# A Simple Algorithm for Graph Reconstruction

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#### Abstract

How efficiently can we find an unknown graph using distance queries between its vertices? We assume that the unknown graph is connected, unweighted, and has bounded degree. The goal is to find every edge in the graph. This problem admits a reconstruction algorithm based on multi-phase Voronoi-cell decomposition and using  $\tilde{O}(n^{3/2})$  distance queries [27].

In our work, we analyze a simple reconstruction algorithm. We show that, on random  $\Delta$ -regular graphs, our algorithm uses  $\tilde{O}(n)$  distance queries. As by-products, we can reconstruct those graphs using  $O(\log^2 n)$  queries to an all-distances oracle or  $\tilde{O}(n)$  queries to a betweenness oracle, and we bound the metric dimension of those graphs by  $\log^2 n$ .

Our reconstruction algorithm has a very simple structure, and is highly parallelizable. On general graphs of bounded degree, our reconstruction algorithm has subquadratic query complexity.

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# 1 Introduction

Discovering the topology of the Internet is a crucial step for building accurate network models and designing efficient algorithms for Internet applications. The topology of Internet networks is typically investigated at the router level, using traceroute. It is a common and reasonably accurate assumption that traceroute generates paths that are shortest in the network. Unfortunately, sometimes routers block traceroute requests due to privacy and security concerns. As a consequence, the inference of the network topology is rather based on the end-to-end delay information on those requests, which is roughly proportional to the shortest-path distances in the network.

In the graph reconstruction problem, we are given the vertex set V of a hidden connected, undirected, and unweighted graph and have access to information about the topology of the graph via an oracle, and the goal is to find every edge in E. Henceforth, unless explicitly mentioned, all graphs studied are assumed to be connected. This assumption is standard and shared by almost all references on the subject, e.g., [7, 14, 27, 39, 41]. The efficiency of an algorithm is measured by the query complexity, i.e., the number of queries to the oracle. Motivated by traceroute, the literature has explored several types of query oracles.

- One type consists of *all-shortest-paths* and *all-distances* queries, when querying a vertex yields either shortest paths from that vertex to all other vertices [7, 41] or distances from that vertex to all other vertices [14]. The latter, of course, is less informative.
- A more refined type of query oracles, suggested in [7, 14], consists of *shortest-path* and *distance* queries, when querying a pair of vertices yields either a shortest path or the distance between them [27, 38, 39]. Again, the latter is less informative.

In this work, we focus on the weakest of those four query oracles, that takes as input a pair of vertices a and b and returns the distance  $\delta(a,b)$  between them. Reyzin and Srivastava [38] showed that graph reconstruction requires  $\Omega(n^2)$  distance queries on general graphs, so we focus on the bounded degree case. For graphs of bounded degree, Kannan, Mathieu, and Zhou [27] gave a reconstruction algorithm based on multi-phase Voronoi-cell decomposition and using  $\tilde{O}(n^{3/2})$  distance queries, and raised an open question of whether  $\tilde{O}(n)$  is achievable.<sup>1</sup>

We provide a partial answer to that open question by analyzing a simple reconstruction algorithm (Algorithm 1). We show that, on (uniformly) random  $\Delta$ -regular graphs, where every vertex has the same degree  $\Delta$ , our reconstruction algorithm uses  $\tilde{O}(n)$  distance queries (Theorem 1). As by-products, we can reconstruct those graphs using  $O(\log^2 n)$  queries to an all-distances oracle (Corollary 2) or using  $\tilde{O}(n)$  queries to a betweenness oracle (Corollary 3), and we bound the metric dimension of those graphs by at most  $\log^2 n$  (Corollary 5).

Our analysis exploits the *locally tree-like* property of random  $\Delta$ -regular graphs, meaning that these graphs contain a small number of short cycles. Our method might be applicable to other locally tree-like graphs, such as Erdös-Rényi random graphs and *scale-free* graphs. In particular, many real world networks, such as Internet networks, social networks, and peer-to-peer networks, are believed to have scale-free properties [6, 25, 34]. We defer the reconstruction of those networks for future work.

Our reconstruction algorithm has a very simple structure, and is highly parallelizable (Corollary 4). On general graphs of bounded degree, the same reconstruction algorithm has subquadratic query complexity (Theorem 6).

#### 1.1 Related Work

The problem of reconstructing a graph using queries that reveal partial information has been extensively studied in different contexts and has many applications.

### **Reconstruction of Random Graphs**

The gist of our paper deals with random graphs. The graph reconstruction problem has already attracted much interest in the setting of random graphs. On Erdös-Rényi random graphs, Erlebach, Hall, and Mihal'ák [15] studied the approximate network reconstruction using all-shortest-paths queries; Anandkumar, Hassidim, and Kelner [4] used end-to-end measurements between a subset of vertices to approximate the network structure. Experimental results to reconstruct random graphs using shortest-path queries were given in [8, 20].

On random  $\Delta$ -regular graphs, Achlioptas et al. [2] studied the bias of traceroute sampling in the context of the network reconstruction. They showed that the structure revealed by traceroute sampling on random  $\Delta$ -regular graphs admits a power-law degree distribution [2], a common phenomenon as in Erdös-Rényi random graphs [31] and Internet networks [16].

#### Metric Dimension and Related Problems

Our work yields an upper bound on the *metric dimension* of random  $\Delta$ -regular graphs. The metric dimension problem was first introduced by Slater [42] and Harary and Melter [21], see also [5, 13, 12, 23, 29, 36, 37, 40]. The metric dimension of a graph is the cardinality of

<sup>&</sup>lt;sup>1</sup> The notation  $\tilde{O}(f(n))$  stands for  $O(f(n) \cdot \text{polylog } f(n))$ .

a smallest subset S of vertices such that every vertex in the graph has a unique vector of distances to the vertices in S. On regular graphs, the metric dimension problem was studied in special cases [12, 24]. In Erdös-Rényi random graphs, the metric dimension problem was studied by Bollobás, Mitsche, and Prałat [11]. Mitsche and Rué [32] also considered the random forest model.

A related problem is the *identifying code* of a graph [28], which is a smallest subset of vertices such that every vertex of the graph is uniquely determined by its neighbourhood within this subset. The identifying code problem was studied on random  $\Delta$ -regular graphs [17] and on Erdös-Rényi random graphs [19]. Other related problems received attentions on random graphs as well, such as the *sequential metric dimension* [35] and the *seeded graph matching* [33].

#### **Betweenness Oracle**

There exists an oracle that is even weaker than the distance oracle: the betweenness oracle [1], which receives three vertices u, v, and w and returns whether w lies on a shortest path between u and v. Our work yields a reconstruction algorithm using  $\tilde{O}(n)$  betweenness queries on random  $\Delta$ -regular graphs. For graphs of bounded degree, Abrahamsen et al. [1] generalized the  $\tilde{O}(n^{3/2})$  result in the distance oracle model from [27] to the betweenness oracle model.

## Tree Reconstruction and Parallel Setting

Our paper focuses on the distance oracle and bounded degree, and considers the parallel setting. All of those aspects were previously raised in the special case of the *tree reconstruction*. Indeed, motivated by the reconstruction of a phylogenetic tree in evolutionary biology, the tree reconstruction problem using a distance oracle is well-studied [22, 30, 43], in particular assuming bounded degree [22]. Afshar et al. [3] studied the tree reconstruction in the parallel setting, analyzing both the *round complexity* and the *query complexity* in the relative distance query model [26].

#### 1.2 Our Results

Our reconstruction algorithm, called SIMPLE, is given in Algorithm 1. It takes as input the vertex set V of size n and an integer parameter  $s \in [1, n]$ .

