An analytical model for jitter in IP networks

Hamza Dahmouni · André Girard · Brunilde Sansò

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Abstract Traditionally, IP network planning and design is mostly based on the average delay or loss constraints which can often be easily calculated. Jitter, on the other hand, is much more difficult to evaluate, but it is particularly important to manage the QoS of realtime and interactive services such as VoIP and streaming video. In this paper, we present simple formulas for the jitter of Poisson traffic in a single queue that can be quickly calculated. It takes into account the packets delay correlation and also the correlation of tandem queues that have a significant impact on the end-to-end jitter. We then extend them to the end-to-end jitter of a tagged stream based on a tandem queueing network. The results given by the model are then compared with event-driven simulations. We find that they are very accurate for Poisson traffic over a wide range of traffic loads and more importantly that they yield conservative

values for the jitter so that they can be used in network design procedures. We also find some very counter-intuitive results. We show that jitter actually decreases with increasing load and the total jitter on a path depends on the position of congested links on that path. We finally point out some consequences of these results for network design procedures.

Keywords Jitter model • Traffic engineering • IP network planning

1 Introduction

1.1 Motivation

The main challenge in the engineering of current IP networks is the integration and support of a wide variety of applications and services combining voice, data, streaming, and VoD. The different media types exchanged by these applications have different requirements in terms of bandwidth, latency, jitter, and reliability. The popularity of these applications has highlighted the limitations of the actual Internet infrastructure.

For real-time and interactive services, delay jitter remains one of the most important parameters of quality of service. For most of applications, the variation in the arrival time of packets at the terminal must be compensated by using a playback buffer in order to provide a regular packet stream to the application. Estimating and controlling the delay variation is important for the operator to avoid both a buffer overflow, which causes packet losses, and buffer underflow when the

H. Dahmouni (⋈)

Institut National des Postes et Télécommunications,

2, Av Allal El Fassi, Madinat Al Irfane,

Rabat, Morocco

e-mail: dahmouni@inpt.ac.ma, hamza.dahmouni@gerad.ca

A. Girard

INRS-EMT and GERAD, 800, de la Gauchetiere O, Suite 6900, Montreal, QC, Canada H5A 1K6 e-mail: andre.girard@gerad.ca

B. Sansò

Electrical Engineering Department, École Polytechnique de Montréal and GERAD, CP 6079 succ Centre-Ville, Montreal, QC, Canada H3C 3A9 e-mail: brunilde.sanso@polymtl.ca



application does not receive packets for some time. In both cases, the users will experience a degraded quality of service. These effects can be avoided to a large degree by controlling packet jitter.

Nevertheless, the effect of jitter on network structure and operation is not well understood. Getting some qualitative understanding of this QoS requirement will be only possible when we have a fast evaluation method for jitter that can be used in network design algorithms. We present here a first solution where we derive a fast jitter model for Poisson traffic that is both accurate and fast enough to be used for network design. We can use it to gain insight into the impact of the jitter on communication data networks.

First, we provide an accurate analytical expression for the end-to-end delay jitter in a single node case. From this, we show that the jitter incurred by an individual network node is bounded by the packet average transit delay and the packet average service time. We then extend this model to calculate an approximate expression for the end-to-end delay jitter along a path in a tandem queueing network. We find that the jitter is significantly important at the first multiplexing node and decreases as the correlation between successive packets increases. We also show that its accuracy is excellent when compared with simulation results of Poisson traffic. We also find the unexpected result that jitter improves as the load increases and that the jitter on a path depends on where the more congested links occur on that path. This is in strong contrast with other QoS measures such as delay or loss.

The technique is fast enough to be used in a network design tool, which could help operators to improve the performance of their networks and provide network optimization that can take into account both jitter and delay QoS constraints.

1.2 Previous work

There has been much work during the 1990s on the estimation of cell delay jitter for ATM networks. This is based on discrete time processes and FCFS multiplexing operation. Most of these results assume that the tagged stream is originally periodic or is a general renewal process. In [15], the jitter steady state is derived for a periodic traffic stream by assuming a Markovian structure for the cell delay process. The authors of [10] and [11] used generating functions to estimate the end-to-end jitter of a general renewal stream in heavy and light traffic.

