrary  $J \in \alpha$ .

Here  $\alpha$  denotes one of the semantics:  $_R P$ ,  $_R P$ ,  $_R C$ ,  $_L P C$ . There are 8 logical consequence relations in each of  $L_1^Q$ and  $L_{\perp}^{QC}$ :

*P* |=*IR*, *<sup>P</sup>* |=*T*, *<sup>P</sup>* |=*F*, *<sup>P</sup>* |=*TF*; *<sup>R</sup>* |=*IR*, *<sup>R</sup>* |=*T*, *<sup>R</sup>* |=*F*, *<sup>R</sup>* |=*TF* ; *Pс* |=*IR*, *<sup>P</sup><sup>с</sup>* |=*T*, *<sup>P</sup><sup>с</sup>* |=*F*, *<sup>P</sup><sup>с</sup>* |=*TF*; *<sup>R</sup><sup>с</sup>* |=*IR*, *<sup>R</sup><sup>с</sup>* |=*T*, *<sup>R</sup><sup>с</sup>* |=*F*, *<sup>R</sup><sup>с</sup>* |=*TF* .

Some of them are degenerate, some of the relations coincide (see [12]). For instance:

**Statement 8.** If  $\Gamma$  and  $\Delta$  consist of *CF*-formulas that do not contain  $\Box$ , then  $\Gamma^R \neq_R \Delta$  and  $\Gamma^{Rc} \neq_R \Delta$ .

At the same time,  $Ez$ ,  $-Ez$   $J=_{IR} \Sigma$  ra  $\Sigma$   $J=_{IR} Ez$ ,  $-Ez$  for each *J*. Therefore,  ${}^{Rc}$  $|=_{IR}$  and  ${}^{R}$  $|=_{IR}$  are degenerate.

**Example 1.** For any  $\Phi \in Fr$  and  $J \in {}_1RC$  we have  $F(\Box \Phi_1) = \emptyset$ ,  $T(\Box \Phi_1) = \emptyset$ ,  $T(\Phi_J) \not\subset T(\Box \Phi_1) = \bot(\Phi_J)$ ,

 $F(\Phi_J) \not\subset F(\Box \Phi_J) = \bot(\Phi_J)$ . Hence  $\Gamma^{Rc} \models_F \Box \Phi$  and  $\neg \Box \Phi^{Rc} \models_T \Delta$ ; however,  $\Phi^{Rc} \models_T \Box \Phi$  and  $\neg \Box \Phi^{Rc} \models_F \Phi$ .

There are 5 distinct non-degenerate relations in  $L_{\perp}^Q$ .  $P_{\parallel = IR}$ ,  $P_{\parallel = T}$ ,  $P_{\parallel = TR}$ ,  $P_{\parallel = TF}$ ,  $R_{\parallel = TF}$ .

In  $L_{\perp}^{QC}$ , we obtain 7 distinct non-degenerate relations:  $^{Pc}|=_{IR}$ ,  $^{Pc}|=_{T}$ ,  $^{Pc}|=_{F}$ ,  $^{Rc}|=_{T}$ ,  $^{Rc}|=_{T}$ ,  $^{Rc}|=_{T}$ ,  $^{Rc}|=_{TF}$ .

The Hasse diagrams for those relations are shown below (we use an arrow  $\rightarrow$  instead of symbol  $\subset$ ):

$$
P|_{T} = \n\begin{array}{ccc}\nP|_{T} & R_{T} = \n\begin{array}{ccc}\nR_{T} = \n\end{array} & P_{T} = \n\end{array}
$$

At the same time, for the relation  $P^c|_{\mathbb{F}_{IR}}$  it is impossible to make a decomposition  $\Box \Phi$  ([12]). Such a decomposition requires to specify *explicitly* an undefinedness domain, which leads to the more general irrefutability logical consequence relation under the conditions of undefinedness  $\vert =_{IR}^{\perp}$  ([9]). For the latter relation, sequent calculi of propositional, renominative and first order levels are constructed [9–11].

In [12], there are introduced logical consequence relations under the conditions of undefinedness  $^{P_c}|=\frac{1}{T}$ ,  $^{P_c}|=\frac{1}{T}$ ,  $^{P_c}|=\frac{1}{T}$ ,  $^{P_c}|=\frac{1}{T}$ ,  $^{P_c}|=\frac{1}{T}$ ,  $^{P_c}|=\frac{1}{T}$ ,  $^{P_c}|=\frac{1}{T}$ , the theorem of eli relations  ${}^{Pc}$   $\models_T$ ,  ${}^{Pc}$   $\models_F$ ,  ${}^{Rc}$   $\models_T$ ,  ${}^{Rc}$   $\models_F$ .

Logical consequence relations on pairs of formulas induce respective logical equivalence relations.

We define a  $\tau$ -equivalence relation in interpretation *J* as follows:  $\Phi_{\mathcal{F}} \tau \Psi$ , if  $\Phi_{\mathcal{J}} = \tau \Psi$  and  $\Psi_{\mathcal{J}} = \tau \Phi$ .

A logical  $\tau$ -equivalence relation in semantics  $\alpha$  is defined as follows:  $\Phi^{\alpha} \sim_{\tau} \Psi$ , if  $\Phi^{\alpha}|=\tau \Psi$  and  $\Psi^{\alpha}|=\tau \Phi$ .

Note the importance of the relation  $J \sim T_F$ :  $\Phi_{J} \sim T_F \Psi \Leftrightarrow T(\Phi_J) = T(\Psi_J)$  and  $F(\Phi_J) = F(\Psi_J) \Leftrightarrow \Phi_J = \Psi_J$ .

Equivalent transformations in  $L_{\perp}^Q$  ra  $L_{\perp}^Q$ <sup>C</sup> are based on the equivalence and substitution of equivalent theorems. **Theorem 4.** Let  $\Phi'$  be obtained from formula  $\Phi$  by substitution of  $\Psi_1, ..., \Psi_n$  instead of  $\Phi_1, ..., \Phi_n$ . If  $\Phi_1 \sim_{\ast} \Psi_1$ ,

..., *<sup>n</sup> n*, then *'* (here denotes one of the following: *<sup>R</sup> TF*, *<sup>P</sup> TF*, *<sup>P</sup> IR*, *<sup>R</sup><sup>с</sup> TF*, *<sup>P</sup><sup>с</sup> TF*, *<sup>P</sup><sup>с</sup> IR*).

**Theorem 5.** Let  $\Phi \sim_{TF} \Psi$ , then we have:  $\Phi, \Gamma \models_{\ast} \Delta \Leftrightarrow \Psi, \Gamma \models_{\ast} \Delta; \Gamma \models_{\ast} \Delta, \Phi \Leftrightarrow \Gamma \models_{\ast} \Delta, \Psi$ .

Let  $\sim_{TF}$  denote one of the relations of the *TF* type, and  $\mid =_{*}$  denote an arbitrary logical consequence relation.

Let us consider properties of logical consequence relations.

M) If  $\Gamma \subset \Lambda$ ,  $\Delta \subset \Sigma$  and  $\Gamma \models_{\ast} \Delta$ , then  $\Lambda \models_{\ast} \Sigma$  – monotonicity.

**Theorem 6.** The following basic properties of formula decomposition hold:

 $L_{\text{Lip}}$  ,  $L = \Phi, \Gamma = \Delta \Leftrightarrow \Phi, \Gamma = \Delta;$  $\vee_{L}$ )  $\Phi \vee \Psi$ ,  $\Gamma \models_{*} \Delta \Leftrightarrow \Phi$ ,  $\Gamma \models_{*} \Delta$  and  $\Psi$ ,  $\Gamma \models_{*} \Delta$ ;  $\vee_{R}$ )  $\Gamma \models_{*} \Delta$ ,  $\Phi \vee \Psi \Leftrightarrow \Gamma \models_{*} \Delta$ ,  $\Phi$ ,  $\Psi$ ;

L) (), |= , , |= ; R) |= , () |= , and |= , .

For the relations of the *IR* type, additionally hold (and do not hold for the relations of the types *T*, *F*, *TF*):

$$
\neg_L) \neg \Phi, \Gamma \models_R \Delta \Leftrightarrow \Gamma \models_R \Delta, \Phi.
$$

Let 
$$
e^{it} =_T
$$
 denote  $e^{Pc} =_T$  or  $e^{Rc} =_T$ ;  $e^{it} =_F$  denote  $e^{Pc} =_F$ ,  $e^{Rc} =_T$ ;  $e^{it} =_{TF}$  denote  $e^{Pc} =_{TF}$  or  $e^{Rc} =_{TF}$ .