#### Algorithm 1 SIMPLE (V, s).

- 1:  $S \leftarrow$  sample of s vertices selected uniformly and independently at random from V
- 2: for  $u \in S$  and  $v \in V$  do QUERY(u, v)
- 3:  $\hat{E} \leftarrow \text{set of vertex pairs } \{a, b\} \subseteq V \text{ such that, for all } u \in S, |\delta(u, a) \delta(u, b)| \leq 1$
- 4: for  $\{a,b\} \in \hat{E}$  do QUERY(a,b)
- 5: **return** set of vertex pairs  $\{a,b\} \in \hat{E}$  such that  $\delta(a,b)=1$

Intuitively, the set  $\hat{E}$  constructed in SIMPLE consists of all vertex pairs  $\{a,b\}\subseteq V$  that might be an edge in E. In order to obtain the edge set E, it suffices to query uniquely the vertex pairs in  $\hat{E}$ . We remark that SIMPLE correctly reconstructs the graph for any parameter  $s\in[1,n]$ , and that choosing an appropriate s only affects the query complexity, see Lemma 9.

## 1.2.1 Random Regular Graphs

Our first main result shows that SIMPLE (Algorithm 1) uses  $\tilde{O}(n)$  distance queries on random  $\Delta$ -regular graphs for an appropriately chosen s (Theorem 1). The analysis exploits the locally tree-like property of random  $\Delta$ -regular graphs. The proof of Theorem 1 consists of several technical novelties, based on a new concept of interesting vertices (Definition 14). See Section 3.

▶ **Theorem 1.** Consider a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . Let  $s = \log^2 n$ . In the distance query model, SIMPLE (Algorithm 1) is a reconstruction algorithm using  $\tilde{O}(n)$  queries in expectation.

We extend Simple and its analysis to reconstruct random  $\Delta$ -regular graphs in the all-distances query model (Corollary 2), in the betweenness query model (Corollary 3), as well as in the parallel setting (Corollary 4). These extensions are based on the observation that the set  $\hat{E}$  constructed in Simple equals the edge set E with high probability (Lemma 17),<sup>2</sup> see Section 4.

- ▶ Corollary 2. Consider a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . In the all-distances query model, there is a reconstruction algorithm using  $O(\log^2 n)$  queries in expectation.
- ▶ Corollary 3. Consider a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . In the betweenness query model, there is a reconstruction algorithm using  $\tilde{O}(n)$  queries in expectation.
- ▶ Corollary 4. Consider a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . In the parallel setting of the distance query model, there is a reconstruction algorithm using 1 + o(1) rounds and  $\tilde{O}(n)$  queries in expectation.

We further extend the analysis of SIMPLE to study the metric dimension of random  $\Delta$ -regular graphs (Corollary 5), by showing (in Lemma 21) that a random subset of  $\log^2 n$  vertices is almost surely a resolving set (Definition 20) for those graphs, see Section 5.

▶ Corollary 5. Consider a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . With probability 1 - o(1), the metric dimension of the graph is at most  $\log^2 n$ .

With extra work, the parameter  $s = \log^2 n$  in Theorem 1 can be reduced to  $\log n \cdot (\log \log n)^{2+\epsilon}$ , for any  $\epsilon > 0$ , see the full version of the paper. As a consequence, the query complexity in the all-distances query model (Corollary 2) and the upper bound on the metric dimension (Corollary 5) can both be improved to  $O(\log n \cdot (\log \log n)^{2+\epsilon})$ .

### 1.2.2 Bounded-Degree Graphs

On general graphs of bounded degree, SIMPLE (Algorithm 1) has subquadratic query complexity and is highly parallelizable (Theorem 6), see Section 6.

▶ Theorem 6. Consider a general graph of bounded degree  $\Delta = O(\text{polylog } n)$ . Let  $s = n^{2/3}$ . In the distance query model, SIMPLE (Algorithm 1) is a reconstruction algorithm using  $\tilde{O}(n^{5/3})$  queries in expectation. In addition, SIMPLE can be parallelized using 2 rounds.

This property (i.e.,  $\hat{E} = E$  with high probability) does not hold on general graphs of bounded degree.

We note that the Multi-Phase algorithm<sup>3</sup> from [27] also reconstructs graphs of bounded degree in the distance query model. How does Simple compare to Multi-Phase? In terms of query complexity, on general graphs of bounded degree, Simple uses  $\tilde{O}(n^{5/3})$  queries, so is not as good as Multi-Phase using  $\tilde{O}(n^{3/2})$  queries; on random  $\Delta$ -regular graphs, Simple is more efficient than Multi-Phase:  $\tilde{O}(n)$  versus  $\tilde{O}(n^{3/2})$ . In terms of round complexity, Simple can be parallelized using 2 rounds on general graphs, and even 1 + o(1) rounds on random  $\Delta$ -regular graphs; while Multi-Phase requires up to  $3 \log n$  rounds due to a multi-phase selection process for centers.<sup>4</sup> In terms of structure, Simple is much simpler than Multi-Phase, which is based on multi-phase Voronoi-cell decomposition.

▶ Remark. In the worst case, the query complexity of SIMPLE is higher than linear. For example, when the graph is a complete binary tree, SIMPLE would require  $\Omega(n\sqrt{n})$  queries (the complexity of SIMPLE is minimized when s is roughly  $\sqrt{n}$ ). Thus the open question from [27] of whether general graphs of bounded degree can be reconstructed using  $\tilde{O}(n)$  distance queries remains open and answering it positively would require further algorithmic ideas.

# **2** Notations and Preliminary Analysis

Let G = (V, E) be a connected, undirected, and unweighted graph, where V is the set of vertices such that |V| = n and E is the set of edges. We say that  $\{a, b\} \subseteq V$  is a *vertex pair* if both a and b belong to V such that  $a \neq b$ . The *distance* between a vertex pair  $\{a, b\} \subseteq V$ , denoted by  $\delta(a, b)$ , is the number of edges on a shortest a-to-b path.

▶ **Definition 7** (Distinguishing). For a vertex pair  $\{a,b\} \subseteq V$ , we say that a vertex  $u \in V$  distinguishes a and b, or equivalently that u is a distinguisher of  $\{a,b\}$ , if  $|\delta(u,a)-\delta(u,b)| > 1$ . Let  $D(a,b) \subseteq V$  denote the set of vertices  $u \in V$  distinguishing a and b.

Let  $s \in [1, n]$  be an integer parameter. The set S constructed in SIMPLE consists of s vertices selected uniformly and independently at random from V.

The set  $\hat{E}$  constructed in SIMPLE consists of the vertex pairs  $\{a,b\} \subseteq V$  such that a and b are not distinguished by any vertex in S, i.e.,  $D(a,b) \cap S = \emptyset$ , or equivalently,  $|\delta(u,a) - \delta(u,b)| \le 1$  for all  $u \in S$ . For any edge  $(a,b) \in E$ , it is easy to see that  $|\delta(u,a) - \delta(u,b)| \le 1$  for all  $u \in V$ , which implies that  $\{a,b\} \in \hat{E}$ . Hence the following inclusion.

## ▶ Fact 8. $E \subseteq \hat{E}$ .

We show that Simple is correct and we give a preliminary analysis on its query complexity as well as on its round complexity, in Lemma 9.

▶ **Lemma 9.** The output of Simple (Algorithm 1) equals the edge set E. The number of distance queries in Simple is  $n \cdot s + |\hat{E}|$ . In addition, Simple can be parallelized using 2 rounds.

