

## Par-BF: a Parallel Partitioned Bloom Filter for Dynamic Data Sets

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#### Outline

- Brief Summary of Bloom Filters (BFs)
- BF Design for Dynamic Data Sets
- Par-BF
- Evaluation
- Summary

## Bloom Filter (BF)

- A space-efficient index to quickly answer "Is an element x in the target set S?"
- Widely used as an in-memory index

"Wherever a list or set is used, and space is at a premium, consider using a Bloom filter if the effect of false positives can be mitigated."

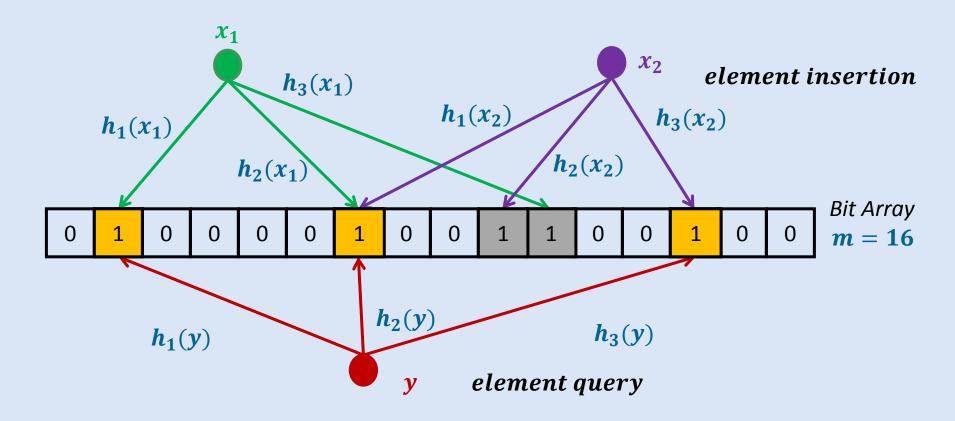
--A. Broder and M. Mitzenmacher

Network applications of bloom filters: A survey

#### **BF** Definition

- A BF is an array of m bits representing a set  $S = \{x_1, x_2, ..., x_n\}$  of n elements
  - > All bits are set to 0 initially
- k independent hash functions  $h_1, ..., h_k$ , with range  $\{1, 2, ..., m\}$ 
  - > Assume that each hash function maps each item in the universe to a random number uniformly over the range
- For each element x in S, the bit position  $h_i(x)$  is set to 1, for  $1 \le i \le k$ 
  - ➤ A bit in the array may be set to 1 multiple times for different elements

## An example of BF



False Positive has been unexpected encountered that y is not existed in S but reports it is in!

## **Dynamic Data Sets**

- Multiple disjointed and independent sets competing for a limited and shared preallocated space
- Cannot predict the number of elements in each set in advance

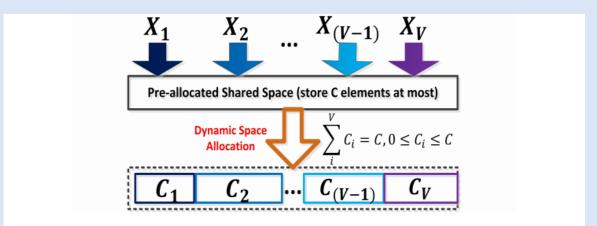


Figure 1: The size allocated to each  $X_i$  may change dynamically when V disjointed and independent sets  $\{X_1, X_2, ..., X_V\}$  to compete for a limited and shared preallocated space.

### Designing a BF for Dynamic Data Sets

- Dividing the shared BF into a certain number of fixed-size sub-BF units (much finer granularity)
- A new sub-BF is added into the sub-BF list of a set  $X_i$  for new insertions when all the previous sub-BFs are full
- Similar with the memory paging policy that each page size is usually 4KB

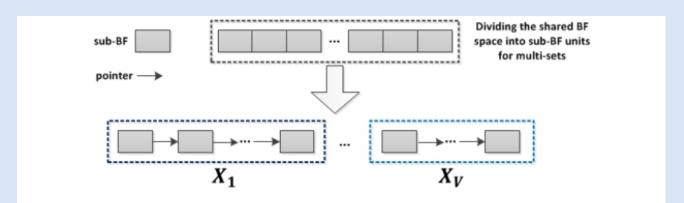


Figure 2: The sub-BF unit is the fundamental BF-based data structure for supporting dynamic sets.