The jitter pdf for a renewal stream multiplexed with uncorrelated background traffic is derived in [8, 9]. An analytical approximation for the delay jitter first-

order and second-order statistics incurred by a periodic traffic is proposed in [7]. In [13], the authors provided a complete characterization of the jitter process when the tagged stream and the background traffic are constant bit rate. A simple analytical approximation for the delay jitter incurred by a periodic stream multiplexed with a background traffic and governed by a general renewal process is described in [2].

Recently, there have been some proposals for delay jitter models in DiffServ networks. An extension of [13] was proposed in [3] to evaluate the per-class jitter. The authors [1] provided some analysis of the delay jitter by means of event-driven simulations (ns-2) where EF flows are represented by renewal periodic ON–OFF flows.

All these methods concentrate on the analysis of the jitter incurred by a tagged periodic cell stream going through nodes of an ATM network so that the service time is constant which is not necessarily the case with IP traffic. Furthermore, the computation time is large which makes them unsuitable as a component of a network dimensioning tool.

1.3 Our contribution

The purpose of this work is to produce a simple formula for the end-to-end delay jitter. The main application is as a component of a network design algorithm, for example, for routing or dimensioning. Typically, these are large nonlinear programs where the jitter appears as a set of QoS constraints. In this context, the evaluation of the jitter has to be done a very large number of times both to test feasibility of a solution and for the calculation of the gradients. This is why the first requirement of such a model is simplicity and fast evaluation. Obviously, accuracy is also needed but it is not very useful to have a very accurate model if it requires such a large computation time that it will make it impossible to solve the design problem in a reasonable time.

For these reasons, the results that we obtain are for Poisson arrivals and exponential holding times. There is a large body of work showing that some real Internet traffic is definitely *not* Poisson and can exhibit longrange dependence. In these cases, the values obtained from a Poisson-based model might not be very accurate. Nevertheless, a less accurate, but fast, jitter model can still be very useful for the following reasons.

First, we have not found any model with more realistic processes that can be calculated within the times required for network design. Right now, the only thing that seems to be fast enough for network design is a Poisson model.



Second, even though the actual values for the jitter may not be accurate, they could provide some insight when *comparing* other network parameters with each other. Suppose for instance that we want to choose between two kinds of transmission systems with different costs. We could run the design algorithm with the Poisson model with the two cost values. Suppose that the Poisson model underestimates the jitter. This will produce an under-dimensioned network in the two cases, but the cost *difference* between the two solutions might very well be close to what we would get with a more realistic jitter model. In other words, the *difference* in the error might be smaller than the actual difference between the approximate and the real cost in each case.

Another area where this may be useful is related to the modeling of network traffic by hierarchical MMPP processes [12]. The packet process is represented by a Poisson process within the ON period of a session process [5]. An analytic model such as the one that we are presenting here could be used within some decomposition technique of the hierarchical MMPP that would be required to compute the jitter.

Finally, it should also be mentioned that we have looked at actual measurements in the access network of a large ISP. We have found that this traffic, which is generated by several HTTP sources, is a major component of the total traffic and that the downstream, upstream, or total traffic can be very accurately approximated by an exponential distribution. This shows that the Poisson assumption *is* realistic in *some* kinds of access networks. In cases like these, the model that we are presenting here can be applied directly to calculate the end-to-end jitter and to design the network.

In the following, we assume that all network nodes have a single output interface, or Egress Port, and several inputs interfaces, or Ingress Ports. Users generate packets of various flows corresponding to different applications on the input interfaces, and all these flows exit the node through the output interface toward different destination nodes. We focus on a particular flow, called the *tagged* flow, which can be any one of the flows through the node. At each node, the tagged flow is multiplexed under the FCFS discipline with several others flows, called the *background traffic*. The inputs parameters of the model are the number of input interfaces at the node, the link speed, and the traffic flow matrix, and the output parameters will be the jitter of the tagged flow packets.

In Section 2, we present our definition of jitter. We then present in Section 3 an analysis of the jitter for a single queue. The jitter model for multiple queues in tandem is described in Section 4 and is also checked by simulation. Section 5 briefly discusses plan-

ning and design issues whereas Section 6 provides some conclusions.