**Proof.** The output of SIMPLE consists of the vertex pairs  $\{a,b\} \in \hat{E}$  such that  $\{a,b\}$  is an edge in E. Since  $E \subseteq \hat{E}$  (Fact 8), the output of SIMPLE equals the edge set E.

Observe that the distance queries in SIMPLE are performed in two stages. The number of distance queries in the first stage is  $|V| \cdot |S| = n \cdot s$ . The number of distance queries in

<sup>&</sup>lt;sup>3</sup> Algorithm 3 in [27]

<sup>&</sup>lt;sup>4</sup> The number of rounds in Multi-Phase is implicit in the proof of Lemma 2.3 from [27].

the second stage is  $|\hat{E}|$ . Thus the query complexity of SIMPLE is  $n \cdot s + |\hat{E}|$ . The distance queries in each of the two stages can be performed in parallel, so SIMPLE can be parallelized using 2 rounds.

From Lemma 9, in order to further study the query complexity of SIMPLE, it suffices to analyze  $|\hat{E}|$ , which equals  $|E| + |\hat{E}| + |\hat{E}| = 1$  according to Fact 8. Since  $|E| \leq \Delta n$  in a graph of bounded degree  $\Delta$ , our focus in the subsequent analysis is  $|\hat{E}| + |\hat{E}| = 1$ .

▶ Lemma 10. Let  $s = \omega(\log n)$  be an integer parameter. Let B be the set of vertex pairs  $\{a,b\} \subseteq V$  such that  $\delta(a,b) \geq 2$  and  $|D(a,b)| \leq 3n \cdot (\log n)/s$ . We have  $\mathbb{E}_S[|\hat{E} \setminus E|] \leq |B| + o(1)$ .

**Proof.** Denote Z as the set  $\hat{E} \setminus E$ . Observe that  $|Z| \leq |B| + |Z \setminus B|$ . Since B is independent of the random set S, we have  $\mathbb{E}_S[|Z|] \leq |B| + \mathbb{E}_S[|Z \setminus B|]$ . It suffices to show that  $\mathbb{E}_S[|Z \setminus B|] = o(1)$ .

We claim that for any vertex pair  $\{a,b\} \subseteq V$  such that  $\{a,b\} \notin B$ , the probability that  $\{a,b\} \in Z$  is  $o(n^{-2})$ . To see this, fix a vertex pair  $\{a,b\} \notin B$ . By definition of B, either  $\delta(a,b)=1$ , or  $|D(a,b)|>3n\cdot(\log n)/s$ . In the first case,  $\{a,b\} \notin Z$  since Z does not contain any edge of E. In the second case, observe that the event  $\{a,b\} \in Z$  implies that  $\{a,b\} \in \hat{E}$ , hence  $D(a,b) \cap S = \emptyset$ . Therefore,

$$\mathbb{P}_{S}\left[\{a,b\} \in Z \mid \{a,b\} \notin B\right]$$

$$\leq \mathbb{P}_{S}\left[D(a,b) \cap S = \emptyset \mid \{a,b\} \notin B\right]$$

$$< \left(1 - \frac{3n \cdot (\log n)/s}{n}\right)^{s}$$

$$= o(n^{-2}),$$

where the second inequality follows since  $|D(a,b)| > 3n \cdot (\log n)/s$  and the set S consists of s vertices selected uniformly and independently at random, and the last step follows since  $s = \omega(\log n)$ .

There are at most n(n-1)/2 vertex pairs  $\{a,b\} \notin B$ . By the linearity of expectation, the expected number of vertex pairs  $\{a,b\} \notin B$  such that  $\{a,b\} \in Z$  is at most  $o(n^{-2}) \cdot n(n-1)/2 = o(1)$ , so  $\mathbb{E}_S[|Z \setminus B|] = o(1)$ . Therefore,  $\mathbb{E}_S[|Z|] \leq |B| + \mathbb{E}_S[|Z \setminus B|] = |B| + o(1)$ .

# **3** Reconstruction of Random Regular Graphs (Proof of Theorem 1)

In this section, we analyze SIMPLE (Algorithm 1) on random  $\Delta$ -regular graphs in the distance query model. We assume that  $\Delta \geq 2$  and that  $\Delta n$  is even since otherwise those graphs do not exist.

We bound the expectation of  $|\hat{E} \setminus E|$  on random  $\Delta$ -regular graphs, in Lemma 11.

▶ Lemma 11. Let G be a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . Let  $s = \log^2 n$ . Let  $S \subseteq V$  be a set of s vertices selected uniformly and independently at random from V. We have  $\mathbb{E}_{G,S}[|\hat{E} \setminus E|] = o(1)$ .

**Proof of Theorem 1 using Lemma 11.** By Lemma 9, SIMPLE is a reconstruction algorithm using  $n \cdot s + |\hat{E}| = n \cdot \log^2 n + |\hat{E}|$  distance queries. From Fact 8,  $|\hat{E}| = |E| + |\hat{E} \setminus E|$ . Since G is  $\Delta$ -regular,  $|E| = \Delta n/2$ . By Lemma 11,  $\mathbb{E}_{G,S}[|\hat{E} \setminus E|] = o(1)$ . Therefore, the expected number of distance queries in SIMPLE is  $n \cdot \log^2 n + \Delta n/2 + o(1)$ , which is  $\tilde{O}(n)$  since  $\Delta = O(1)$ .

It remains to prove Lemma 11 in the rest of this section.

Configuration Model [9, 44]. We consider a random  $\Delta$ -regular graph generated according to the configuration model. Given a partition of a set of  $\Delta n$  points into n cells  $v_1, v_2, \ldots, v_n$  of  $\Delta$  points, a configuration is a perfect matching of the points into  $\Delta n/2$  pairs. It corresponds to a (not necessarily connected) multigraph G' in which the cells are regarded as vertices and the pairs as edges: a pair of points  $\{x,y\}$  in the configuration corresponds to an edge  $(v_i,v_j)$  of G' where  $x \in v_i$  and  $y \in v_j$ . Since each  $\Delta$ -regular graph has exactly  $(\Delta!)^n$  corresponding configurations, a  $\Delta$ -regular graph can be generated uniformly at random by rejection sampling: choose a configuration uniformly at random,<sup>5</sup> and reject the result if the corresponding multigraph G' is not simple or not connected. The configuration model enables us to show properties of a random  $\Delta$ -regular graph by analyzing a multigraph G' corresponding to a random configuration.

In order to prove Lemma 11, we need the following Structural Lemma.

▶ Lemma 12 (Structural Lemma). Let  $\Delta = O(1)$  be such that  $\Delta \geq 3$ . Let G' be a multigraph corresponding to a uniformly random configuration. Let  $\{v,w\}$  be a vertex pair in G' such that  $\delta(v,w) \geq 2$ . With probability  $1 - o(n^{-2})$ , we have  $|D(v,w)| > 3n/\log n$ .

We defer the proof of the Structural Lemma for the moment and first show how it implies Lemma  $11.^6$ 

**Proof of Lemma 11 using the Structural Lemma (Lemma 12).** Let G be a random graph and let S be a random subset of vertices, both defined in the statement of Lemma 11. According to Lemma 10,  $\mathbb{E}_{G,S}[|\hat{E}\setminus E|] \leq \mathbb{E}_G[|B|] + o(1)$ . It suffices to prove that  $\mathbb{E}_G[|B|] = o(1)$ .

