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Solution of P versus NP Problem

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Abstract: The P versus NP problem is one of the most important and unsolved problems in computer science. This consists in knowing the answer of the following question: Is P equal to NP? This incognita was first mentioned in a letter written by Kurt Gödel to John von Neumann in 1956. However, the precise statement of the P versus NP problem was introduced in 1971 by Stephen Cook in a seminal paper. We consider a new complexity class, called equivalent-P, which has a close relation with this problem. The class equivalent-P has those languages that contain ordered pairs of instances, where each one belongs to a specific problem in P, such that the two instances share a same solution, that is, the same certificate. We demonstrate that equivalent-P = NP and equivalent-P = P. In this way, we find the solution of P versus NP problem, that is, P = NP.

1 Introduction

The *P* versus *NP* problem is a major unsolved problem in computer science. This problem was introduced in 1971 by Stephen Cook [2]. It is considered by many to be the most important open problem in the field [4]. It is one of the seven Millennium Prize Problems selected by the Clay Mathematics Institute to carry a US\$1,000,000 prize for the first correct solution.

The argument made by Alan Turing in the twentieth century states that for any algorithm we can create an equivalent Turing machine [10]. There are some definitions related with this model such as the deterministic or nondeterministic Turing machine. A deterministic Turing machine has only one next action for each step defined in its program or transition function [9]. A nondeterministic Turing

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machine can contain more than one action defined for each step of the program, where this program is not a function, but a relation [9].

Another huge advance in the last century was the definition of a complexity class. A language L over an alphabet is any set of strings made up of symbols from that alphabet [3]. A complexity class is a set of problems, which are represented as a language, grouped by measures such as the running time, memory, etc [3].

In computational complexity theory, the class *P* consists in all those decision problems (defined as languages) that can be decided on a deterministic Turing machine in an amount of time that is polynomial in the size of the input; the class *NP* consists in all those decision problems whose positive solutions can be verified in polynomial-time given the right information, or equivalently, that can be decided on a nondeterministic Turing machine in polynomial-time [7].

The biggest open question in theoretical computer science concerns the relationship between those two classes:

Is *P* equal to *NP*?

In a 2002 poll of 100 researchers, 61 believed the answer to be no, 9 believed the answer is yes, and 22 were unsure; 8 believed the question may be independent of the currently accepted axioms and so impossible to prove or disprove [6].

There is an important complexity class called *NP-complete* [7]. The *NP-complete* problems are a set of problems to which any other *NP* problem can be reduced in polynomial-time, but whose solution may still be verified in polynomial-time [7]. In addition, there is another important complexity class called *P-complete* [9]. The *P-complete* problems are a set of problems to which any other *P* problem can be reduced in logarithmic-space, but they still remain in *P* [9]. We shall define a new complexity class that we called *equivalent-P* (see the Abstract) and denoted as $^{\sim}P$. We shall show that there is an *NP-complete* problem in $^{\sim}P$ and a *P-complete* problem in $^{\sim}P$. Moreover, we shall prove the complexity class $^{\sim}P$ is closed under reductions. Since *P* and *NP* are also closed under reductions, then we can conclude that P = NP.

2 Theoretical framework

2.1 NP-complete class

We say that a language L_1 is polynomial-time reducible to a language L_2 , written $L_1 \leq_p L_2$, if there exists a polynomial-time computable function $f: \{0,1\}^* \to \{0,1\}^*$ such that for all $x \in \{0,1\}^*$,

$$x \in L_1$$
 if and only if $f(x) \in L_2$. (2.1)

There is an important complexity class called *NP-complete* [7]. A language $L \subseteq \{0,1\}^*$ is *NP-complete* if

- $L \in NP$, and
- $L' \leq_p L$ for every $L' \in NP$.

Furthermore, if *L* is a language such that $L' \leq_p L$ for some $L' \in NP$ -complete, then *L* is NP-hard [3]. Moreover, if $L \in NP$, then $L \in NP$ -complete [3].

One of the first discovered *NP-complete* problems was *SAT* [5]. An instance of *SAT* is a Boolean formula ϕ which is composed of

- Boolean variables: x_1, x_2, \dots ;
- Boolean connectives: Any Boolean function with one or two inputs and one output, such as $\land (AND), \lor (OR), \neg (NOT), \rightarrow (implication), \leftrightarrow (if and only if);$ and
- parentheses.