2 Definition of jitter

Jitter is a measure of the packets' transfer delay variation. It can depend on the packets' routes and is caused by multiplexing several flows in the node queues. There are several definitions of jitter that try to capture the delay variation of packets. In this paper, we adopt the IETF [6] definition of jitter. It is based on the transit delay between the entry and the exit nodes. Let T_j represent the delay experienced by the jth packet going through a queue. The difference of transit time between two consecutive packets of the tagged flow can be written as

$$J_i = T_{i+1} - T_i \tag{1}$$

which can be positive or negative. The average end-toend delay jitter is then given by the expected absolute value of this random variable

$$J = E\left[|T_{i+1} - T_i|\right]. \tag{2}$$

In the case of a network, let $T_j^{(n)}$ be the delay of *j*th packet at node *n*. The end-to-end jitter for a tagged flow passing through *N* tandem nodes is given by

$$J^{(N)} = E \left[\left| \sum_{n=1}^{N} T_{j+1}^{(n)} - T_{j}^{(n)} \right| \right].$$
 (3)

3 Jitter model for a single queue

We now consider a single queue with infinite buffer and a FCFS discipline. There are K streams of packets arriving to this queue each with possibly different parameters for the inter-arrival time and packet length distributions. We are interested in the jitter of a particular stream k, called a *tagged* stream. Unless otherwise noted, all these streams are Poisson with arrival rate λ_m , and all service time distributions are negative exponential with parameter μ_m . We provide exact formulas for the jitter in two limit cases where either the arrival rate of the tagged stream is much larger or much lower than the others. We also present an approximate formula for the intermediate case which we evaluate through simulation. Define

- λ the total arrival rate $\lambda = \sum_{m=1}^{K} \lambda_m$
- λ_k the arrival rate of the tagged flow
- λ_0 the background arrival rate $\lambda_0 = \lambda \lambda_k$



3.1 Small arrival rate

Suppose that $\lambda_k \ll \lambda_0$. In this case, two packets of stream k are separated by a large number of packets from the other streams so that we can ignore the correlation between the transit delays of two consecutive packets and assume that T_{j+1} and T_j are two independent random variables. Since the T_j s are the sojourn time of a customer in a queue, we know that they have a negative exponential distribution with parameter $\eta = \mu - \lambda$. Under these conditions, we can use a well-known property of exponential distributions [14].

Theorem 1 Let X_1 and X_2 be two continuous independent and identically distributed random variables with the same distribution f as the random variable X. The distribution of the random variable $|X_1 - X_2|$ is f if and only if f is the exponential distribution.

From this, we get directly that

Proposition 1 When the arrival rate of the tagged stream is small, the jitter is given by

$$J = E\left[\mid T_{j+1} - T_j \mid \right] = \frac{1}{n}, \quad where \quad \eta = \mu - \lambda. \tag{4}$$

3.2 Large arrival rate

Next consider the case where $\lambda_k \approx \lambda$. In this case, we can neglect the presence of the other streams and consider that we have a queue with only one flow. The conditions of Proposition 1 no longer apply since the sojourn times of two consecutive packets are clearly not independent and we have to take the correlation between the transit time of two consecutive packets into account. First define

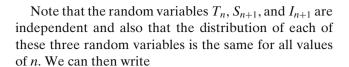
- t_j arrival time of packet j and $I_j = t_j t_{j-1}$ the interarrival time
- r_j departure time of packet j
- W_i waiting time of packet j
- S_j service time of packet j
- T_i transit time of packet j so that $T_i = W_i + S_i$

We can write

$$W_{j+1} = \begin{cases} 0, & \text{if } r_j \le t_{j+1}, \\ W_j + S_j - (t_{j+1} - t_j), & \text{if } r_j > t_{j+1} \end{cases}$$
 (5)

so that we have

$$T_{j+1} - T_j = \max(S_{j+1} - T_j, S_{j+1} - I_{j+1}).$$
 (6)



$$J = E\left[\mid T_{n+1} - T_n \mid \right]$$

$$= \int_0^\infty I(i) \left\{ \int_0^\infty S(s) \left[\int_0^i \mid s - x \mid T(x) dx + \mid s - i \mid \int_i^\infty T(x) dx \right] ds \right\} di$$
(7)

Note that this expression is entirely general. We now assume that the distributions are exponential, namely that

$$T(x) = \eta e^{-\eta x}; \quad S(s) = \mu e^{-\mu s}; \quad I(i) = \lambda e^{-\lambda i}.$$
 (8)