**Theorem 7.** The following properties of decomposition for  $\Box \Phi$  formulas hold:

$$
\text{or} \ \Gamma^{c\#}\models_T\Delta \Leftrightarrow \Gamma^{c\#}\models_T\Delta, \Phi, \neg \Phi; \qquad \text{or} \ \Gamma^{c\#}\models_T\Delta, \Box \Phi \Box \Leftrightarrow \Phi, \Gamma^{c\#}\models_T\Delta \text{ and } \neg \Phi, \Gamma^{c\#}\models_T\Delta;
$$

$$
\neg\Box_{\rm RF})\,\Gamma^{\,c\#}\!\!\models_F\!\Delta,\neg\Box\,\Phi\;\Leftrightarrow\;\Gamma,\Phi,\neg\Phi^{\,c\#}\!\!\models_F\!\Delta;\qquad \neg\Box_{\rm LF})\,\,\neg\Box\,\Phi,\Box^{\,c\#}\!\!\models_F\!\Delta \,\Leftrightarrow\,\Gamma^{\,c\#}\!\!\models_T\!\Delta,\Phi\;\;\text{and}\;\;\Gamma^{\,c\#}\!\!\models_T\!\Delta,\neg\Phi.
$$

**Theorem 8.** The following properties of elimination for  $\Box \Phi$  formulas hold:

 $\left( \neg\ \Box\ \text{EI}\right)\Gamma^{c\#} \!\!\left| =_T\! \Delta,\neg\Box\, \Phi \;\;\Leftrightarrow \;\Gamma^{c\#}$  $| =_T \Delta; \qquad \qquad \Box$   $\Box$   $\Box$   $\Phi$ ,  $\Gamma^{\mathcal{C}^{\#}} | =_F \Delta \Leftrightarrow \Gamma^{\mathcal{C}^{\#}} | =_F \Delta$ .

**Statement 9.** The properties that guarantee the specified logical consequence relation:

 $(C \Box) \Gamma^{c\#}|_{\equiv F} \Box \Phi \Delta$ ;  $C \Box \Gamma \Box \Phi^{c\#}|_{\equiv F} \Delta$ .

Composition  $\Box$  has different properties on truth and falsity domains of predicates inducing different properties of decomposition for  $\Box \Phi$  formulas for the relations of the types *T* and *F* and making impossible to formulate a joint property for the relations of the *TF* type. Therefore, for relations  $c^{\#}|=_{TF}$  decomposition for  $\Box \Phi$  is possible for  $c^{\#}|=_{T}$  and  $c^{\#}|=_{T}$  and  $\epsilon^{\mu}$  = *F* only separately.

Thus, sequent calculi for relations  $c^{\#}$  =  $_{TF}$  aggregate calculi for relations  $c^{\#}$  =  $_T$  and  $c^{\#}$  =  $_F$ .

We will concentrate on the relations *<sup>P</sup>* |=*IR*, *<sup>P</sup>* |=*T*, *<sup>P</sup>* |=*F*, *<sup>P</sup>* |=*TF*, *<sup>R</sup>* |=*TF* in *L <sup>Q</sup>* and *<sup>P</sup><sup>с</sup>* |=*T*, *<sup>P</sup><sup>с</sup>* |=*F*, *<sup>R</sup><sup>с</sup>* |=*T*, *<sup>R</sup><sup>с</sup>* |=*F* in *L QС* .

Let us consider properties R<sub>1</sub>, R<sub>1</sub>I, R<sub>1</sub>U, R<sub>1</sub>R, R<sub>1</sub>¬, R<sub>1</sub> $\vee$ , R<sub>1</sub> $\Box$  for predicates. Each of the properties R<sub>1</sub>\* induces 4 corresponding properties  $R_{L}$ ,  $R_{R}$ ,  $R_{R}$ ,  $R_{L}$ ,  $R_{R}$  for a logical consequence relation, depending on the position of a formula or its negation (either in the left or in the right side of the relation).  $R_{\perp}$ <sup>†</sup> induces the following 8 properties:

$$
R_{\perp}\uparrow 1) \ R_{\overline{x},\perp,z}^{\overline{v},\overline{u},\overline{v}}(\Phi),\Gamma\models_{*}\Delta,Ez \Leftrightarrow R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},\overline{v}}(\Phi),\Gamma\models_{*}\Delta,Ez;\ \Gamma\models_{*}\Delta,R_{\overline{x},\perp,z}^{\overline{v},\overline{u},\overline{v}}(\Phi),Ez \Leftrightarrow \Gamma\models_{*}\Delta,R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},\overline{v}}(\Phi),Ez;
$$

$$
\neg R_{\perp}\uparrow 1) \neg R_{\overline{x},\perp,\overline{z}}^{\overline{v},\overline{u},\overline{y}}(\Phi),\Gamma \models_* \Delta,Ez \Leftrightarrow \neg R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},\overline{y}}(\Phi),\Gamma \models_* \Delta,Ez;\ \ \Gamma \models_* \Delta, \neg R_{\overline{x},\perp,\overline{z}}^{\overline{v},\overline{u},\overline{y}}(\Phi),Ez \Leftrightarrow \ \Gamma \models_* \Delta, \neg R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},\overline{z}}(\Phi),Ez;
$$

$$
R_\perp\textbf{12})\ R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},z}(\Phi),\Gamma\models_{\ast}\Delta,Ez\Leftrightarrow\ R_{\overline{x},\perp}^{\overline{v},\overline{u}}(\Phi),\Gamma\models_{\ast}\Delta,Ez;\ \Gamma\models_{\ast}\Delta,R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},z}(\Phi),Ez\ \Leftrightarrow\ \Gamma\models_{\ast}\Delta,R_{\overline{x},\perp}^{\overline{v},\overline{u}}(\Phi),Ez;
$$

$$
\neg R_{\perp}\uparrow 2) \neg R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},z}(\Phi),\Gamma \models_* \Delta,Ez \Leftrightarrow \neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(\Phi),\Gamma \models_* \Delta,Ez;\ \Gamma \models_* \Delta, \neg R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},z}(\Phi),Ez \Leftrightarrow \Gamma \models_* \Delta, \neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(\Phi),Ez;
$$

Properties of  $\rightarrow$  elimination in  $-Ez$  and in  $\overline{R}_{\overline{w},\perp}^{\overline{v},\overline{u}}(Ez)$  and renomination properties of variable assignment predicates are the following:

$$
\neg_{E}) - Ez, \Gamma \models_{*} \Delta \Leftrightarrow \Gamma \models_{*} \Delta, Ez, \Gamma \models_{*} \Delta, \neg Ez \Leftrightarrow Ez, \Gamma \models_{*} \Delta;
$$
\n
$$
\neg_{R \perp E}) - R_{\overline{w}, \perp}^{\overline{v}, \overline{u}}(Ez), \Gamma \models_{*} \Delta \Leftrightarrow \Gamma \models_{*} R_{\overline{w}, \perp}^{\overline{v}, \overline{u}}(Ez), \Delta; \Gamma \models_{*} \neg R_{\overline{w}, \perp}^{\overline{v}, \overline{u}}(Ez), \Delta \Leftrightarrow R_{\overline{w}, \perp}^{\overline{v}, \overline{u}}(Ez), \Gamma \models_{*} \Delta;
$$
\n
$$
R_{\perp E}) R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(Ez), \Gamma \models_{*} \Delta \Leftrightarrow Ez, \Gamma \models_{*} \Delta, \text{ ae } z \notin \{\overline{v}, \overline{u}\}; \Gamma \models_{*} \Delta, R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(Ez) \Leftrightarrow \Gamma \models_{*} \Delta, Ez, \text{ ae } z \notin \{\overline{v}, \overline{u}\};
$$
\n
$$
R_{\perp Ev}) R_{\overline{x}, \perp, \overline{y}}^{\overline{v}, \overline{u}, z}(Ez), \Gamma \models_{*} \Delta \Leftrightarrow Ey, \Gamma \models_{*} \Delta; \Gamma \models_{*} \Delta, R_{\overline{x}, \perp, \overline{y}}^{\overline{v}, \overline{u}, z}(Ez) \Leftrightarrow \Gamma \models_{*} \Delta, Ey.
$$