A truth assignment for a Boolean formula ϕ is a set of values for the variables of ϕ and a satisfying truth assignment is a truth assignment that causes it to evaluate to true. A formula with a satisfying truth assignment is a satisfiable formula. The *SAT* asks whether a given Boolean formula is satisfiable.

One convenient language is 3CNF satisfiability, or 3SAT [3]. We define 3CNF satisfiability using the following terms. A literal in a Boolean formula is an occurrence of a variable or its negation. A Boolean formula is in conjunctive normal form, or CNF, if it is expressed as an AND of clauses, each of which is the OR of one or more literals. A Boolean formula is in 3-conjunctive normal form, or 3CNF, if each clause has exactly three distinct literals.

For example, the Boolean formula

$$(x_1 \vee \neg x_1 \vee \neg x_2) \wedge (x_3 \vee x_2 \vee x_4) \wedge (\neg x_1 \vee \neg x_3 \vee \neg x_4) \tag{2.2}$$

is in 3CNF. The first of its three clauses is $(x_1 \lor \neg x_1 \lor \neg x_2)$, which contains the three literals x_1 , $\neg x_1$, and $\neg x_2$. In 3SAT, we are asked whether a given Boolean formula ϕ in 3CNF is satisfiable.

Many problems can be proved that belong to *NP-complete* by a polynomial-time reduction from 3SAT [5]. For example, the problem *ONE-IN-THREE 3SAT* defined as follows: Given a Boolean formula ϕ in 3CNF, is there a truth assignment such that each clause in ϕ has exactly one true literal?

2.2 P-complete class

We say that a language L_1 is logarithmic-space reducible to a language L_2 , if there exists a logarithmic-space computable function $f: \{0,1\}^* \to \{0,1\}^*$ such that for all $x \in \{0,1\}^*$,

$$x \in L_1$$
 if and only if $f(x) \in L_2$. (2.3)

The logarithmic space reduction is frequently used for *P* and below [9].

There is an important complexity class called *P-complete* [9]. A language $L \subseteq \{0,1\}^*$ is *P-complete* if

- $L \in P$, and
- L' is logarithmic-space reducible to L for every $L' \in P$.

One of the *P-complete* problems is *HORNSAT* [9]. We say that a clause is a Horn clause if it has at most one positive literal [9]. That is, all its literals, except possibly for one, are negations of variables. An instance of *HORNSAT* is a Boolean formula ϕ in *CNF* which is composed only of Horn clauses [9].

For example, the Boolean formula

$$(\neg x_2 \lor x_3) \land (\neg x_1 \lor \neg x_2 \lor \neg x_3 \lor \neg x_4) \land (x_1)$$
 (2.4)

is a conjunction of Horn clauses. The *HORNSAT* asks whether an instance of this problem is satisfiable [9].

2.3 Problems in P

Another special case is the class of problems where each clause contains XOR (i.e. exclusive or) rather than (plain) OR operators. This is in P, since an XOR-SAT formula can also be viewed as a system of linear equations mod 2, and can be solved in cubic time by Gaussian elimination [8]. We denote the XOR function as \oplus . The XOR 3SAT problem will be equivalent to XOR-SAT, but the clauses in the formula have exactly three distinct literals. Since $a \oplus b \oplus c$ evaluates to true if and only if exactly 1 or 3 members of $\{a,b,c\}$ are true, each solution of the ONE-IN-THREE 3SAT problem for a given 3CNF formula is also a solution of the XOR 3SAT problem and in turn each solution of XOR 3SAT is a solution of 3SAT.

In addition, a Boolean formula is in 2-conjunctive normal form, or 2CNF, if it is in CNF and each clause has exactly two distinct literals. There is a problem called 2SAT, where we asked whether a given Boolean formula ϕ in 2CNF is satisfiable. This problem is in P [1].

3 Definition of ~ P

Let L be a language and M a Turing machine. We say that M is a verifier for L if L can be written as

$$L = \{x : (x, y) \in R \text{ for some } y\}$$

$$(3.1)$$

where R is a polynomially balanced relation decided by M [9]. According to Cook's Theorem, a language L is in NP if and only if it has a polynomial-time verifier [9].