From these, we can compute Eq. 7 and get

$$J = \eta \mu \lambda (A + B) \tag{9}$$

$$A = \frac{1}{\mu^2} \left(\frac{1}{\lambda \eta} - \frac{1}{\eta \mu} \right) \tag{10}$$

$$B = \frac{1}{\mu^2} \frac{1}{\eta \mu} \tag{11}$$

from which we get the following proposition:

Proposition 2 If the arrival rate of the tagged stream is large, its jitter is given by

$$J = E[|T_{j+1} - T_j|] = \frac{1}{\mu}.$$
 (12)

3.3 Intermediate arrival rate

Finally, we consider the case where the arrival rate of the tagged flow takes values between the two extreme points. The tagged flow is multiplexed under the FCFS discipline with a background Poisson traffic with parameter λ_0 generated by the others flows. The value of the total traffic load ρ is

$$\rho = \frac{\lambda}{\mu} = \frac{\lambda_k + \lambda_0}{\mu}.\tag{13}$$

We want to compute the jitter J_k of a particular Poisson flow k with parameter λ_k . It is defined as

$$J_k = E\left[\mid T_j^k - T_{j-1}^k \mid \right]$$

where T_j^k is the delay of the *j*th packet of flow k. In this case, we provide a light-load approximation only.



We denote P_j and P_{j+1} two consecutive packets of the tagged flow with corresponding delays T_j and T_{j+1} . The light load assumption can be stated as

Proposition 3 In a lightly loaded system, packet P_{j+1} of flow k arrives at the queue when P_j has already left the system.

Given that the arrival process is Poisson with parameter λ_k , the average time between P_j and P_{j+1} is $\tau_k = 1/\lambda_k$. The light load assumption can then be stated as

$$Pr\{T_i > \tau_k\} \approx 0. \tag{14}$$

We show in the "Appendix" that the jitter for the tagged flow is given by

Proposition 4 The end-to-end jitter of a tagged flow produced by a single node can be approximated as

$$J_k \approx \frac{1}{\eta} f(\tau_k, \eta) \tag{15}$$

where

$$f(\tau_k, \eta) = 1 - e^{-\eta \tau_k} \left(\eta \tau_k + e^{-\eta \tau_k} \right). \tag{16}$$

In this equation, the expression $1 - f(\tau_k, \eta)$ can be seen as an estimate of the degree of correlation of two successive packets from flow k.

We can see that the approximation 15 satisfies a number of requirements. First, if $\lambda_k \approx 0$, then $\tau_k \approx \infty$ and we get $J_k \approx 1/\eta$. This is in line with the argument presented in Proposition 1.

When the tagged flow is dominant, $\lambda_k \approx \lambda$ so that $\eta \tau_k \approx (1 - \rho)/\rho$. In that case, we have

$$J \approx \frac{1}{\eta} \left[1 - e^{(\rho - 1)/\rho} \left(\frac{1 - \rho}{\rho} + e^{(\rho - 1)/\rho} \right) \right]. \tag{17}$$

Consider the two extreme values for ρ . If $\rho\approx 0$, we see that the exponential will be small and that $J\approx 1/\eta$ as well. In other words, when ρ is small, the jitter does not depend much on the proportion of tagged traffic. If, on the other hand, $\rho\approx 1$, then $\eta\tau_k\approx 0$ and we get, after expanding the exponentials to first order, $J\approx 1/\mu$. To summarize, if ρ is small, J should be relatively insensitive to the mix of traffic while it will be more sensitive when ρ is large. These limit cases are summarized in Table 1.

Table 1 Limit values for J

ρ	λ_k	
	0	λ
0	$1/\eta$	$1/\eta$
1	$1/\eta$	$1/\mu$

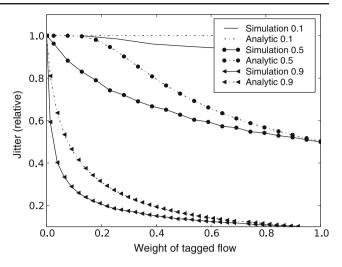


Fig. 1 Validation of model

3.4 Validation of single node model

The model is validated by comparison with simulation results as shown on Fig. 1. We assume that the packet size distribution is exponential with mean 1 Kbyte. C is the capacity of the link, say in bits per second. The average service time of a packet is $1/\mu = L/C$. In these examples, we consider a link with high capacity C = 622 Mbits/s.