Let us specify properties of quantifier elimination, *E*-distribution and primary definition:

$$
∃L) ∃xΦ, Γ |=∗ Δ ⇔ Rzx(Φ), Ez, Γ |=∗ Δ given z∈fu(Γ, Δ, ∃xΦ));\n∃Rµ, PWµµπ(∃xΦ), Γ |=∗ Δ ⇔ RWµµπ(x), Ez | =∗ ¬ Rzπ(Φ), Δ given z ∈ fu(Γ, Δ, RWµπ(∃xΦ));\n¬∃Rµ Σ Γ |=∗ ¬xΦ, Δ ⇔ Γ, Ez |=∗ ¬ RWµπ(x), Δ given z ∈ fu(Γ, Δ, RWµπ(∃xΦ));\n∃Rµ Σ Γ |=∗ ¬ RWµπ(∃xΦ), Δ ⇔ Γ, Ez |=∗ ¬ RWµπ(Φ), Δ ;\n∃Rµν, Π, Ey |=∗ ∃xΦ, Δ ⇔ Γ, Ey |=∗ ∃xΦ, Ryπ(Φ), Δ ;\n∃Rµν, Γ, Ey |=∗ ∆xΦ, RWµπ(∃xΦ) ⇔ Γ, Ey |=∗ ∶\n¬∃Vµ) ¬x
$$

The following properties additionally guarantee the specified logical consequence relation:

 $CL$ )  $\Phi$ ,  $\neg \Phi$ ,  $\Gamma$ <sup>*P*</sup>|=<sub>*T*</sub> $\Delta$ ;  $\Phi$ ,  $\neg \Phi$ ,  $\Gamma$ <sup>*Pc*</sup>|=<sub>*T*</sub> $\Delta$ ;  $CR$ )  $\Gamma^P$   $\models_F \Delta$ ,  $\Phi$ ,  $\neg \Phi$ ;  $\Gamma^P$ <sup> $Pc$ </sup> $\models_F \Delta$ ,  $\Phi$ ,  $\neg \Phi$ ;  $CLR$ )  $\Phi$ ,  $\neg \Phi$ ,  $\Gamma$ <sup> $P$ </sup>|=<sub>*TF*</sub> $\Delta$ ,  $\Psi$ ,  $\neg \Psi$ .

Various properties which guarantee the specified logical consequence relation can be obtained from properties of constant and partial constant predicates: properties  $C\Box$ ,  $C\Box$  and

*CF*)  $R_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},z}(E_z), \Gamma \models_{\ast} \Delta$  – holds for all introduced logical consequence relations.

Finally, we can specify the conditions that *guarantee* a certain logical consequence relation:

C) there exists formula  $\Phi$  such that:  $\Phi \in \Gamma$  and  $\Phi \in \Delta - \Gamma \models_{*} \Delta$  for every introduced relation;

CL) there exists formula Φ such that:  $Φ ∈ Γ$  and  $¬Φ ∈ Γ$  – guarantees  $Γ<sup>P</sup> | =<sub>T</sub> Δ$  and  $Γ<sup>Pc</sup> | =<sub>T</sub> Δ$ ;

CR) there exists formula  $\Phi$  such that:  $\Phi \in \Delta$  and  $\neg \Phi \in \Delta$  – guarantees  $\Gamma^P|_{F} \Delta$  and  $\Gamma^{Pc}|_{F} \Delta$ ;

CLR) there exist formulas  $\Phi$ ,  $\Psi$  such that:  $\Phi$ ,  $\neg \Phi \in \Gamma$  and  $\Psi$ ,  $\neg \Psi \in \Delta$  – guarantees  $\Gamma^P$   $\models_{TF} \Delta$ ;

CF) there exists formula  $R_{\overline{x},\perp,\perp}^{\overline{y},\overline{u},z}(E_z) \in \Gamma$  – guarantees  $\Gamma \models_{\ast} \Delta$  for every introduced relation;

 $C \Box$ )  $\Box \Phi \in \Delta$  – guarantees  $\Gamma^{Pc} \models_F \Delta$  and  $\Gamma^{Rc} \models_F \Delta$ ;

 $C \neg \Box$ )  $\neg \Box \Phi \in \Gamma$  – guarantees  $\Gamma^{Pc} = T \Delta$  and  $\Gamma^{Rc} = T \Delta$ .

#### **3. First order sequent calculi**

Sequent calculi formalize logical consequence relations between sets of formulas. We construct calculi in the style of semantic tableau, so, we will treat sequents as finite sets of formulas signed (marked, indexed) by symbols  $\vdash$ and  $\Box$ . Sequents are denoted  $\Box \Box \Delta$ , in abbreviated form  $\Sigma$ . Formulas from  $\Gamma$  (they are signed by  $\Box$ ) are called *T*formulas, formulas from  $\Delta$  (they are signed by  $\Delta$ ) are called *F*-formulas.

Sequent calculus is constructed in such a way that a sequent  $\Box \Box \Delta$  is derivable  $\Leftrightarrow \Gamma \models \Delta$ .

For a set of signed formulas  $\Sigma = \bot \top \Delta$ , let us introduce sets of *defined* and *undefined* names (*val*-variables and *unv*-variables):  $val(\llcorner \Gamma \llcorner \Delta) = \{x \in V | Ex \in \Gamma\}$ ;  $unv(\llcorner \Gamma \llcorner \Delta) = \{x \in V | Ex \in \Delta\}$ .

Also we specify a set of *undistributed* names for  $\Sigma$ :  $ud(\Sigma) = nm(\Sigma) \setminus (val(\Sigma) \cup unv(\Sigma))$ .

The derivation in sequent calculi has the form of a tree, the vertices of which are sequents; such trees are called sequent trees. A sequent  $\Sigma$  is derivable if there is a closed sequent tree with the root  $\Sigma$ . A sequent tree is closed if every its leaf is a closed sequent.

Sequent calculus is defined by basic sequent forms and closure conditions for sequents.

Closed sequents are axioms of the sequent calculus. A closedness  $\Box \Box \Delta$  must guarantee  $\Gamma \models \Delta$ .

Rules of sequent calculus are called sequent forms. They are syntactical analogues of the semantic properties of

the corresponding logical consequence relations and have a form of  $\frac{\Sigma}{\Omega}$  or  $\frac{\Sigma}{\Omega}$ .

For the relations  $P_{r} = R$ ,  $P_{r} = R$ ,  $P_{r} = R$ ,  $P_{r} = R$  in  $L_{\perp}^Q$  we have calculi  $C_{\perp}^{QR}$ ,  $C_{\perp}^{QT}$ ,  $C_{\perp}^{QFT}$ ,  $C_{\perp}^{QTF}$ ,  $C_{\perp}^{QTF}$ . For the relations  $^{Pc}|_{T} = r$ ,  $^{Pc}|_{T} = r$ ,  $^{Rc}|_{T} = r$  in  $L_{\perp}^{OC}$  we obtain calculi  $C_{\perp}^{OCT}$ ,  $C_{\perp}^{OCT}$ ,  $C_{\perp}^{OCTR}$ ,  $C_{\perp}^{OCFR}$ .

**Closure conditions for sequents.** Closure conditions for a sequent  $\Gamma$ – $\Delta$  correspond to conditions that *guarantee* a certain logical consequence relation:

 $-$  calculus  $C_{\perp}^{QIR}$ : condition  $C \vee CF$  (guarantees  $\Gamma^P \models_R \Delta$ );

 $-$  calculus  $C_{\perp}^{QT}$ : condition  $C \vee CF \vee CL$  (guarantees  $\Gamma^{P}|=T\Delta$ );

 $-$  calculus  $C_{\perp}^{QF}$ : condition  $C \vee CF \vee CR$  (guarantees  $\Gamma^{P}|=F\Delta$ );

 $-$  calculus  $C_{\perp}^{QTF}$ : condition  $C \vee CF \vee CLR$  (guarantees  $\Gamma^{P}|=_{TF}\Delta$ );

 $-$  calculus  $C_{\perp}^{QTFR}$ : condition  $C \vee CF$  (guarantees  $\Gamma^R \models_{TF} \Delta$ );

 $\sim$  calculus  $C_{\perp}^{QCT}$ : condition  $C \vee CF \vee CL \vee C \perp \square$  (guarantees  $\Gamma^{Pc} \models_T \Delta$ );

- $\sim$  calculus  $C_{\perp}^{QCF}$ : condition  $C \vee CF \vee CR \vee C\Box$  (guarantees  $\Gamma^{Pc}|=F\Delta$ );
- $\sim$  calculus  $C_{\perp}^{QCTR}$ : condition  $C \vee CF \vee C \vdash \Box$  (guarantees  $\Gamma^{Re}|=\tau \Delta$ );
- $\subset$  calculus  $C_{\perp}^{QCFR}$ : condition  $C \vee CF \vee C \Box$  (guarantees  $\Gamma^{Rc} \models_F \Delta$ ).

The conditions C, CF, CL, CR, CLR, C $\Box$ , C $\Box$  were specified earlier.

**Basic sequent forms for the calculi**  $C_1^{QT}$ ,  $C_1^{QF}$ ,  $C_1^{QTF}$ ,  $C_1^{QTFR}$ . Properties of logical consequence relations induce the corresponding sequent forms. Let us specify basic forms for the calculi  $C_1^{QT}$ ,  $C_2^{QF}$ ,  $C_1^{QTF}$ ,  $C_2^{QTF}$ . Their basic forms are the same, the difference is in closure conditions for sequents.