Definition 3.1. Given two languages, L_1 and L_2 , and two Turing machines, M_1 and M_2 , such that $L_1 \in P$ and $L_2 \in P$ where M_1 and M_2 are the verifiers of L_1 and L_2 respectively, we say that a language L belongs to ${}^{\sim}P$ if,

$$L = \{(x, y) : \exists z \text{ such that } M_1(x, z) = \text{"yes" and } M_2(y, z) = \text{"yes" where } x \in L_1 \text{ and } y \in L_2\}.$$
 (3.2)

We will call the complexity class ${}^{\sim}P$ as "equivalent-P".

4 Reduction in ~ P

There is a different kind of reduction for ${}^{\sim}P$: The *e-reduction*.

Definition 4.1. Given two languages L_1 and L_2 , such that the instances of L_1 and L_2 are ordered pairs of strings, we say that a language L_1 is *e-reducible* to a language L_2 , written $L_1 \leq L_2$, if there exist two logarithmic-space computable functions $f: \{0,1\}^* \to \{0,1\}^*$ and $g: \{0,1\}^* \to \{0,1\}^*$ such that for all $x \in \{0,1\}^*$ and $y \in \{0,1\}^*$,

$$(x, y) \in L_1 \text{ if and only if } (f(x), g(y)) \in L_2.$$
 (4.1)

We say that a complexity class C is closed under reductions if, whenever L_1 is reducible to L_2 and $L_2 \in C$, then also $L_1 \in C$ [9].

Theorem 4.2. ${}^{\sim}P$ is closed under reductions.

Proof. Let L and L' be two arbitrary languages, where their instances are ordered pairs of strings, $L \le \sim L'$ and $L' \in {}^{\sim}P$. We shall show that L is in ${}^{\sim}P$ too. By definition of ${}^{\sim}P$, there are two languages L'_1 and L'_2 , such that for each $(v,w) \in L'$ we have that $v \in L'_1$ and $w \in L'_2$ where $L'_1 \in P$ and $L'_2 \in P$. Moreover, there are two Turing machines M'_1 and M'_2 which are the verifiers of L'_1 and L'_2 respectively, and for each $(v,w) \in L'$ exists a polynomially bounded certificate z such that $M'_1(v,z) = \text{``yes''}$ and $M'_2(w,z) = \text{``yes''}$. Besides, by definition of e-reduction, there exist two logarithmic-space computable functions $f: \{0,1\}^* \to \{0,1\}^*$ and $g: \{0,1\}^* \to \{0,1\}^*$ such that for all $x \in \{0,1\}^*$ and $y \in \{0,1\}^*$,

$$(x,y) \in L \text{ if and only if } (f(x),g(y)) \in L'.$$
 (4.2)

From this preliminary information, we can conclude there exist two languages L_1 and L_2 , such that for each $(x,y) \in L$ we have that $x \in L_1$ and $y \in L_2$ where $L_1 \in P$ and $L_2 \in P$. Indeed, we could define L_1 and L_2 as the instances $f^{-1}(v)$ and $g^{-1}(w)$ respectively, such that $f^{-1}(v) \in L_1$ and $g^{-1}(w) \in L_2$ if and only if $v \in L'_1$ and $w \in L'_2$. Certainly, for all $x \in \{0,1\}^*$ and $y \in \{0,1\}^*$, we can decide $x \in L_1$ or $y \in L_2$ in polynomial-time just verifying that $f(x) \in L'_1$ or $g(y) \in L'_2$ respectively, because $L'_1 \in P$, $L'_2 \in P$ and $SPACE(log\ n) \in P$ [9]. Furthermore, there exist two Turing machines M_1 and M_2 which are the verifiers of L_1 and L_2 respectively, and for each $(x,y) \in L$ exists a polynomially bounded certificate z such that $M_1(x,z) =$ "yes" and $M_2(y,z) =$ "yes" and $M_2(y,z) =$ "yes" for some polynomially bounded string z just verifying whether $M_1(x,z) =$ "yes" and $M_2(y,z) =$ "yes". That is, we may have that $M_1(x,z) = M'_1(f(x),z)$ and $M_2(y,z) = M'_2(g(y),z)$, because we can evaluate f(x) and g(y) in polynomial-time since $SPACE(log\ n) \in P$ [9]. In this way, we have proved that $L \in {}^{\sim}P$.

$5 \sim P = NP$

We define ~ONE-IN-THREE 3SAT as follows,

$$^{\sim}ONE\text{-}IN\text{-}THREE 3SAT = \{(\phi, \phi) : \phi \in ONE\text{-}IN\text{-}THREE 3SAT\}.$$
 (5.1)

It is trivial to see the ~ONE-IN-THREE 3SAT problem remains in NP-complete (see Section 2).