First, we consider the case when  $\Delta = O(1)$  is such that  $\Delta \geq 3$ . Our analysis is based on the configuration model. Let G' be a multigraph corresponding to a uniformly random configuration. Let  $\mathbb{E}_{G'}[|B|]$  denote the expected size of the set B defined on G'. Since each  $\Delta$ -regular graph corresponds to the same number of configurations and because the probability spaces of configurations and of  $\Delta$ -regular graphs, respectively, are uniform, we have  $\mathbb{E}_{G}[|B|] \leq \mathbb{E}_{G'}[|B|]/p$ , where p is the probability that G' is both simple and connected. According to [44], when  $\Delta \geq 3$ ,  $p \sim e^{(1-\Delta^2)/4}$ , which is constant since  $\Delta = O(1)$ . Thus  $\mathbb{E}_{G}[|B|] = O(\mathbb{E}_{G'}[|B|])$ .

In order to bound  $\mathbb{E}_{G'}[|B|]$ , consider any vertex pair  $\{v,w\}$  in G' such that  $\delta(v,w) \geq 2$ . From Lemma 12, the event  $|D(v,w)| \leq 3n/\log n$  occurs with probability  $o(n^{-2})$ . Equivalently, the event  $|D(v,w)| \leq 3n \cdot (\log n)/s$  occurs with probability  $o(n^{-2})$ , since  $s = \log^2 n$ . Thus the event  $\{v,w\} \in B$  occurs with probability  $o(n^{-2})$  according to the definition of B in Lemma 10. There are n(n-1)/2 vertex pairs  $\{v,w\}$  in G'. By linearity of expectation,  $\mathbb{E}_{G'}[|B|]$  is at most  $o(n^{-2}) \cdot n(n-1)/2 = o(1)$ . Hence  $\mathbb{E}_{G}[|B|] = O(\mathbb{E}_{G'}[|B|]) = o(1)$ .

In the special case when  $\Delta=2$ , a 2-regular graph G is a ring. Consider any vertex pair  $\{v,w\}$  in G such that  $\delta(v,w)\geq 2$ . It is easy to see that at least n-4 vertices u in the ring G are such that  $|\delta(u,v)-\delta(u,w)|>1$ , so  $|D(v,w)|\geq n-4$  by Definition 7. When n is large enough,  $n-4>3n/\log n$ , so  $|D(v,w)|>3n/\log n$ . Equivalently, we have  $|D(v,w)|>3n\cdot(\log n)/s$ , since  $s=\log^2 n$ . Thus  $\{v,w\}\notin B$  according to the definition of B in Lemma 10. Therefore,  $B=\emptyset$  and  $\mathbb{E}_G[|B|]=0$ .

We conclude that  $\mathbb{E}_G[|B|] = o(1)$  for any  $\Delta = O(1)$ . Thus  $\mathbb{E}_{G,S}[|\hat{E} \setminus E|] \leq \mathbb{E}_G[|B|] + o(1) = o(1)$ .

<sup>&</sup>lt;sup>5</sup> To generate a random configuration, the points in a pair can be chosen sequentially: the first point can be selected using any rule, as long as the second point in that pair is chosen uniformly from the remaining points.

<sup>&</sup>lt;sup>6</sup> Note that Lemma 11 is an intermediate step to prove Theorem 1 using Lemma 12. We state Lemma 11 separately since it will be reused in Section 4.

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The rest of the section is dedicated to prove the Structural Lemma (Lemma 12).

Let G' be a multigraph corresponding to a uniformly random configuration, and let V be the vertex set of G'. Let  $\{v,w\} \subseteq V$  be a vertex pair such that  $\delta(v,w) \geq 2$ . For a vertex  $x \in V$ , denote  $\ell(x) \in \mathbb{Z}$  as the distance in G' between x and the vertex pair  $\{v,w\}$ , i.e.,  $\ell(x) = \min(\delta(x,v),\delta(x,w))$ . For any integer  $k \geq 0$ , denote  $U_k \subseteq V$  as the set of vertices  $x \in V$  such that  $\ell(x) = k$ . Denote  $U_{\leq k} = \bigcup_{j < k} U_j$ .

To construct the multigraph G' from a random configuration, we borrow the approach from [10], which proceeds in phases to construct the edges in G', exploring vertices  $x \in V$  in non-decreasing order of  $\ell(x)$ . We start at the vertices of  $U_0 = \{v, w\}$ . Initially (i.e., in the 0-th phase), we construct all the edges incident to v or incident to w. Suppose at the beginning of the k-th phase (for  $k \in [1, n-1]$ ), we have constructed all the edges with at least one endpoint belonging to  $U_{\leq k-1}$ . During the k-th phase, we construct the edges incident to the vertices in  $U_k$  one by one, till the degree of all the vertices in  $U_k$  reaches  $\Delta$ . Let G' be the resulting multigraph in the end of the construction.

An edge (a,b) in G' is *indispensable* if it explores either the vertex a or the vertex b for the first time in the edge construction. In the first case, b is the *predecessor* of a; and in the second case, a is the *predecessor* of b. An edge is *dispensable* if it is not indispensable, in other words, if each of its endpoints either belongs to  $\{v, w\}$  or is an endpoint of an edge constructed previously.

▶ Fact 13. Neither v or w has a predecessor. For any vertex in V, its predecessor, if exists, is unique. If vertex a is the predecessor of vertex b, then  $\ell(b) = \ell(a) + 1$ .

We introduce the concept of *interesting vertices*, which is a key idea in the analysis.

▶ **Definition 14** (Interesting Vertices). A vertex  $x \in V$  is v-interesting if, for all vertices  $z \in V \setminus \{v\}$  with  $\delta(v, z) + \delta(z, x) = \delta(v, x)$ , the edges incident to z are indispensable. Similarly, a vertex  $x \in V$  is w-interesting if, for all vertices  $z \in V \setminus \{w\}$  with  $\delta(w, z) + \delta(z, x) = \delta(w, x)$ , the edges incident to z are indispensable.

For any finite integer  $k \geq 1$ , let  $I_k(v) \subseteq V$  denote the set of v-interesting vertices  $x \in V$  such that  $\delta(v, x) = k$ , and let  $I_k(w) \subseteq V$  denote the set of w-interesting vertices  $x \in V$  such that  $\delta(w, x) = k$ .

We show in Lemma 15 that interesting vertices distinguish the vertex pair  $\{v, w\}$ , which is a main technical novelty of the section.

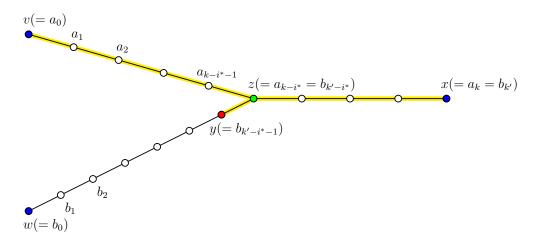
▶ **Lemma 15.** For any finite integer  $k \ge 1$ , we have  $I_k(v) \cup I_k(w) \subseteq D(v, w)$ .

**Proof.** Fix a finite integer  $k \geq 1$ . From the symmetry of v and w, it suffices to prove  $I_k(v) \subset D(v,w)$ .

Let x be any vertex in  $I_k(v)$ . By definition, x is v-interesting and  $\delta(v, x) = k$ . Let  $a_0 = v, a_1, \ldots, a_k = x$  be any shortest v-to-x path. For any vertex  $a_i$  with  $i \in [1, k]$ , the edges incident to  $a_i$  are indispensable according to Definition 14.