Simplification forms (condition for the forms of type  $R_1U: v \in V(\Phi)$ ):

$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma};
$$
\n
$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma};
$$
\n
$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma};
$$
\n
$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma};
$$
\n
$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma};
$$
\n
$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma};
$$
\n
$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1-R(\Phi),\Sigma};
$$
\n
$$
+R \frac{1}{1-R(\Phi),\Sigma}; \qquad -R \frac{1}{1
$$

Forms of equivalent transformations:

$$
+R_{\perp}R \xrightarrow[-R_{\overline{y},\perp}^{T,\overline{z}} \sigma_{\overline{x},\perp}^{\overline{u},\overline{t}}(\Phi),\Sigma ]
$$
\n
$$
+R_{\perp}R \xrightarrow[-R_{\overline{y},\perp}^{T,\overline{u}} \sigma_{\overline{y},\perp}^{\overline{u},\overline{t}}(\Phi),\Sigma ]
$$
\n
$$
+R_{\perp}R \xrightarrow[-R_{\overline{x},\perp}^{T,\overline{u}} \sigma_{\overline{y},\perp}^{\overline{u}}(\Phi),\Sigma ]
$$
\n
$$
+R_{\perp}R \xrightarrow[-R_{\overline{x},\perp}^{T,\overline{u}} \sigma_{\overline{y},\perp}^{\overline{u}}(\Phi),\Sigma ]
$$
\n
$$
+R_{\perp}R \xrightarrow[-R_{\overline{x},\perp}^{T,\overline{u}} \sigma_{\overline{y},\perp}^{\overline{u}}(\Phi),\Sigma ]
$$
\n
$$
+R_{\perp}R \xrightarrow[-R_{\overline{x},\perp}^{T,\overline{u}} \sigma_{\overline{y},\perp}^{\overline{u},\overline{u}}(\Phi),\Sigma ]
$$
\n
$$
+R_{\perp}R \xrightarrow[-R_{\overline{x},\perp}^{T,\overline{u}} \sigma_{\overline{y},\perp}^{\overline{u},\overline{u}}(\Phi) \vee R_{\overline{x},\perp}^{\overline{u},\overline{u}}(\Phi),\Sigma ]
$$
\n
$$
+R_{\perp}R \xrightarrow[-R_{\over
$$

$$
-R \underset{\mathbf{p}}{\underset{\mathbf{p}}{\rightarrow}} R_{\mathbf{p}} \underset{\mathbf{p}}{\underset{\mathbf{p}}{\rightarrow}} \underset{\mathbf{p}}{\mathcal{R}_{\mathbf{y},\mathbf{L}}^{\overline{\mathcal{R}},\overline{\mathcal{R}}}}; \quad \text{where } p \in P \text{,}
$$
\n
$$
-R_{\mathbf{y},\mathbf{L}} \underset{\mathbf{p}}{\underset{\mathbf{p}}{\mathcal{R}_{\mathbf{y},\mathbf{L}}^{\overline{\mathcal{R}},\overline{\mathcal{R}}}} \left(\Phi\right), \Sigma}{\underset{\mathbf{p}}{\rightarrow}} \underset{\mathbf{p}}{\mathcal{R}_{\mathbf{y},\mathbf{L}}^{\overline{\mathcal{R}},\overline{\mathcal{R}}}} \left(\Phi\right), \Sigma}{\underset{\mathbf{p}}{\rightarrow}} \left(\Phi\right), \Sigma}, \quad \text{where } \underset{\mathbf{p}}{\mathcal{R}_{\mathbf{y},\mathbf{L}}^{\overline{\mathcal{R}},\overline{\mathcal{R}}}} \left(\Phi\right), \Sigma}{\underset{\mathbf{p}}{\rightarrow}} \left(\Phi\right), \Sigma}, \quad \text{where } \underset{\mathbf{p}}{\mathcal{R}_{\mathbf{y},\mathbf
$$

$$
\begin{aligned}\n & \underset{-\vert R_{\perp} \vert N} \frac{\vert R_{\overline{y},\mathbb{I}}^{\overline{\eta},\overline{z}} \circ_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Phi), \Sigma}{\vert R_{\overline{y}}^{\overline{\eta}}(R_{\overline{y}}^{\overline{\eta}}(\Phi)), \Sigma}; \\
 & \underset{-\vert R_{\perp} \vert R} \frac{\vert R_{\overline{y},\mathbb{I}}^{\overline{\eta}} \circ_{\overline{x},\mathbb{I}}^{\overline{\eta}} (\Phi)), \Sigma}{\vert R_{\overline{y},\mathbb{I}}^{\overline{\eta},\overline{z}} \circ_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\tau}} (\Phi), \Sigma}, \\
 & \underset{-\vert R_{\overline{y},\mathbb{I}}^{\overline{\eta},\overline{z}} \left( \overline{R_{\overline{y},\mathbb{I}}^{\overline{\eta},\overline{\tau}} (\Phi), \Sigma}{\vert R_{\overline{y},\mathbb{I}}^{\overline{\eta},\overline{\mu}} (\Phi), \Sigma}, \right. \\
 & \left. \underset{-\vert R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} \left( \overline{\Phi}, \Sigma \right)}{\vert R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\mu}} (\overline{\Phi}), \Sigma}, \right. \\
 & \left. \underset{-\vert R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Phi) \vee R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Phi), \Sigma}{\vert R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Phi) \vee R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Psi), \Sigma}, \right. \\
 & \left. \underset{-\vert R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Phi) \vee R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Phi), \Sigma}{\vert R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\eta}} (\Phi \vee \Psi), \Sigma}, \right. \\
 & \left. \underset{-\vert \neg R_{\overline{x},\mathbb{I}}^{\overline{\eta},\overline{\
$$

Forms of  $\rightarrow$  elimination in formulas  $\neg Ey$  and  $\neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(Ez)$ :

$$
\vdash^{\neg\mathsf{E}} \frac{\neg Ez,\Sigma}{\vdash^{\neg\mathsf{E}z,\Sigma}}; \qquad \qquad \dashv^{\neg\mathsf{E}} \frac{\vdash^{\mathsf{E}z,\Sigma}}{\neg^{\neg\mathsf{E}z,\Sigma}}; \qquad \qquad \vdash^{\neg\mathsf{R}_{\bot\mathsf{E}}}\frac{\neg R_{\mathsf{X},\mathsf{L}}^{\overline{\mathsf{v}},\overline{\mathsf{u}}}(Ez),\Sigma}{\vdash^{\neg R_{\overline{\mathsf{X}},\mathsf{L}}^{\overline{\mathsf{v}},\overline{\mathsf{u}}}(Ez),\Sigma}; \qquad \qquad \dashv^{\mathsf{R}_{\overline{\mathsf{X}}}}\frac{\vdash^{\mathsf{R}_{\overline{\mathsf{X}},\mathsf{L}}^{\overline{\mathsf{v}},\overline{\mathsf{u}}}(Ez),\Sigma}{\neg^{\neg R_{\mathsf{X},\mathsf{L}}^{\overline{\mathsf{v}},\overline{\mathsf{u}}}(Ez),\Sigma}.
$$

Renomination simplification for variable assignment predicates (condition for  $_{\perp}R_{\perp}E$   $_{\perp}a_{\perp}R_{\perp}E$ :  $z \notin {\overline{\nu}, \overline{u}}$ ):

$$
\begin{array}{ll}\n\downarrow \text{R}_{\perp} \text{E} & \frac{\downarrow -Ez, \Sigma}{\downarrow -R_{\overline{x},\perp}^{\overline{v},\overline{u}}(Ez), \Sigma}; \\
& \downarrow \text{Recomposition forms:} \\
& \downarrow \text{P} & \frac{\downarrow -\Phi, \Sigma}{\downarrow -R_{\overline{x},\perp}^{\overline{v},\overline{u}}(Ez), \Sigma}; \\
& \downarrow \text{P} & \frac{\downarrow -\Phi, \Sigma}{\downarrow -R_{\overline{x},\perp}^{\overline{v},\overline{u},z}(Ez), \Sigma}; \\
& \downarrow \text{P} & \frac{\downarrow -\Phi, \Sigma}{\downarrow -R_{\overline{x},\perp}^{\overline{v},\overline{u},z}(Ez), \Sigma}; \\
& \downarrow \text{P} & \frac{\downarrow -\Phi, \Sigma}{\downarrow -R_{\overline{x},\perp}^{\overline{v},\overline{u},z}(Ez), \Sigma}; \\
& \downarrow \text{P} & \frac{\downarrow -\Phi, \Sigma}{\downarrow -R_{\overline{x},\perp}^{\overline{v},\overline{u},z}(Ez)};\n\end{array}
$$