Definition 5.1. 3XOR-2SAT is a problem in ${}^{\sim}P$, such that if $(\psi, \varphi) \in 3XOR$ -2SAT, then $\psi \in XOR$ 3SAT and $\varphi \in 2SAT$. That is, the instances of XOR 3SAT and 2SAT (see Section 2) that can have the same satisfying truth assignment (with the same variables).

Theorem 5.2. $^{\sim}ONE\text{-}IN\text{-}THREE 3SAT \leq_{\sim} 3XOR\text{-}2SAT.$

Proof. Given an arbitrary Boolean formula ϕ in 3CNF of m clauses, we will iterate for each clause $c_i = (x \lor y \lor z)$ in ϕ , where x, y and z are literals, and create the following formulas,

$$Q_i = (x \oplus y \oplus z) \tag{5.2}$$

$$P_i = (\neg x \lor \neg y) \land (\neg y \lor \neg z) \land (\neg x \lor \neg z). \tag{5.3}$$

Since Q_i evaluates to true if and only if exactly 1 or 3 members of $\{x,y,z\}$ are true and P_i evaluates to true if and only if exactly 1 or 0 members of $\{x,y,z\}$ are true, we obtain the clause c_i has exactly one true literal if and only if both formulas Q_i and P_i are satisfiable with the same truth assignment. Hence, we can create the ψ and φ formulas as the conjunction of the Q_i and P_i formulas for every clause c_i in φ , that is, $\psi = Q_1 \wedge ... \wedge Q_m$ and $\varphi = P_1 \wedge ... \wedge P_m$. Finally, we obtain that,

$$(\phi, \phi) \in {}^{\sim}ONE\text{-}IN\text{-}THREE 3SAT if and only if } (\psi, \phi) \in 3XOR\text{-}2SAT.$$
 (5.4)

In addition, there exist two logarithmic-space computable functions $f: \{0,1\}^* \to \{0,1\}^*$ and $g: \{0,1\}^* \to \{0,1\}^*$ such that $f(<\phi>) = <\psi>$ and $g(<\phi>) = <\varphi>$. Indeed, we only need a logarithmic-space to analyze at once each clause c_i in the input ϕ and generate Q_i or P_i to the output, since the complexity class $SPACE(log\ n)$ does not take the length of the input and the output into consideration [9].

Theorem 5.3. ${}^{\sim}P = NP$.

Proof. If there is an *NP-complete* problem reducible to a problem in ${}^{\sim}P$, then this *NP-complete* problem will be in ${}^{\sim}P$, and thus, ${}^{\sim}P = NP$, because ${}^{\sim}P$ is closed under reductions (see Theorem 4.2) and *NP* too [9]. Therefore, this is a direct consequence of Theorem 5.2.

6 P = NP

We define $\sim HORNSAT$ as follows,

$$^{\sim}HORNSAT = \{(\phi, \phi) : \phi \in HORNSAT\}. \tag{6.1}$$

It is trivial to see the $^{\sim}HORNSAT$ problem remains in *P-complete* (see Section 2).

Theorem 6.1. $^{\sim}HORNSAT \in {^{\sim}P}$.

Proof. The $^{\sim}HORNSAT$ problem complies with all the properties of a language in $^{\sim}P$. That is, for each $(\phi,\phi) \in ^{\sim}HORNSAT$, the Boolean formula ϕ belongs to a language in P, that is, the same HORNSAT. In addition, the verifier M of HORNSAT complies that always exists a polynomially bounded certificate z when ϕ is satisfiable, that is the satisfying truth assignment of ϕ , such that $M(\phi,z) = \text{``yes''}$. Certainly, we can prove this result, because any ordered pair of Boolean formulas in $^{\sim}HORNSAT$ can share the same certificate due to they are equals.

Theorem 6.2. ${}^{\sim}P = P$.

Proof. If a *P-complete* is in ${}^{\sim}P$, then ${}^{\sim}P = P$, because ${}^{\sim}P$ is closed under reductions (see Theorem 4.2) and *P* too [9]. Therefore, this is a direct consequence of Theorem 6.1.

Theorem 6.3. P = NP.

Proof. Since ${}^{\sim}P = NP$ and ${}^{\sim}P = P$ as result of Theorems 5.3 and 6.2, then we can conclude that P = NP.

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