We claim that, for any  $i \in [1, k]$ ,  $a_{i-1}$  is the predecessor of  $a_i$ , and in addition,  $\ell(a_i) = i$ . The proof is by induction. First, consider the case when i = 1. The edge  $(a_0, a_1)$  is incident to the vertex  $a_1$ , so is indispensable. Thus either  $a_0$  is the predecessor of  $a_1$ , or  $a_1$  is the

When a multigraph corresponding to a random configuration is not connected, the resulting G' consists of the union of the components of v and of w, respectively, in that multigraph. It is not necessary to extend G' to the entire multigraph. Indeed, any vertex  $x \in V$  outside the union of those two components cannot distinguish v and w (i.e.,  $x \notin D(v, w)$ ), thus x is irrelevant to |D(v, w)| in the statement of Lemma 12.



**Figure 1**  $a_0, a_1, \ldots, a_k$  is a shortest v-to-x path, and  $b_0, b_1, \ldots, b_{k'}$  is a shortest w-to-x path. The vertex z represents the branching point of these two paths. Since the vertex x is v-interesting, the highlighted edges are indispensable.

predecessor of  $a_0$ . Since  $a_0 = v$  has no predecessor (Fact 13),  $a_1$  cannot be the predecessor of  $a_0$ , so  $a_0$  is the predecessor of  $a_1$ . Again using Fact 13, we have  $\ell(a_1) = \ell(a_0) + 1$ . Since  $\ell(a_0) = \ell(v) = 0$ , we have  $\ell(a_1) = 1$ . Next, consider the case when  $i \geq 2$ , and assume that the claim holds already for  $1, \ldots, i-1$ . The edge  $(a_{i-1}, a_i)$  is incident to the vertex  $a_i$ , so is indispensable. Thus either  $a_{i-1}$  is the predecessor of  $a_i$ , or  $a_i$  is the predecessor of  $a_{i-1}$ . By induction,  $a_{i-2}$  is the predecessor of  $a_{i-1}$ . Since the predecessor of  $a_{i-1}$  is unique (Fact 13),  $a_i$  cannot be the predecessor of  $a_{i-1}$ , so  $a_{i-1}$  is the predecessor of  $a_i$ . Again using Fact 13, we have  $\ell(a_i) = \ell(a_{i-1}) + 1$ . Since  $\ell(a_{i-1}) = i - 1$  by induction, we have  $\ell(a_i) = i$ .

In order to show that  $x \in D(v, w)$ , we prove in the following that  $\delta(w, x) \ge k + 2$ . Indeed, since  $\delta(v, x) = k$ , the event  $\delta(w, x) \ge k + 2$  implies that  $x \in D(v, w)$  by Definition 7.<sup>8</sup>

Let  $b_0 = w, b_1, \ldots, b_{k'} = x$  be any shortest w-to-x path, for some integer k'. See Figure 1. Let  $i^* \in [0, k]$  be the largest integer such that  $a_{k-j} = b_{k'-j}$  for all  $j \in [0, i^*]$ . Let z denote the vertex  $a_{k-i^*}$ , which equals  $b_{k'-i^*}$ . If  $i^* = k$ , the v-to-x path  $a_0, a_1, \ldots, a_k$  is a subpath of the w-to-x path  $b_0, b_1, \ldots, b_{k'}$ . Since  $\delta(w, v) \geq 2$ , we have  $\delta(w, x) = \delta(w, v) + \delta(v, x) \geq 2 + k$ , which implies that  $x \in D(v, w)$ . From now on, it suffices to consider the case when  $i^* < k$ .

Let y denote the vertex  $b_{k'-i^*-1}$ . Since y is on a shortest w-to-x path, we have

$$\delta(w, x) = \delta(w, y) + \delta(y, x) = \delta(w, y) + (i^* + 1) \ge \ell(y) + (i^* + 1), \tag{1}$$

where the inequality follows from the definition of  $\ell(y)$ . It remains to analyze the value of  $\ell(y)$ .

The edge (z, y) is incident to the vertex  $z = a_{k-i^*}$ , so is indispensable. Thus either y is the predecessor of z, or z is the predecessor of y. From the previous claim,  $a_{k-i^*-1}$  is the predecessor of z. Since the predecessor of z is unique (Fact 13) and  $y \neq a_{k-i^*-1}$  (by definition of  $i^*$ ), y cannot be the predecessor of z, so z is the predecessor of y. Again by

<sup>&</sup>lt;sup>8</sup> When  $\delta(w, x)$  is infinite (i.e., w and x are not connected in G'), it is trivial that  $x \in D(v, w)$ , since  $\delta(v, x)$  is finite. Therefore, it suffices to consider the case when  $\delta(w, x)$  is finite in the rest of the proof.

Fact 13,  $\ell(y) = \ell(z) + 1$ . Since  $\ell(z) = \ell(a_{k-i^*}) = k - i^*$  by the previous claim, we have  $\ell(y) = k - i^* + 1$ . We conclude from Equation (1) that

$$\delta(w, x) \ge (k - i^* + 1) + (i^* + 1) = k + 2,$$

which implies that  $x \in D(v, w)$ .

We proved that  $I_k(v) \subseteq D(v, w)$ . Similarly,  $I_k(w) \subseteq D(v, w)$ . Therefore,  $I_k(v) \cup I_k(w) \subseteq D(v, w)$ .

A lower bound on the number of interesting vertices is given in Lemma 16, which is another technical novelty. The proof is based on the *locally tree-like* property in random  $\Delta$ -regular graphs. It exploits the concept of interesting vertices in a non-trivial way and extends a 3-level argument from Bollobás [10] in the context of automorphisms of those graphs to an analysis of  $\log \log n$  levels. See the full version of the paper for details.

▶ Lemma 16. Let  $\Delta = O(1)$  be such that  $\Delta \geq 3$ . Let k be any positive integer such that  $k \leq \lceil \log_{\Delta-1}(3n/\log n) \rceil + 2$ . With probability  $1 - o(n^{-2})$ , we have  $|I_k(v) \cup I_k(w)| > (\Delta - 2 - o(1))(\Delta - 1)^{k-1}$ .

**Proof of the Structural Lemma (Lemma 12).** We set  $k = \lceil \log_{\Delta-1}(3n/\log n) \rceil + 2$ . By Lemma 15,  $|D(v, w)| \ge |I_k(v) \cup I_k(w)|$ . By Lemma 16, with probability  $1 - o(n^{-2})$ , we have

$$|I_k(v) \cup I_k(w)| > (\Delta - 2 - o(1))(\Delta - 1)^{k-1} \ge (\Delta - 2 - o(1))(\Delta - 1) \cdot (3n/\log n),$$

where the last inequality follows from the definition of k. Since  $\Delta \geq 3$ , we have  $(\Delta - 2 - o(1))(\Delta - 1) > 1$ . Thus with probability  $1 - o(n^{-2})$ , we have  $|I_k(v) \cup I_k(w)| > 3n/\log n$ , which implies that  $|D(v, w)| > 3n/\log n$ .

# 4 Other Reconstruction Models (Proofs of Corollaries 2–4)

In this section, we study the reconstruction of random  $\Delta$ -regular graphs in the all-distances query model, in the betweenness query model, as well as in the parallel setting.

By extending the analysis from Section 3, we observe that the set  $\hat{E}$  constructed in SIMPLE (Algorithm 1) equals the edge set E with high probability, in Lemma 17.

▶ **Lemma 17.** Let G be a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . Let  $s = \log^2 n$ . Let  $S \subseteq V$  be a set of s vertices selected uniformly and independently at random from V. With probability 1 - o(1),  $|\hat{E}| = \Delta n/2$ . In addition, the event  $|\hat{E}| = \Delta n/2$  implies  $\hat{E} = E$ .