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$$
\begin{array}{ll}\n\vdash^{\vee}\frac{\bot\Phi,\Sigma}{\bot\Phi\vee\Psi,\Sigma};\\
\vdash^{\neg\vee}\frac{\bot\Phi,\bot\Psi,\Sigma}{\bot\neg(\Phi\vee\Psi),\Sigma};\\
\vdash^{\neg\vee}\frac{\bot\neg\Phi,\bot\Psi,\Sigma}{\bot\neg(\Phi\vee\Psi),\Sigma};\\
\end{array};\\
$$

Forms of quantifier elimination:

$$
\begin{array}{lll}\n & +\exists & \frac{|-R_z^x(\Phi)_+ - Ez, \Sigma}{|- \exists x \Phi, \Sigma}; \\
 & & +\exists R_\perp \frac{|-R_{\overline{w},\perp,z}^{\overline{v},\overline{u},x}(\Phi)_+ - Ez, \Sigma}{|-R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi), \Sigma}; \\
 & & +\exists R_\perp \frac{|-R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi)_+ - Ez, \Sigma}{|-R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi), \Sigma}; \\
 & & +\neg R_\perp \frac{|\neg R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\Phi)_+ - R_{\overline{w},\perp,z}^{\overline{v}}(\Phi)_+)}{|- \neg R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\Phi)_+ - B_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\Phi)_+)}; \\
 & & +\neg R_\perp \frac{|\neg R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\Phi)_+ - R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\Phi)_+)}{|- \neg R_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi)_+ - R_{\overline{w},\perp,y}^{\overline{v},\overline{u},x}(\Phi)_+ - B_{\overline{w},\perp,y}^{\overline{v},\overline{u}}(\Phi)_+ - B_{\overline{w},\perp,y}^{\overline{v},\overline{u}}(\Phi)_+ - R_{\overline{w},\perp,y}^{\overline{v},\overline{u}}(\exists x \Phi)_+ - B_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi)_+ - B_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi)_+ - B_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi)_+ - B_{\overline{w},\perp,z}^{\overline{v},\overline{u}}(\exists x \Phi)_+ - B_{\overline{w},\perp,z}^{\overline{v},\overline
$$

Let us call forms  $\Box R_L$ ,  $\Box \Box R_L$ ,  $\Box J$ ,  $\Box J = \Box_T$ -forms; forms  $\Box \Box v$ ,  $\Box \Box v$ ,  $\Box R_L v$ ,  $\Box \Box R_L v - \Box_F$ -forms. Conditions for  $\Box$ ,  $\Box$ ,  $\Box$ :  $z \in \hat{f}u(\Sigma, \exists x \Phi)$ ; conditions for  $\Box$ R $\Box$ ,  $\Box$  $\Box$ R $\Box$ :  $z \in \hat{f}u(\Sigma, R^{\overline{v},\overline{u}}_{\overline{w},\bot}(\exists x \Phi))$ ; condition for  $\Box$ <sub>F</sub>-form: *Ey* does not belong to  $\Sigma$ .

Auxiliary forms of *E*-distribution Ed and primary definition of Ev:

$$
\text{Ed} \quad \frac{\vdash Ex, \Sigma \quad \vdash Ex, \Sigma}{\Sigma}; \qquad \qquad \text{Ev} \quad \frac{\vdash Ez, \Sigma}{\Sigma} \quad \text{given } z \in \text{fu}(\Sigma).
$$

**Basic sequent forms for the calculus** *С QIR***.** Forms |–R, –|R, |–RI, –|RI, |–RU, –|RU, |–R1, –|R1, |–R2, –|R2,  ${}_+RR, \, {}_+RR, \, {}_+R-, \, {}_+R\vee, \, {}_+R\vee, \, {}_+R\vee, \, {}_+R_\perp E, \, {}_+R_\perp Ev, \, {}_+R_\perp Ev, \, {}_+\vee, \, {}_-\vee, \, {}_-\exists, \, {}_+ \exists R_\perp, \, {}_-\exists v, \, {}_-\exists R_\perp v, \, Ed, \, Ev \, with \, addition \, of: \, \Box$ 

$$
\hspace{2cm} \mathcal{P} \rightarrow \frac{1}{\mathcal{P} \rightarrow \mathbf{0} \rightarrow \Sigma}; \hspace{2cm} \mathcal{P} \rightarrow \frac{1}{\mathcal{P} \rightarrow \mathbf{0} \rightarrow \Sigma}.
$$

**Basic sequent forms for the calculi**  $C_1^{QCT}$  **and**  $C_1^{QCTR}$ **. Their basic forms are the same, the difference is in** closure conditions for sequents. To the specified above sequent forms we add forms of the type  $R_1 \Box$  and forms of decomposition of | T and | T :

$$
\begin{array}{ll}\n & \underset{\vdash}{\mathsf{R}}_{\bot} \negthickspace\negthickspace\negthickspace\negthickspace\negthickspace-\mathsf{R}}_{\bot} \negthickspace\negthickspace\negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\left(\negthickspace\negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace-\mathsf{R}}_{\overline{\mathsf{x}},\bot} \negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace\rightarrow} \negthickspace\negthickspace\rightarrow} \negthickspace\rightarrow} \negthickspace\negthickspace\rightarrow} \negthickspace\rightarrow} \negthickspace
$$

**Basic sequent forms for the calculi**  $C_1^{QCF}$  **and**  $C_1^{QCFR}$ **. Their basic forms are the same, the difference is in** closure conditions for sequents. We take the sequent forms for calculi  $C_1{}^{QCT}$  and  $C_1{}^{QCTR}$  replacing forms  $\bigcap_{n=1}^{\infty}$  and  $\bigcap_{n=1}^{\infty}$ by  $_{\vdash}$  -  $_{\sqsubseteq}$  and  $_{\dashv}$  -  $_{\sqsubseteq}$  :

$$
T_{\text{max}} = \frac{1}{T_{\text{max}} \cdot \frac{1}{T_{\text{max}} \cdot \frac{1}{T_{\text{max}}}} \cdot \frac{1}{T_{\text{max}} \cdot \frac{1}{T_{\
$$

 $\mathbf{r}$ 

Forms of types R, RI, RU,  $R_{\perp}$  are *auxiliary*, they are used every time the specified situation arises. Forms Ed and Ev are also specific; all the other basic sequents are *main forms*.

**The main property of sequent forms.** Let  $|=\ast\>}$  be one of the introduced logical consequence relations.

**Theorem 9.** 1. Let 
$$
\frac{|A| |\mathbf{A}|}{|A| |\mathbf{A}|}
$$
 be a basic sequent form. Then: a)  $\Lambda |=_{*} K \Leftrightarrow \Gamma |=_{*} \Delta$ ; b)  $\Gamma | \neq_{*} \Delta \Leftrightarrow \Lambda | \neq_{*} K$ .  
2. Let  $\frac{|A| |K|}{|A| |\mathbf{A}|^2}$  be a basic sequent form. Then: a)  $\Lambda |=_{*} K$  and  $X |=_{*} Z \Leftrightarrow \Gamma |=_{*} \Delta$ ; b)  $\Lambda | \neq_{*} K$  or  $X | \neq_{*} Z \Leftrightarrow \Gamma | \neq_{*} \Delta$ .

**Procedure of construction of a sequent tree.** The main action during the process of derivation (construction of a sequent tree) is decomposition or simplification of a formula choosen from the sequent. We treat sequents as *sets* of signed formulas, so we will not add there another copy of a formula that may happen to be obtained at some stage of derivation.

Let us describe all stages of the procedure for a given *finite* sequent  $\Sigma$ .

We start from the root. On the initial stage *primary distribution* of names is performed: we obtain all the possible distributions of names from  $ud(\Sigma)$  to defined and undefined by applying Ed-form. This leads to a tree of a height  $h = |ud(\Sigma)|$  with root  $\Sigma$  and  $m = 2^h$  descendants. If  $val(\Sigma) = \emptyset$ , we use Ev-form to perform primary definition for a descendant sequent  $\Sigma_0$  with  $val(\Sigma_0) = \emptyset$ :  $\Sigma_0$  is enriched with formula  $E_z$  such that  $z \in fu(\Sigma)$ , so sequent  $\Sigma_0$ ,  $E_z$  is obtained. As a result, the set of defined names is not empty for all descendants of  $\Sigma$  which guarantees applicability of  $\exists_F$ -forms.