The x axis represents the weight of the tagged flow λ_k/λ and the vertical axis is the value of the jitter normalized to the largest value $1/\eta$. Three sets of curves were produced where the total load ρ was fixed to the values $\rho = 0.1, 0.5, 0.9$. In each case, the value of λ_k was increased from 0 to λ while decreasing the values of the other flows such that λ remained constant. Two curves are shown for each set, a dotted line for the analytic results and a solid one for the simulation results.

For low load, at $\rho = 0.1$, we see that the model is insensitive to the weight of λ_k while in reality, there is a slight decrease in the value of the jitter as λ_k increases. For moderate to high loads, the approximation is reasonably accurate for smaller weights and very good at higher values of the weight. More important, however, is the fact that the model is conservative in the sense that it gives values of the jitter that are somewhat higher than the actual value. In the absence of an exact model, this is a desirable value for network design since it will produce a network with sufficient QoS to meet the required value.

3.5 Jitter under increasing load

It is common wisdom that in a queuing system, performance will degrade as the load increases. This is



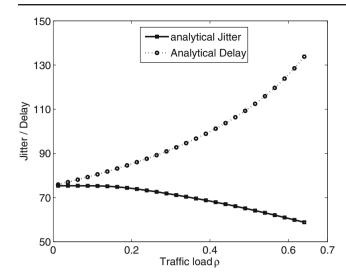


Fig. 2 Delay and jitter behavior

certainly true for delay and loss, and it is intuitively clear that it should be so. A most surprising feature of delay jitter is that this "obvious" behavior is no longer true. This can be seen from Fig. 2 where we have plotted the average delay and jitter as a function of λ_k . There is a striking difference in the two curves, and we see that jitter actually *decreases* as the load increases. This result is confirmed by event-driven simulation and also in realistic environments [4].

This behavior is not a consequence of the delay model since it has been observed in more realistic situations [16]. It can be explained to some extent by the following argument: When a queue is nearly empty, arriving packets do not have to wait very often so that the delay depends on the inter-arrival process, the service time, and the time in queue. When the queue is large, almost all packets have to wait so that the inter-arrival process does not contribute much to the sojourn time. In that case, most of the variation in the delay is due to the service time only, and it is not unreasonable to expect that the jitter will be smaller in this case that what it is in a lightly loaded network. This has some consequences for network design that are briefly discussed in Section 5.

4 Multiple node case

The estimation of the jitter along a path is more complicated than for a single queue because of the multiplexing of several flows at each node and the correlation between the service time at a node and the arrival at the next node.

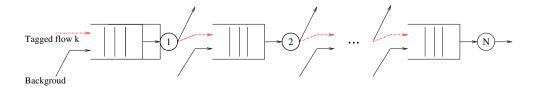
We want to estimate the end-to-jitter for a tagged flow k passing through N tandem nodes, as in the example of an access network of Fig. 3. At each node, flow k is multiplexed under the FCFS discipline with several others flows called *background traffic*. Let $\lambda_k^{(n)}$ be the arrival rate of packets of flow k at the node n, and let $\lambda_0^{(n)}$ the arrival rate of the background traffic at the same node. The service time of all packets is a negative exponential with parameter μ .

4.1 Correlation in tandem queues

Jitter is defined as the variation in the delay of packets through a router or over the network. The packet delays through a queue are strongly correlated with each other. If we are interested in the delays of a particular flow, this effect can be reduced by the multiplexing of several flows but still needs to be taken into account. In a network, there is also a strong correlation between queues in tandem due to the dependence between the service time of a given packet and the arrival time at the following router. These effects have a significant impact on the end-to-end jitter and the standard queuing theory techniques are too complex to calculate an exact value for the jitter.

We show in Fig. 4 some simulation results for the jitter incurred by two queues in tandem. We can see that the jitter incurred by the second queue is much lower than the jitter at the first queue. But this becomes less important after the second node as shown in Fig. 5. In this figure, we measure the jitter at each queue on a path, and we plot these values as a function of the node number on the path. It is quite clear that the first node has a much larger jitter than the others. We also note that the traffic load has a significant impact on the jitter value at each node.