**Proof.** From Lemma 11,  $\mathbb{E}_{G,S}[|\hat{E} \setminus E|] = o(1)$ . By Markov's inequality, the event that  $|\hat{E} \setminus E| \geq 1$  occurs with probability o(1). Thus with probability 1 - o(1), we have  $\hat{E} \subseteq E$ . On the other hand,  $E \subseteq \hat{E}$  by Fact 8. Therefore, the event that  $\hat{E} = E$  occurs with probability 1 - o(1), and this event occurs if and only if  $|\hat{E}| = |E|$ . The statement follows since  $|E| = \Delta n/2$  in a  $\Delta$ -regular graph.

### 4.1 A Modified Algorithm

Lemma 17 enables us to design another reconstruction algorithm in the distance query model, called Simple-Modified, which is a modified version of Simple, see Algorithm 2. Simple-Modified repeatedly computes a set  $\hat{E}$  as in Simple, until the size of  $\hat{E}$  equals  $\Delta n/2$ . The parameter s is fixed to  $\log^2 n$ .

#### Algorithm 2 SIMPLE-MODIFIED (V).

```
1: repeat
2: S \leftarrow \text{sample of } s = \log^2 n \text{ vertices selected uniformly and independently at random from } V
3: for u \in S and v \in V do QUERY(u, v)
4: \hat{E} \leftarrow \text{set of vertex pairs } \{a, b\} \subseteq V \text{ such that, for all } u \in S, |\delta(u, a) - \delta(u, b)| \le 1
5: until |\hat{E}| = \Delta n/2
6: return \hat{E}
```

▶ Lemma 18. Let G be a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . In the distance query model, SIMPLE-MODIFIED (Algorithm 2) is a reconstruction algorithm, i.e., its output equals the edge set E. The expected number of iterations of the **repeat** loop in SIMPLE-MODIFIED is 1 + o(1).

**Proof.** Upon termination of the **repeat** loop in SIMPLE-MODIFIED, we have  $|\hat{E}| = \Delta n/2$ , which implies  $\hat{E} = E$  by Lemma 17. Thus the output of SIMPLE-MODIFIED equals the edge set E.

In each iteration of the **repeat** loop, the event that  $|\hat{E}| = \Delta n/2$  occurs with probability 1 - o(1) by Lemma 17. Thus the expected number of iterations of the **repeat** loop is 1 + o(1).

# 4.2 All-Distances Query Model (Proof of Corollary 2)

By Lemma 18, SIMPLE-MODIFIED is a reconstruction algorithm in the distance query model. We extend SIMPLE-MODIFIED to the all-distances query model.

Observe that in SIMPLE-MODIFIED, the distance queries are performed between each sampled vertex  $u \in S$  and all vertices in the graph. This is equivalent to a single query at each sampled vertex  $u \in S$  in the all-distances query model. Hence each iteration of the **repeat** loop in SIMPLE-MODIFIED corresponds to  $|S| = \log^2 n$  all-distances queries. Again by Lemma 18, the expected number of iterations of the **repeat** loop in SIMPLE-MODIFIED is 1 + o(1). Therefore, in the all-distances query model, an algorithm equivalent to SIMPLE-MODIFIED reconstructs the graph using  $(1 + o(1)) \cdot \log^2 n = O(\log^2 n)$  all-distances queries in expectation.

# 4.3 Betweenness Query Model (Proof of Corollary 3)

In the betweenness query model, Abrahamsen et al. [1] showed that  $\tilde{O}(\Delta^2 \cdot n)$  betweenness queries suffice to compute the distances from a given vertex to all vertices in the graph (it is implicit in Lemma 16 from [1]), so an all-distances query can be simulated by  $\tilde{O}(\Delta^2 \cdot n)$  betweenness queries. As a consequence of Corollary 2, we achieve a reconstruction algorithm using  $\tilde{O}(\Delta^2 \cdot n \cdot \log^2 n) = \tilde{O}(n)$  betweenness queries in expectation, since  $\Delta = O(1)$ .

# 4.4 Parallel Setting (Proof of Corollary 4)

By Lemma 18, Simple-Modified is a reconstruction algorithm in the distance query model. We analyze Simple-Modified in the parallel setting.

Each iteration of the **repeat** loop consists of  $n \cdot \log^2 n$  distance queries, and the distance queries within the same iteration of the **repeat** loop can be performed in parallel. Again by Lemma 18, the expected number of iterations of the **repeat** loop in SIMPLE-MODIFIED is 1 + o(1). Thus the expected number of rounds in SIMPLE-MODIFIED is 1 + o(1), and the expected number of distance queries in SIMPLE-MODIFIED is  $(1 + o(1)) \cdot n \cdot \log^2 n = \tilde{O}(n)$ .

# 5 Metric Dimension (Proof of Corollary 5)

In this section, we study the metric dimension of random  $\Delta$ -regular graphs. To begin with, we show an elementary structural property of random  $\Delta$ -regular graphs, in Lemma 19, based on a classical result on those graphs.

▶ Lemma 19. Let G = (V, E) be a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . With probability 1 - o(1), for any edge (a, b) of the graph G, there exists a vertex  $c \in V \setminus \{a, b\}$  that is adjacent to b but is not adjacent to a.

**Proof.** First, consider the case when  $\Delta=2$ . A 2-regular graph is a ring. Let (a,b) be any edge of the graph. The vertex b has two neighbors, the vertex a and another vertex, let it be c. We have  $c \in V \setminus \{a,b\}$  and c is not adjacent to a (as soon as n>3). The statement of the lemma follows.

Next, consider the case when  $\Delta = O(1)$  is such that  $\Delta \geq 3$ . Let  $\mathcal{E}$  denote the event that, for any edge (a,b) of G, there do not exist two vertices  $c_1$  and  $c_2$  in G, such that all of the 4 edges  $(a,c_1),(a,c_2),(b,c_1),(b,c_2)$  belong to G. We show that  $\mathcal{E}$  occurs with probability 1-o(1). Indeed, if for some edge (a,b) of G, there exist two vertices  $c_1$  and  $c_2$  such that  $(a,c_1),(a,c_2),(b,c_1),(b,c_2)$  are edges of G, then the induced subgraph on  $\{a,b,c_1,c_2\}$  consists of at least 5 edges. A classical result on random  $\Delta$ -regular graphs shows that, for any constant integer k, the probability that there exists an induced subgraph of k vertices with at least k+1 edges is o(1), see, e.g., Lemma 11.12 in [18]. Therefore,  $\mathcal{E}$  occurs with probability 1-o(1).

We condition on the occurrence of  $\mathcal{E}$ . For any edge (a,b) of G, let N(a) be the set of  $\Delta-1$  neighbors of a that are different from b, and let N(b) be the set of  $\Delta-1$  neighbors of b that are different from a. Since  $\Delta \geq 3$ , we have  $|N(a)| = |N(b)| \geq 2$ . The event  $\mathcal{E}$  implies that  $N(a) \neq N(b)$ , so there exists a vertex  $c \in N(b) \setminus N(a)$ . By definition, c is adjacent to b but is not adjacent to a, and  $c \in V \setminus \{a,b\}$ . Since  $\mathcal{E}$  occurs with probability 1-o(1), we conclude that, with probability 1-o(1), for any edge (a,b) of the graph G, there exists a vertex  $c \in V \setminus \{a,b\}$  that is adjacent to b but is not adjacent to a.