Let us describe derivation of an unclosed sequent leaf  $\eta$ ; this implies building a finite subtree with node  $\eta$ . We activate all non-primitive formulas in the sequent  $\eta$ . A corresponding main form is applied to each active formula. During the process, every time the situation arise, appropriate auxiliary forms R, R<sub>I</sub>I, R<sub>I</sub>U, R<sub>I</sub><sup>†</sup> are used for simplifications.

Forms  $R_1$  are applied to primitive formulas and their negations. After that, all primitive formulas in the sequent and their negations become *Un*-formulas, where *Un* is a set of all *unv*-variables of formulas in sequents in the path from root to the current sequent.

Resulting formula(s) become(s) *passive* after application of a main form and implicated simplifications: at this stage main forms can not be used on them.

Let us take a look at main forms' application. At first, we use all the forms except  $\exists_F$ -forms. With each application of  $\exists_{\rm T}$ , a *new* (absent in the path from root to the current sequent)  $z \in V_T$  is taken.  $\exists_{\rm F}$ -forms are applied after  $\exists_{\rm T}$ forms.  $\exists_F$ -form should be used repeatedly for each defined *y* of formulas in the path from  $\Sigma$  to the current sequent.

When no active formulas are left on the current stage, we need to check every sequent leaf  $\Omega$  on closedness. If *all* the leaves are closed sequents, we obtained a finite closed tree: the procedure ended *positively*.

If a sequent leaf  $\Omega$  is unclosed, it has to be checked whether  $\Omega$  is a final sequent.

Unclosed sequent node  $\Omega$  is called *final*, if there is no applicable form to it or no *new* (differing from formulas on the path from  $\Sigma$  to  $\Omega$ ) formula can be obtained using applicable forms. It signals that the sequent tree has an *unclosed* path (from root to the current final sequent, all its nodes are unclosed sequents): the derivation process ended *negatively*.

Thus, during construction of a sequent tree the following cases are possible:

1) construction procedure is completed positively; we obtained a finite closed tree;

2) construction procedure is completed negatively; we obtained a finite unclosed tree. Such tree has at least one unclosed path, all nodes of which are unclosed sequents.

3) construction procedure is not completed; we obtained an infinite unclosed tree. König's lemma [2] states that such tree has at least one infinite path. All its nodes should be unclosed sequents, otherwise this path would finish. Hence, there is an infinite unclosed path in the tree.

Let us see the differences in the construction of a sequent tree for a given *countable* sequent  $\Sigma$ .

The process also has its stages and starts from the root  $\Sigma$ . There is a finite set of *available* on the current stage formulas (see [4, 6]); forms can be applied only to these formulas. In the beginning a pair of first formulas from the lists of *T*-formulas and *F*-formulas of the sequent  $\Sigma$  is available (and one of the lists can be empty).

Every stage starts with an access step for all unclosed sequents: another pair from the lists of *T*-formulas and *F*formulas of a sequent is added to the set of available formulas. Let n be a sequent obtained in the beginning of a stage after adding a pair of new available formulas. *Stage distribution* of names is performed next: we obtain all the possible distributions of names from  $ud(\eta)$  to defined and undefined by applying Ed-form. This leads to a subtree of a height | $|ud(\eta)|$  with root  $\eta$  and  $k = 2^{|ud(\eta)|}$  descendants. If  $val(\eta) = \emptyset$ , we use Ev-form to perform primary definition for a descendant sequent  $\eta_0$  with  $val(\eta_0) = \emptyset$  and obtain a sequent  $\eta_0$ , *Ez*.

Forms' application is not different from the finite sequent case.

When no active formulas are left on the current stage, every sequent leaf  $\Omega$  is checked on closedness. If *all* the leaves are closed sequents, we obtained a finite closed tree: the procedure ended *positively*. Otherwise begin the next stage. For a sequent tree for a countable sequent the notion of a final node does not make sense, thus only two outcomes are possible:

1) procedure is completed positively; we obtained a finite closed tree;

2) procedure is not completed; we obtained an infinite unclosed tree with an infinite unclosed path: every formula of the sequent  $\Sigma$  will appear in this path and become available.

**The soundness theorem.** It has the same formulation for all introduced calculi. Let the logical consequence relations  $P_{r} = R_{r}P_{r} = R_{r}P_{r$  $C_{\perp}^{QCT}$ ,  $C_{\perp}^{QCF}$ ,  $C_{\perp}^{QCTR}$ ,  $C_{\perp}^{QCFR}$  respectively. We obtain

**Theorem 10** (soundness). Let sequent  $\Gamma \vdash \Delta$  is derivable in  $C_{\perp}^{O^{\#}}$ . Then  $\Gamma \models_{*} \Delta$ .

If  $\perp \Gamma \perp \Delta$  is derivable in a calculus  $C_{\perp}^{Q^{\#}}$ , then a finite closed tree was constructed for  $\perp \Gamma \perp \Delta$ . For any node of this tree  $\Box$ A $\Box$ K we have  $\Lambda$  |=  $\Box$ K. For leaves it is implied from the notion of a closed sequent. By Theorem 9, sequent forms preserve logical consequence relation. Hence, for the root  $\Box \Box \Delta$  we also have that  $\Gamma \models_{\ast} \Delta$  holds.

#### **4. The counter-model existence theorems. The completeness theorem**

The completeness of sequent calculi is traditionally proved on the basis of theorems of the existence of a counter-model for the set of formulas of an unclosed path in the sequent tree. In this case a method of *Hintikka (model) sets* is used ([4]). Let us apply this method for the calculi  $C_1^{QCTR}$  and  $C_1^{QCFR}$ .

**Theorem 11.** Let  $\wp$  be an unclosed path in the derivation tree constructed in  $C_1^{QCTR}$  for a sequent  $\vdash \Gamma \not\rightarrow \Delta$ ; let *H* be the set of all specified formulas of this path. Then there exist an interpretation  $A = (S, I)$  and data  $\delta \in S'$  such that:

 $H_T$ )  $\Box \Phi \in H \implies \delta \in T(\Phi_A)$  and  $\Box \Phi \in H \implies \delta \notin T(\Phi_A)$ .

**Theorem 12.** Let  $\wp$  be an unclosed path in the derivation tree constructed in  $C_1^{QCFR}$  for a sequent  $\vdash \Gamma \not\models \Delta$ ; let *H* be the set of all specified formulas of this path. Then there exist an interpretation  $\mathbf{B} = (S, I)$  and data  $\delta \in \mathcal{A}$  such that:

 $H_F$ )  $\Box \Phi \in H \implies \delta \notin F(\Phi_B)$  and  $\Box \Phi \in H \implies \delta \in F(\Phi_B)$ .

Let  $(A, \delta)$  be called *T*-counter-model and let  $(B, \delta)$  be called *F*-counter-model for a sequent  $\Box \Box \Delta$ .

Let us define a set  $Un = \{y \in nm(H) | \exists Ey \in H\}$  and call it a set of undefined names of the set *H*. Let us specify  $W = nm(H) \setminus Un$ . The primary definition gives the condition  $W = \{y \in nm(H) | \perp Ey \in H\}$ .

Theorems 11 and 12 are proved in the same style. We continuously apply forms to sequents of the path  $\varnothing$  while we can: in the end, every non-primitive formula of the path (or its negation) will be decomposed or simplified. All the sequents of the path  $\wp$  are unclosed, therefore the closure condition does not hold:  $C \vee CF \vee C \dashv \Box$  for  $C_1^{\ Q CTR}$  and  $C \vee CF \vee \text{Cl}$  for  $C_{\perp}^{QCFR}$ . Thus, for the set *H* the following correctness conditions hold:

HC) there is no formula  $\Phi$  such that  $\Phi \in H$  and  $\Phi \in H$ ;

HCF) there is no formula  $R_{\overline{x},\perp,\perp}^{\overline{y},\overline{u},z}(Ez)$  such that  ${}_{\vert_{\Gamma}}R_{\overline{x},\perp,\perp}^{\overline{y},\overline{u},z}(Ez) \in H$ ;

HC- $\Box$ ) there is no formula  $\Phi$  such that  $\Box \Box \Phi \in H$  – for the set *H* from theorem 11;

 $HC \Box$ ) there is no formula  $\Phi$  such that  $\Box \Box \Phi \in H$  – for the set *H* from theorem 12.