Fig. 3 *N* simple queues in tandem





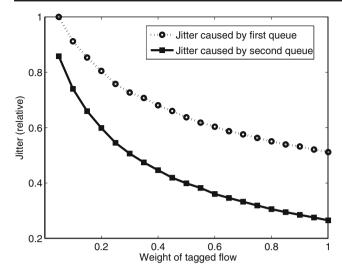


Fig. 4 Tandem queue correlation impacts on the tagged flow

Based on these empirical remarks, we assume that the formula of the jitter in the second node can be written as

$$J_k^2 = \frac{1}{\eta^{(2)}} K\left(\lambda_k^{(2)}, \eta^{(2)}\right) f\left(\tau_k^{(2)}, \eta^{(2)}\right)$$
 (18)

where $K(\lambda_k^{(n)}, \eta_2)$ depends on the delay correlation at the entrance of the second queue and J_1^k is the jitter at the first queue given by Eq. 15. The problem will

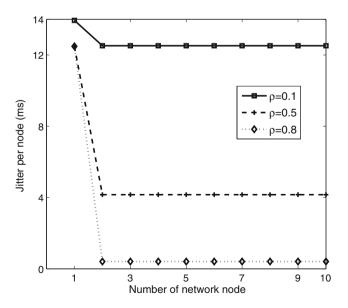


Fig. 5 Jitter variation as a function of the node number

be solved if we can approximate this delay correlation. In the next section, we describe an analytical approximation of this correlation, and from this, we deduce a general formula for the jitter in the case of multiple nodes.

4.2 Analytical model

We consider the case where the tagged flow goes through N tandem nodes. The two measurement points are the entry of the first buffer and the exit from the last server on the path. All the parameters of Section 3 are now indexed with a superscript n to indicate the node. For instance, we let $\lambda_k^{(n)}$ be the arrival rate of packets of flow k and $\lambda_0^{(n)}$ the arrival rate of the background traffic at node n.

Let $T_j^{(n)}$ be the delay of packet j through node n. The path jitter of the tagged flow k is given by

$$J_k^{(N)} = E\left[\left|\sum_{n=1}^N T_{j+1}^{(n)} - T_j^{(n)}\right|\right]. \tag{19}$$

The direct calculation of Eq. 19 is not easy so that we will use a simple approximation that takes into account the correlation of tandem queues. Still, we can see from Eq. 19 that

$$J_k^{(N)} \le \sum_{n=1}^N J_k^n \tag{20}$$

where J_n^k is the jitter of flow k at node n given by Eq. 16. Summing the jitter of the queues on a path will produce an overestimate of the true jitter. We quantify in Section 4.3 the magnitude of this over-estimation.

Let $q_i^{(n)}$ be the queue occupancy at the *i*th arrival from flow k at queue n. We then obtain the autocorrelation function for packets of flow k by

$$E\left[q_{i}^{(n)}q_{i+1}^{(n)}\right] = \frac{1}{\left(L^{(n)}\right)^{2} + \left(R^{(n)}\right)^{2}} \times \left(\left(L^{(n)}\right)^{2} + \frac{\lambda_{k}^{(n)}\left(R^{(n)}\right)^{2}}{\lambda_{k}^{(n)} + \mu/\left(R^{(n)}\right)^{2}}\right). \tag{21}$$

where $L^{(n)}$ is the mean queue length and $(R^{(n)})^2$ is the mean square length of the queue and are given by

$$L^{(n)} = \rho^{(n)}/1 - \rho^{(n)}$$
$$(R^{(n)})^2 = \rho^{(n)}/(1 - \rho^{(n)})^2$$



We define

$$K\left(\lambda_k^{(n)}, \eta^{(n)}\right) = 1 - E\left[q_i^{(n)} q_{i+1}^{(n)}\right].$$
 (22)

The end-to-end jitter of a tagged flow k in multiple node case can then be approximated by the following proposition:

Proposition 5 The end-to-end jitter for a tagged flow passing through N network nodes is approximated by

$$J_k^{(N)} \approx \frac{1}{\eta^{(1)}} f\left(\tau_k, \eta^{(1)}\right) + \sum_{n=2}^{N} \frac{1}{\eta^{(n)}} K\left(\lambda_k^{(n)}, \eta^{(n)}\right) f\left(\tau_k^{(n)}, \eta^{(n)}\right)$$
(23)

where

$$\eta^{(n)} = \mu \left(1 - \rho^{(n)} \right)$$

$$\lambda_k^{(n)} = \frac{1}{\tau_k^{(n)}}$$

and
$$f\left(\tau_k^{(n)}, \eta^{(n)}\right)$$
 is given by Eq. 16.