# Previous work (1) The Dynamic Bloom Filters (DBF)

- A DBF consists of s homogeneous standard (or counting) sub-BFs
  - $\succ$  "Homogeneous" means both the array size m and the k hash functions are exactly the same
- Merit: support useful bit vector based algebra operations: union, intersection, and halving
- Defect: no mechanism to control the overall false positive rate, F

$$F = 1 - \prod_{h=1}^{s} (1 - f(h)) \approx \sum_{h=1}^{s} f(h)$$

$$(\forall h = 1, 2, ..., s, f(h) \ll 1/s)$$
(3)

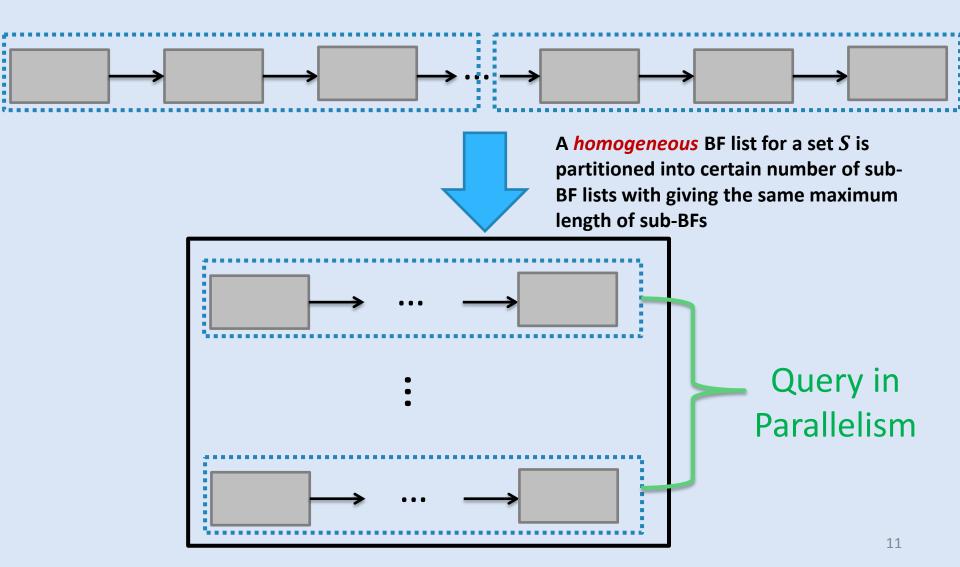
## Previous work (2) The Scalable BF (SBF)

- A SBF is made up of a series of heterogeneous sub-BFs
  - $\succ$  "heterogeneous" means both the size m and the k hash mapping functions of each sub-BF are different
- The key idea is that both m and k of each sub-BF is well-conducted with a tighter maximum fpp on a geometric progression
- Merit: the overall false positive rate, F is in convergence
- Main Defect: No support of BF-based algebra operations for simplifying resource management

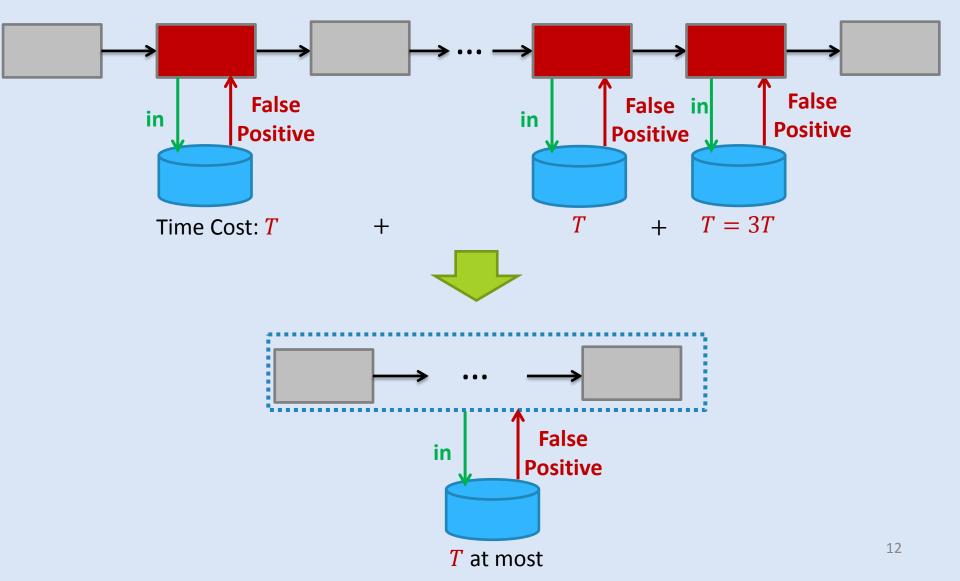
#### Contributions of Par-BF

- Query in Parallelism on a sub-BF list basis
- Making the overall false positive rate F limited
- Supporting useful bit vector based algebra operations
- Performance-driven Initialization