We can move from lower to higher node of the path  $\wp$  after applying a certain sequent form, therefore the corresponding conditions for transition for *Н* should hold. In particular:

HR<sub>⊥</sub>11) 
$$
+Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},y}(p) \in H \implies -R_{x,\perp,z}^{\overline{v},\overline{u},y}(p) \in H; \quad +Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},y}(p) \in H \implies -R_{x,\perp,z}^{\overline{v},\overline{u},y}(p) \in H;
$$
  
\nH
$$
+R_{\perp}11) +Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},y}(p) \in H \implies -R_{x,\perp,z}^{\overline{v},\overline{u},y}(p) \in H;
$$
  
\n
$$
+Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},z}(p) \in H \implies -R_{x,\perp,z}^{\overline{v},\overline{u}}(p) \in H;
$$
  
\nHR<sub>⊥</sub>12) 
$$
+Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},z}(p) \in H \implies -R_{x,\perp,z}^{\overline{v},\overline{u}}(p) \in H;
$$
  
\nH<sub>−R<sub>⊥</sub></sub>12) 
$$
+Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},z}(p) \in H \implies -R_{x,\perp}^{\overline{v},\overline{u}}(p) \in H;
$$
  
\nH<sub>−R<sub>⊥</sub></sub>12) 
$$
+Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},z}(p) \in H \implies -R_{x,\perp}^{\overline{v},\overline{u}}(p) \in H;
$$
  
\n
$$
+Ez \in H
$$
 and 
$$
+R_{x,\perp,z}^{\overline{v},\overline{u},z}(p) \in H \implies -R_{x,\perp}^{\overline{v},\overline{u}}(p) \in H;
$$
  
\n

above conditions of transition and the condition  $H \Box_T$  apply, an  $R_{TC}$ *-model set*. Let us call the set of signed formulas *H* for which the conditions of correctness HC, HCF, HC $\Box$ , the specified

above conditions of transition and the condition  $H \neg \Box_F$  apply, an  $R_{FC}$ *model set*.

Conditions  $H \sqcap_T$  and  $H \sqcap_T$  are defined as follows:

 $H \Box$   $\Box$   $\Box$   $\Box$   $\Phi \in H \implies \Box \Phi \in H$  and  $\Box \neg \Phi \in H$ ;  $\Box$   $\Box$   $\Phi \in H \implies \Box \Phi \in H$  or  $\Box \neg \Phi \in H$ ;

$$
H \cap \Box_F) \Box \Box \Phi \in H \implies \Box \Phi \in H \text{ or } \Box \Box \Phi \in H; \Box \Box \Phi \in H \implies \Box \Phi \in H \text{ and } \Box \Box \Phi \in H.
$$

Let us obtain a counter-model using the  $R_{TC}$ -model set *H*. Let *S* be a set such that  $|S| = |W|$ . We need to take an injective  $\delta \in V S$  with its domain *W*; such  $\delta$  is a bijection *W* $\mathbb{R}$  *S*.

 $⊩Ex ∈ H$  gives  $x ∈ W$ , then  $Ex_A(δ) = T$ , therefore  $δ ∈ T(EX_A)$ ;  $⊒Ex ∈ H$  gives  $x ∉ W$ , then  $δ(x)$ ↑, therefore  $δ ∉ T(EX_A)$ .

Let us specify basic values of predicates: we define values of atomic formulas, primitive *Un*-formulas and their negations on  $\delta$  in interpretation  $\vec{A}$  as follows:

$$
\neg \neg P \in H \Rightarrow \delta \in T(p_A); \neg P \in H \Rightarrow \delta \notin T(p_A); \neg \neg P \in H \Rightarrow \delta \in T(\neg P_A); \neg \neg P \in H \Rightarrow \delta \notin T(\neg P_A);
$$
\n
$$
\neg \neg P \in T, \overline{R}_{\overline{x},\perp}^{\overline{v},\overline{u}}(p) \in H \Rightarrow \delta \in T(R_{\overline{x},\perp}^{\overline{v},\overline{u}}(p)_A); \neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(p) \in H \Rightarrow \delta \notin T(R_{\overline{x},\perp}^{\overline{v},\overline{u}}(p)_A);
$$
\n
$$
\neg \neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(p) \in H \Rightarrow \delta \in T(\neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(p)_A); \neg \neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(p) \in H \Rightarrow \delta \notin T(\neg R_{\overline{x},\perp}^{\overline{v},\overline{u}}(p)_A).
$$

In the same way we can obtain a counter-model using the  $R_{FC}$ -model set *H*. *S* and  $\delta$  are defined similarly.

 $\Box E x \in H$  gives  $x \in W$ , then  $Ex_A(\delta) = T$ , therefore  $\delta \notin F(EX_B)$ ;  $\Box Ex \in H$  gives  $x \notin W$ , then  $\delta(x)$  t, therefore  $\delta \in F(EX_B)$ . We specify basic values of predicates, defining values of atomic formulas, primitive *Un*-formulas and their negations on  $\delta$  in interpretation  $\boldsymbol{B}$  as follows:

$$
\neg \neg P \in H \Rightarrow \delta \notin F(p_B); \neg p \in H \Rightarrow \delta \in F(p_B); \neg \neg p \in H \Rightarrow \delta \notin F(\neg p_B); \neg \neg p \in H \Rightarrow \delta \in F(\neg p_B);
$$
\n
$$
\neg \neg R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p) \in H \Rightarrow \delta \notin F(R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p)_B); \neg R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p) \in H \Rightarrow \delta \in F(R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p)_B);
$$
\n
$$
\neg \neg R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p) \in H \Rightarrow \delta \notin F(\neg R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p)_B); \neg \neg R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p) \in H \Rightarrow \delta \in F(\neg R_{\overline{x}, \perp}^{\overline{v}, \overline{u}}(p)_B).
$$

For atomic formulas, primitive *Un*-formulas and their negations, statements of theorem 11 and theorem 12 hold basing on the definitions above.

We will prove the condition  $HR_1 \uparrow 1$  for both interpretations *A* and *B*.

Let  $\downarrow$  *Ez* $\in$ *H* and  $\downarrow$   $\underset{\overline{x}, \perp, z}{R^{\overline{y}, \overline{u}, y}}(p) \in$ *H*. Condition  $\downarrow$  *Ez* $\in$ *H* gives  $z \notin W$ , then  $\delta(z)$ **f**, therefore  $\underset{\overline{x}, \perp, \perp}{R^{\overline{y}, \overline{u}, y}}(\delta) = \underset{\overline{x}, \perp, z}{r^{\overline{y}, \overline{u}, y}}(\delta)$ .

By HR<sub>1</sub><sup>†</sup>1 we have  ${}_{\vdash}R^{\overline{v},\overline{u},y}_{\overline{x},\perp,\perp}(p) \in H$ . Whence  $\delta \in T(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,\perp}(p)_A)$ ,  $\delta \in T(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,z}(p)_A)$  and  $\delta \notin F(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,\perp}(p)_B)$ ,  $,\overline{\overline{u}},$ 

$$
\delta \notin F(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,z}(p)_B).
$$

Let  $\#Ez \in H$  and  $\lim_{\pi \to \pi} R^{\overline{v},\overline{u},y}(p) \in H$ . Condition  $\#Ez \in H$  gives  $z \notin W$ , then  $\delta(z)$ <sup>†</sup>, therefore  $\mathbf{r}_{\overline{x},\perp,\perp}^{\overline{v},\overline{u},y}(\delta) = \mathbf{r}_{\overline{x},\perp,z}^{\overline{v},\overline{u},y}(\delta)$ .

By HR<sub>1</sub><sup>†</sup>1 we have  ${}_{-1}R^{\overline{v},\overline{u},y}_{\overline{x},\perp,\perp}(p) \in H$ . Whence  $\delta \notin T(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,\perp}(p)_A)$ ,  $\delta \notin T(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,z}(p)_A)$  and  $\delta \in F(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,\perp}(p)_B)$ ,  $\delta \in F(R^{\overline{v},\overline{u},y}_{\overline{x},\perp,z}(p)_B)$ .

The proof will be similar for the conditions  $H-R_1 \uparrow 1$ ,  $HR_1 \uparrow 2$ ,  $H-R_1 \uparrow 2$  and  $H_{\neg F}$ ,  $H_{\neg R/F}$ .

The rest can be proved by the usual way by induction on the formula structure.

We will illustrate it for H $\Box$  T (theorem 11) and H $\neg$   $\Box$  F (theorem 12).

Let  $\Box \Box \Phi \in H$ . By H $\Box_T$  we have  $\Box \Phi \in H$  and  $\Box \neg \Phi \in H$ . By induction hypothesis we have  $\delta \notin T(\Phi_A)$  and  $\delta \notin T(\neg \Phi_A) = F(\Phi_A)$ , whence  $\delta \in \bot(\Phi_A)$ . However  $\bot(\Phi_A) = T(\Box \Phi_A)$ , therefore  $\delta \in T(\Box \Phi_A)$ .

Let  $\Box \Box \Phi \in H$ . Be  $H \Box_T$  we have  $\Box \Phi \in H$  or  $\Box \neg \Phi \in H$ . By induction hypothesis we have  $\delta \in T(\Phi_A)$  or  $\delta \in T(-\Phi_A) = F(\Phi_A)$ , whence  $\delta \notin L(\Phi_A)$ . However  $L(\Phi_A) = T(\Box \Phi_A)$ , therefore  $\delta \notin T(\Box \Phi_A)$ .