▶ Definition 20 (e.g., [5, 12]). A subset of vertices  $S \subseteq V$  is a resolving set for a graph G = (V, E) if, for any pair of vertices  $\{a, b\} \subseteq V$ , there is a vertex  $u \in S$  such that  $\delta(u, a) \neq \delta(u, b)$ . The metric dimension of G is the smallest size of a resolving set for G.

Based on the analysis of SIMPLE from Lemma 17 and the structural property from Lemma 19, we show that, with high probability, a random subset of  $\log^2 n$  vertices is a resolving set for a random  $\Delta$ -regular graph, in Lemma 21.

▶ Lemma 21. Let G = (V, E) be a uniformly random  $\Delta$ -regular graph with  $\Delta = O(1)$ . Let  $S \subseteq V$  be a sample of  $s = \log^2 n$  vertices selected uniformly and independently at random from V. With probability 1 - o(1), the set S is a resolving set for the graph G.

**Proof.** Let  $\mathcal{E}_1$  denote the event that, for any edge (a,b) of the graph G, there exists a vertex  $c \in V \setminus \{a,b\}$  that is adjacent to b but is not adjacent to a. By Lemma 19, the event  $\mathcal{E}_1$  occurs with probability 1-o(1). Let  $\mathcal{E}_2$  denote the event  $\hat{E}=E$ . By Lemma 17, the event  $\mathcal{E}_2$  occurs with probability 1-o(1). Thus with probability 1-o(1), both events  $\mathcal{E}_1$  and  $\mathcal{E}_2$  occur simultaneously. We condition on the occurrences of both events  $\mathcal{E}_1$  and  $\mathcal{E}_2$  in the subsequent analysis.

First, consider any vertex pair  $\{a,b\} \subseteq V$  such that  $\delta(a,b) \geq 2$ . The event  $\mathcal{E}_2$  implies that  $\{a,b\} \notin \hat{E}$ . By definition, there exists some vertex  $u \in S$  such that  $|\delta(u,a) - \delta(u,b)| \geq 2$ , which implies that  $\delta(u,a) \neq \delta(u,b)$ .

Next, consider any vertex pair  $\{a,b\} \subseteq V$  such that  $\delta(a,b) = 1$ . The event  $\mathcal{E}_1$  implies that there exists a vertex  $c \in V \setminus \{a,b\}$  that is adjacent to b but is not adjacent to a. Since  $\delta(a,c) \geq 2$ , the event  $\mathcal{E}_2$  implies that  $\{a,c\} \notin \hat{E}$ . By definition, there exists some vertex  $u \in S$  such that  $|\delta(u,a) - \delta(u,c)| \geq 2$ . Using an elementary inequality of  $|x-y| + |y-z| \geq |x-z|$  for any three real numbers x, y, and z, we have

$$\begin{split} |\delta(u,a) - \delta(u,b)| &\geq |\delta(u,a) - \delta(u,c)| - |\delta(u,b) - \delta(u,c)| \\ &\geq |\delta(u,a) - \delta(u,c)| - \delta(b,c) & \text{(by the triangle inequality)} \\ &\geq 2 - \delta(b,c) & \text{(by the definition of } u) \\ &\geq 1 & \text{(since } (b,c) \text{ is an edge in } G). \end{split}$$

Thus  $\delta(u, a) \neq \delta(u, b)$ .

Therefore, conditioned on the occurrences of both events  $\mathcal{E}_1$  and  $\mathcal{E}_2$ , for any vertex pair  $\{a,b\}\subseteq V$ , there exists a vertex  $u\in S$  such that  $\delta(u,a)\neq\delta(u,b)$ .

We conclude that, with probability 1 - o(1), the set S is a resolving set for G.

From Lemma 21, with probability 1 - o(1), the metric dimension of a random  $\Delta$ -regular graph is at most  $\log^2 n$ . This completes the proof of Corollary 5.

# **6** Reconstruction of Bounded-Degree Graphs (Proof of Theorem 6)

In this section, we analyze SIMPLE (Algorithm 1) on general graphs of bounded degree in the distance query model. Recall that a set B of vertex pairs  $\{a,b\} \subseteq V$  is defined in Lemma 10. For every vertex  $a \in V$ , we define the set of vertices  $B(a) \subseteq V$  as

$$B(a) = \{ b \in V \mid \{a, b\} \in B \}.$$

Intuitively, B(a) consists of the vertices  $b \in V$  that has few distinguishers with a. We bound the size of the set B(a) for any vertex a, in Lemma 22.

▶ **Lemma 22.** Let G be a general graph of bounded degree  $\Delta$ . For any vertex  $a \in V$ ,  $|B(a)| \leq 9\Delta^3 \cdot n^2 \cdot (\log^2 n)/s^2$ .

We defer the proof of Lemma 22 for the moment and first show how it implies Theorem 6.

**Proof of Theorem 6 using Lemma 22.** By Lemma 9, SIMPLE is a reconstruction algorithm using  $n \cdot s + |\hat{E}|$  distance queries, and in addition, SIMPLE can be parallelized using 2 rounds. It remains to further analyze the query complexity.

From Fact 8,  $|\hat{E}| = |E| + |\hat{E} \setminus E|$ . Since the graph has bounded degree  $\Delta$ ,  $|E| \leq \Delta n$ . From Lemma 10,  $\mathbb{E}_S[|\hat{E} \setminus E|] \leq |B| + o(1)$ . Therefore, the expected number of distance queries in SIMPLE is at most  $n \cdot s + \Delta n + |B| + o(1)$ . It suffices to analyze |B|.

Observe that  $|B| \leq \sum_{a \in V} |B(a)|$  by definition of  $\{B(a)\}_{a \in V}$ . From Lemma 22,  $|B(a)| \leq 9\Delta^3 \cdot n^2 \cdot (\log^2 n)/s^2$ , for any vertex  $a \in V$ . Hence  $|B| \leq (9\Delta^3 \cdot n^2 \cdot (\log^2 n)/s^2) \cdot n$ . Thus the expected number of distance queries in SIMPLE is at most  $n \cdot s + \Delta n + (9\Delta^3 \cdot n^2 \cdot (\log^2 n)/s^2) \cdot n + o(1)$ , which is  $\tilde{O}(n^{5/3})$  since  $s = n^{2/3}$  and  $\Delta = O(\text{polylog } n)$ .

The rest of the section is dedicated to prove Lemma 22.

Let a be any vertex in V. Let T be an (arbitrary) shortest-path tree rooted at a and spanning all vertices in V. For any vertex  $b \in V$ , let the shortest a-to-b path denote the path between a and b in the tree T. To simplify the presentation, we assume that, for any

 $b \in B(a)$ ,  $\delta(a, b)$  is even, so that the *midpoint vertex* of the shortest a-to-b path is uniquely defined. We extend our analysis to the general setting in the end of the section.

For any vertex  $m \in V$ , define the set  $B(a, m) \subseteq B(a)$  as

 $B(a,m) = \{b \in B(a) \mid \text{the midpoint vertex of the shortest } a\text{-to-}b \text{ path is } m\}.$ 

Define the set  $M(a) \subseteq V$  as

$$M(a) = \{ m \in V \mid B(a, m) \neq \emptyset \}.$$

In other words, M(a) consists of the vertices  $m \in V$  that is the midpoint vertex of the shortest a-to-b path for some  $b \in B(a)$ . From the construction, we have

$$B(a) = \bigcup_{m \in M(a)} B(a, m). \tag{2}$$

In order to bound the size of B(a), first we bound the size of B(a, m) for any midpoint  $m \in M(a)$ , in Lemma 23, and then we bound the number of distinct midpoints, in Lemma 24.