4.3 Validation of multiple node model

We can estimate the accuracy of formula 23 by comparing with the results of simulations. We show four estimations of the jitter through four queues in tandem, each with a different load ρ_i , as a function of the importance factor for the tagged flow. Two curves labeled

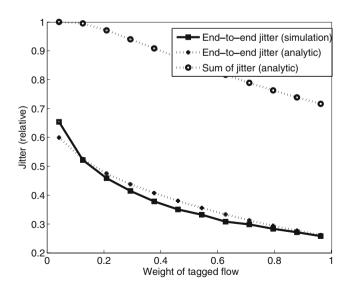


Fig. 6 Jitter vs arrival rate for four queues in tandem with $\rho_1 = 0.3$, $\rho_2 = 0.5$, $\rho_3 = 0.5$, and $\rho_4 = 0.8$

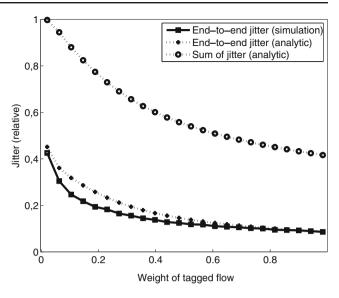


Fig. 7 Jitter vs arrival rate for four queues in tandem with $\rho_1 = 0.6$, $\rho_2 = 0.7$, $\rho_3 = 0.7$, and $\rho_4 = 0.9$

end-to-end jitter represent the actual jitter from the start to the end of the path. The curve labeled analytic shows the results obtained using Eq. 23 and the other one shows those obtained from the simulation. The most important conclusion is that for Poisson traffic, the analytic model is an excellent approximation to the end-to-end jitter over a large range of traffic loads. As we mentioned before, any dimensioning tool based on this model will then produce a conservative design where the actual jitter will be lower than what has been planned.

A similar pair of curves are presented when we replace the end-to-end calculation by the sum of the jitter

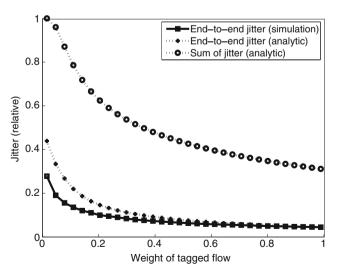


Fig. 8 Jitter vs arrival rate for four queues in tandem with $\rho_1 = 0.8$, $\rho_2 = 0.85$, $\rho_3 = 0.87$, and $\rho_4 = 0.9$



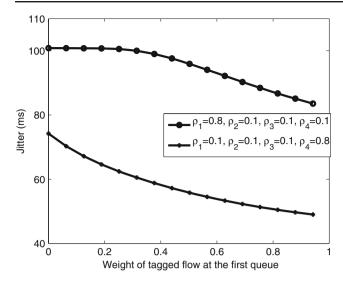


Fig. 9 Jitter for different positions of congested link

at each node (Figs. 6, 7, and 8). Although this would simplify the calculation considerably, we see that it is a very large overestimate and it may not be sufficiently accurate for planning purposes.

4.4 Effect of link congestion on jitter

The model provides insight into another unexpected property of path jitter. Suppose that a path has one link more heavily loaded than the others. If we compute the path delay, the location of this congested link on the path will have no impact on the value of the path delay. In the case of jitter, we can see from Fig. 9 that the *position* of the congested link in the path has a large influence on the total path jitter. We see that when the congested link is at the beginning of the path, the total jitter is much larger than when it is at the end of the path. This is another counter-intuitive result showing that jitter behaves quite differently from other QoS measures.