Let  $\Box \Box \Phi \in H$ . By  $H \cap \Box_F$  we have  $\Box \Phi \in H$  or  $\Box \neg \Phi \in H$ . By induction hypothesis we have  $\delta \in F(\Phi_B)$  or

 $\delta \in F(\neg \Phi_B) = T(\Phi_B)$ , whence  $\delta \notin \bot(\Phi_B)$ . However  $\bot(\Phi_B) = T(\Box \Phi_B) = F(\neg \Box \Phi_B)$ , therefore  $\delta \notin F(\neg \Box \Phi_B)$ .

Let  $\Box$   $\neg$   $\neg$   $\neg$   $\neg$   $\neg$   $H$ . By  $H \neg \Box_F$  we have  $\varphi \in H$  and  $\varphi \neg \Phi \in H$ . By induction hypothesis we have  $\delta \notin F(\Phi_B)$  and  $\delta \notin F(\neg \Phi_B) = T(\Phi_B)$ , whence  $\delta \in \bot(\Phi_B)$ . However  $\bot(\Phi_B) = T(\Box \Phi_B) = F(\neg \Box \Phi_B)$ , therefore  $\delta \in F(\neg \Box \Phi_B)$ .

The counter-model existence theorems for the calculi  $C_1^{QCT}$  and  $C_1^{QCF}$  can be formulated and proved similarly. As calculi  $C_1^{QCT}$  and  $C_1^{QCF}$  formalize relations  $P^c \models_T$  and  $P^c \models_F$ , all the predicates  $\Phi_A$  and  $\Phi_B$  need to be single-valued.

Additional correctness conditions should be specified for the set *Н*:

HCL) there is no formula  $\Phi$  such that  $\phi_{\phi}$  – $\neg \Phi \in H$  (case of derivation in  $C_{\phi}^{QCT}$ );

HCR) there is no formula 9 such that  $\Box$ 9,  $\neg$  9 $\in$ *H* (case of derivation in  $C_{\perp}^{QCF}$ ).

The counter-model existence theorems for the calculi  $C_{\perp}^{QT}$  and  $C_{\perp}^{QF}$  can be formulated and proved similarly to theorems 11 and 12: conditions HR  $\Box$ , H-R  $\Box$ , H $\Box$ , H- $\Box$ , H- $\Box$  and HC $\Box$ , HC- $\Box$  should be omitted, conditions НСL and НСR added instead.

Let us specify the counter-model existence theorems for the calculi  $C_1^{QTFR}$ ,  $C_1^{QTF}$  and  $C_1^{QR}$ .

**Theorem 13.** Let  $\wp$  be an unclosed path in the derivation tree constructed in  $C_1^{QTFR}$  for a sequent  $\vdash \Gamma \not\rightarrow \Delta$ ; let *H* be the set of all specified formulas of this path. Then there exist interpretations  $A = (S, I_A)$ ,  $B = (S, I_B)$  and data  $\delta \in S'$  such that conditions  $H_T$  and  $H_F$  hold.

We will call such  $(A, \delta)$  and  $(B, \delta)$  *T*-counter-model and *F*-counter-model for  $\Box \Box \Delta$ .

**Theorem 14.** Let  $\wp$  be an unclosed path in the derivation tree constructed in  $C_1^{QTF}$  for a sequent  $\Box$  $\Box$  $\Box$  $\Box$ ; let *H* be the set of all specified formulas of this path. Then there exist interpretations  $A = (S, I_A)$ ,  $B = (S, I_B)$  and data  $\delta \in K^V S$  such that conditions  $H_T$  and  $H_F$  hold.

We will call such  $(A, \delta)$  and  $(B, \delta)$   $T^P$ -counter-model and  $F^P$ -counter-model for  $\Box \Box \Delta$ .

In the proofs of theorems 13 and 14 the conditions  $HR_1 \Box$ ,  $H \neg R_1 \Box$ ,  $H \neg \Box$ ,  $H \neg \Box$ , and  $HCl$ ,  $HC \Box \Box$ , are omitted; the following correctness condition НСLR is added for theorem 14:

HCLR) there are no formulas  $\Phi$  and  $\theta$  such that  $\phi_{\mu} \rightarrow \Phi \in H$  and  $\phi_{\mu} \rightarrow \Phi \in H$ .

Obviously, HCLR  $\Leftrightarrow$  HCL  $\vee$  HCR. One should make clear the choice of a counter-model in this situation. For *T*<sup>*P*</sup>counter-model  $\delta$ , violation of the condition HCL (there is a formula  $\Phi$  such that  $\Box \Phi \in H$  and  $\Box \neg \Phi \in H$ ) gives  $\Phi_A(\delta) = T$ and  $\neg \Phi_A(\delta) = T$ , therefore  $\Phi_A(\delta) = F$ , and ambiguity for  $\Phi_A$ . For  $F^P$ -counter-model  $\eta$  violation of the condition HCR,

(there is a formulda  $\theta$  such that  $\theta \in H$  and  $\theta \in H$ ) gives  $\theta_B(\delta) = F$  and  $\theta_B(\delta) = F$ , therefore  $\theta_B(\delta) = T$ , and ambiguity for  $\vartheta_B$ .

Thus, should we have the condition HCLR, in the case of violation of HCL we choose the  $F<sup>p</sup>$ -counter-model, and in the case of violation of HCR we choose the  $T^P$ -counter-model; we can choose any of the two counter-models if both conditions НСL and НСR hold.

**Theorem 15.** Let  $\wp$  be an unclosed path in the derivation tree constructed in  $C_1^{QR}$  for a sequent  $\vdash \Gamma \dashv \Delta$ ; let *H* be the set of all specified formulas of this path. Then there exist interpretation  $A = (S, I)$  and data  $\delta \in S'$  such that:

 $H_C$ )  $\downarrow$   $\Phi \in H \Rightarrow \Phi_A(\delta) = T$  and  $\downarrow$   $\Phi \in H \Rightarrow \Phi_A(\delta) = F$ .

We will call such  $(A, \delta)$  *IR*-counter-model for  $\Box \Box \Delta$ .

Theorems of the existence of a counter-model for the considered sequent calculi allow us to prove the completeness theorem. It has the same formulation for all these calculi. Let the logical consequence relations  $P|_{F,R}$ ,  $C_{\perp}^{QCTR}$ ,  $C_{\perp}^{QCFR}$  respectively. We obtain

**Theorem 16** (completeness). Let  $\Gamma \models_{*} \Delta$ . Then sequent  $\Gamma \Box \Delta$  is derivable in  $C_{\perp}^{Q^{\#}}$ .

Let us prove for relation  $\binom{Rc}{r} = T$  and calculus  $C_{\perp}^{QCTR}$  (for more similar proofs see [4, 11]).

Assume that  $\Gamma^{Rc}$   $\models_T \Delta$ , but sequent  $\bot \Box \Delta$  is not derivable. In this case a sequent tree for  $\bot \Box \Delta$  is not closed. Thus, an unclosed path  $\wp$  exists in this tree. Let *H* be the set of all signed formulas of this path. By Theorem 11, there is a *T*counter-model  $(A, \delta)$ :  $\Box \Phi \in H \Rightarrow \delta \in T(\Phi_A)$  and  $\Box \Phi \in H \Rightarrow \delta \notin T(\Phi_A)$ .

By  $\perp \Gamma \perp \Delta \subseteq H$  for all  $\Phi \in \Gamma$  we have  $\delta \in T(\Phi_A)$ , for all  $\Psi \in \Delta$  we have  $\delta \notin T(\Psi_A)$ . Whence  $\delta \in T(\Gamma_A)$  and  $\delta \notin T(\Delta_A)$ , therefore  $T(\Gamma_A) \subseteq T(\Delta_A)$  does not hold. This contradicts to  $\Gamma_A = T\Delta$ , so it contradicts to  $\Gamma^{Re} = T\Delta$ .

#### **Conclusion**

We have studied new classes of program-oriented logical formalisms – pure first-order logics of quasiary predicates with extended renominations and a composition of predicate complement. Such operations are used in various versions of the Floyd-Hoare program logic with partial pre- and post-conditions. We have considered composition systems and languages of these logics, specified various logical consequence relations and described properties of formulas decomposition and quantifier elimination.

Properties of logical consequence relations form a semantic base for construction of corresponding calculi of sequent type. We have defined basic sequent forms for the specified calculi and closeness conditions, and illustrated the process of derivation (building a sequent tree). The soundness, completeness, and counter-model existence theorems are proved for the introduced calculi.

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