▶ Lemma 23. For any 
$$m \in M(a)$$
,  $|B(a,m)| \leq 3\Delta \cdot n \cdot (\log n)/s$ .

**Proof.** For any  $b \in B(a, m)$ , the vertex m is the midpoint vertex of the shortest a-to-b path by definition. From the assumption,  $\delta(a, b)$  is even for any  $b \in B(a, m)$ , so there exists for some positive integer  $\ell$ , such that  $\delta(m, a) = \ell$  and  $\delta(m, b) = \ell$  for any  $b \in B(a, m)$ .

For every neighbor m' of m such that  $\delta(a,m') = \delta(a,m) + 1$ , define a set  $Y(m') \subseteq B(a,m)$  that consists of the vertices  $b \in B(a,m)$  such that m' is on the shortest a-to-b path. Let  $\hat{m}$  be a neighbor of m such that  $\delta(a,\hat{m}) = \delta(a,m) + 1$  and that  $|Y(\hat{m})|$  is maximized, see Figure 2. Since the graph has bounded degree  $\Delta$ , we have  $|B(a,m)| \leq \Delta \cdot |Y(\hat{m})|$ . It suffices to bound  $|Y(\hat{m})|$ .

The main observation is that any vertex of  $Y(\hat{m})$  distinguishes a and any other vertex of  $Y(\hat{m})$ . To see this, let  $b_0$  be any vertex in  $Y(\hat{m})$ . By definition,  $\delta(a, \hat{m}) = \delta(a, m) + 1 = \ell + 1$ . Since  $\hat{m}$  is on the shortest a-to- $b_0$  path, we have  $\delta(\hat{m}, b_0) = \delta(a, b_0) - \delta(a, \hat{m}) = \ell - 1$ , thus  $\delta(\hat{m}, b_0) = \delta(\hat{m}, a) - 2$ . For any vertex  $b_1 \in Y(\hat{m})$ , from the triangle inequalities on  $\delta$ , we have

$$\delta(b_1, b_0) \le \delta(b_1, \hat{m}) + \delta(\hat{m}, b_0) = \delta(b_1, \hat{m}) + \delta(\hat{m}, a) - 2 = \delta(b_1, a) - 2.$$

According to Definition 7, the vertex  $b_1$  distinguishes a and  $b_0$ , and equivalently,  $b_1 \in D(a, b_0)$ . Thus we have  $Y(\hat{m}) \subseteq D(a, b_0)$ , hence  $|Y(\hat{m})| \leq |D(a, b_0)| \leq 3n \cdot (\log n)/s$  using the fact that  $b_0 \in Y(\hat{m}) \subseteq B(a)$  and the definition of B in Lemma 10.

We conclude that 
$$|B(a,m)| \leq \Delta \cdot |Y(\hat{m})| \leq 3\Delta \cdot n \cdot (\log n)/s$$
.

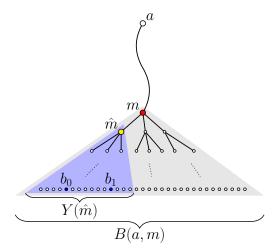
## ▶ Lemma 24. $|M(a)| \leq 3\Delta \cdot n \cdot (\log n)/s$ .

**Proof.** For each vertex  $m \in M(a)$ , denote  $x_m$  as the second-to-last vertex on the shortest a-to-m path. Denote  $X(a) \subseteq V$  as the set of vertices  $x_m$  for all  $m \in M(a)$ . See Figure 3. Since G has bounded degree  $\Delta$ , we have  $|M(a)| \leq \Delta \cdot |X(a)|$ . It suffices to bound |X(a)|.

Let  $b^*$  be a vertex in B(a) such that  $\delta(a, b^*)$  is maximized. From the assumption,  $\delta(a, b^*)$  is even, so we denote  $\delta(a, b^*) = 2\ell$  for some positive integer  $\ell$ .

The main observation is that any vertex of X(a) distinguishes a and  $b^*$ . To see this, let x be any vertex in X(a). Let m be any vertex in M(a) such that x is the second-to-last vertex on the shortest a-to-m path. We have  $\delta(a, m) \leq \ell$  and  $\delta(a, x) = \delta(a, m) - 1 \leq \ell - 1$ . By the

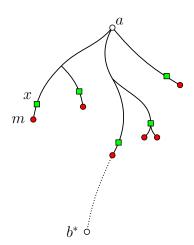
<sup>&</sup>lt;sup>9</sup> Such a vertex m exists according to the construction of X(a).



**Figure 2** The vertex m is the midpoint of the shortest path between a and any vertex in B(a, m). The vertex  $\hat{m}$  is a well-chosen neighbor of m. Consider any vertex  $b_0 \in Y(\hat{m})$ . We can show that any vertex  $b_1 \in Y(\hat{m})$  distinguishes a and  $b_0$ .

triangle inequality on the distances,  $\delta(b^*,x) \geq \delta(a,b^*) - \delta(a,x) \geq 2\ell - (\ell-1) = \ell+1$ . Thus  $\delta(b^*,x) - \delta(a,x) \geq 2$ . According to Definition 7, the vertex x distinguishes a and  $b^*$ , and equivalently,  $x \in D(a,b^*)$ . Thus  $X(a) \subseteq D(a,b^*)$ , hence  $|X(a)| \leq |D(a,b^*)| \leq 3n \cdot (\log n)/s$  using the fact that  $b^* \in B(a)$  and the definition of B in Lemma 10.

We conclude that  $|M(a)| \leq \Delta \cdot |X(a)| \leq 3\Delta \cdot n \cdot (\log n)/s$ .



**Figure 3** Solid circular nodes represent the vertices  $m \in M(a)$ . Solid curves represent the shortest a-to-m paths. Solid square nodes represent the vertices in X(a). Denote  $b^*$  as a vertex in B(a) that is farthest from a. We can show that any vertex  $x \in X(a)$  distinguishes a and  $b^*$ .

From Equation (2),  $|B(a)| \leq \sum_{m \in M(a)} |B(a,m)|$ . From Lemma 23,  $|B(a,m)| \leq 3\Delta \cdot n \cdot (\log n)/s$  for every  $m \in M(a)$ . From Lemma 24,  $|M(a)| \leq 3\Delta \cdot n \cdot (\log n)/s$ . Therefore,  $|B(a)| \leq 9\Delta^2 \cdot n^2 \cdot (\log^2 n)/s^2$ .

Finally, consider the general setting in which  $\delta(a,b)$  is not necessarily even for any  $b \in B(a)$ . For a vertex m on the shortest a-to-b path, we say that m is the midpoint vertex of that path if  $\delta(a,m) = \lfloor \delta(a,b)/2 \rfloor$ . The definitions of B(a,m) and M(a) remain the same.

Lemma 24 holds in the same way. In Lemma 23, the upper bound of |B(a,m)| is replaced by  $3\Delta^2 \cdot n \cdot (\log n)/s$ . Indeed, to extend the proof of Lemma 23, instead of considering vertex m' (resp., vertex  $\hat{m}$ ) that is a neighbor of m, we consider m' (resp.,  $\hat{m}$ ) that is at distance 2 from m. We have  $|B(a,m)| \leq \Delta^2 \cdot |Y(\hat{m})|$ . The bound  $|Y(\hat{m})| \leq 3n \cdot (\log n)/s$  remains the same, so we have  $|B(a,m)| \leq 3\Delta^2 \cdot n \cdot (\log n)/s$ . Hence  $|B(a)| \leq 9\Delta^3 \cdot n^2 \cdot (\log^2 n)/s^2$ .

We complete the proof of Lemma 22. Therefore, we obtain Theorem 6.

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