5 Planning and design issues

Planning and designing of data communication networks is immensely complex. These problems are generally formulated as large nonlinear optimization problems where any solution algorithm will have to evaluate the QoS a very large number of times while solving a given network. It is essential that any QoS model used in such a design tool can be evaluated quickly and as accurately as possible. The average network delay and throughput have usually been used as metrics to optimize the network cost and performance in current

design tools. This is simply due to the absence of a robust and simple formula for the others parameters such as the jitter, so that current network planning and design techniques are mostly based on average delay or loss constraints simply because they can often be easily calculated. We mentioned in this section some recommendations and suggestion to perform optimal network design.

As we have seen from Fig. 2, jitter decreases when the traffic load increases and is a concave function of load. This is very different from delay, which is a convex function of load. Optimizing with a concave objective tends to produce sparse networks while the opposite is true for convex functions which produce networks with higher connectivity. It is thus likely that the choice of QoS, delay or jitter, can have an impact on network routing and structure.

We have also seen in Fig. 5 that jitter is likely to be much more important when it occurs at the access nodes. This is due to the fact that access links have limited capacity so that congestion is more likely to occur on these links as opposed to the core. The results of Fig. 4 show that having jitter at the first node on a path will have a larger impact than when this occurs elsewhere on a path. This is another important effect that will have to be taken into account by network design algorithms.

6 Conclusion

In this paper, we have presented and evaluated an analytical approximation of the end-to-end jitter for Poisson traffic that can be used interactively or within a network design algorithm. We have given simple formulas for the jitter through a single queue and extended these to nodes in tandem. We have shown that in the case of a single network, jitter is bounded by the average service time and average transit time of packets. We have also shown that jitter decreases as packets move forward on a path. The analytic formulas were compared with simulation results. The accuracy was quite good for Poisson traffic. More importantly, however, is that the analytic values were larger than the actual values, which shows that a design tool based on them would produce a conservative solution which would easily meet the requires QoS.

We have found that in some cases, jitter can be a decreasing function of load and that the position where congestion occurs on a path can have a large impact on path jitter. These are counter-intuitive results that can potentially change the routing and/or network structure when jitter is taken into account.



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Appendix: Calculation for intermediate rate

Under the assumption of Proposition 3, T_{i+1} and T_i can be considered as two continuous independent and identically distributed random variables with a negative exponential distribution. That is, the pdf of $\Delta = T_{i+1} - T_i$ can be approximated as follows.

For the case z > 0,

$$f_{\Delta}(z) = \int_{-\tau_k}^{0} f_{-T_i}(u) f_{T_{i+1}}(z - u) du$$

= $\frac{\eta}{2} e^{-\eta z} - \frac{\eta}{2} e^{-\eta (2\tau_k + z)}$. (24)

For the case $-\tau \le z < 0$,

$$f_{\Delta}(z) = \int_{0}^{\tau_{k}+z} f_{T_{i+1}}(u) f_{T_{i}}(z-u) du$$
$$= \frac{\eta}{2} e^{\eta z} - \frac{\eta}{2} e^{-\eta(2\tau_{k}+z)}.$$
 (25)

Otherwise,

$$f_{\Delta}(z) = 0. (26)$$

Thus, from the definition of the jitter 2, we have

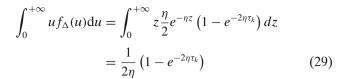
$$J^{k} = E[|T_{i+1} - T_{i}|]$$

$$= \int_{-\infty}^{+\infty} |u| f_{\Delta}(u) du$$

$$= -\int_{0}^{0} u f_{\Delta}(u) du + \int_{0}^{+\infty} u f_{\Delta}(u) du.$$
 (27)

We also have

$$-\int_{-\tau}^{0} u f_{\Delta}(u) du = \int_{\tau_{k}}^{0} z \frac{\eta}{2} e^{\eta z} - \frac{\eta}{2} e^{-\eta(2\tau_{k}+z)} dz$$
$$= \frac{1}{\eta} \left[\frac{1}{2} - e^{-\eta \tau_{k}} \left(\eta \tau_{k} + \frac{1}{2} e^{-\eta \tau_{k}} \right) \right]$$
(28)



From this, we get the closed form formula for the jitter

$$J^{k} = \frac{1}{\eta} \left[1 - e^{-\eta \tau_{k}} \left(\eta \tau_{k} + e^{-\eta \tau_{k}} \right) \right]. \tag{30}$$

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