#### **Partition Method**



### Merits of the Partition



#### Merits of the Partition

- Query in Parallelism makes fpp of an independent sub-BF list, F, in a limited range
- Supporting useful bit vector based algebra operations, since all sub-BFs are homogeneous

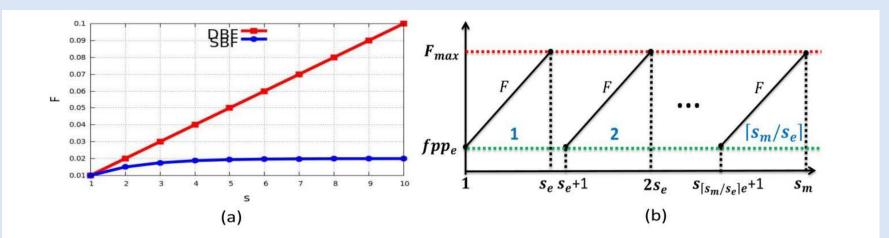


Figure 3: (a) An example of F value growth comparison between DBF and SBF, f(1) = 0.01, r = 0.5 in SBF. (b) Our recommended Par-BF design,  $s_m = \frac{C}{n}$ .

#### Performance-driven Initialization

- The thread is assigned on a sub-BF list basis to do independent and parallel membership query
  - Assuming the thread number can be maximally equal to that of CPU cores
- Guaranteeing the worst lookup cost of each thread,  $Q_{worst}$ , when the element x is not in the set S
- Guaranteeing the memory overhead is not exceed the expected size, M

### The Worst Lookup Cost of each Thread

- If we define the expected look up cost,  $Q_{worst}$ , in advance, how to measure the upper bound value of fpp of each sub-BF list,  $F_{max}$ ?
- $S_q \gg S_b$ , when each sub-BF of the sub-BF list is in memory

$$Q_{worst} = s_e(0.5^k \cdot (S_b + S_q) + (1 - 0.5^k) \cdot S_b) = F_{max} \cdot S_q + s_e \cdot S_b$$
 (7)

Average lookup cost of an element in backup container

Average lookup cost in a sub-BF

#### Initialization Results

• If we previously define the whole capacity space C, the thread number T, the I/O metrics:  $S_q$ ,  $S_b$  and  $Q_{worst}$ , the maximum memory overhead M, all essential parameters of par-BF can be properly initialized.

Table IV: The Results of Some Parameters

Symbol	Value
$F_{max}$	$\frac{Q_{worst} - s_e \cdot S_b}{S_q}$
$fpp_e$	$0.5^{k}$
n	$\frac{N \cdot fpp_e}{F_{max}} = \frac{C \cdot 0.5^k \cdot S_q}{T \cdot (Q_{worst} - s_e \cdot S_b)}$
m(bits)	$n \cdot 1.44 \cdot k$
M	$1.44 \cdot k \cdot C$
$s_e$	$\frac{M}{m \cdot T} = \frac{C}{n \cdot T}$

**Known in advance** 

Table VI: Preliminary Definition of Parameters

Parameter	Т	C	s	$S_q$	$S_b$	M	$Q_{worst}$
Value	32	$3 \times 10^{9}$	1KB	0.01ms	0	4.32GB	0.0006ms
Parameter	k	$fpp_e$	$F_{max}$	n	m	$s_e$	N
Value	8	0.4%	6%	$6.25 \times 10^{6}$	9MB	15	$9.375 \times 10^{7}$

ID

#### **Evaluation**

- Par-BF can find the sweet point, to balance the trade-off between high-performance and low-overhead
- The actual  $Q_{worst}$  is close to the expected  $Q_{worst}$  (nearly 99%) which validate our policy of parameter tunings

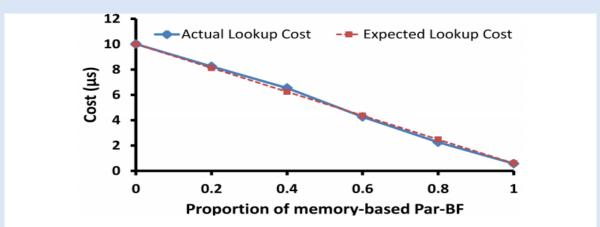


Figure 5:  $Q_{worst}$  comparisons between the actual value and the expected value when choosing different proportion of memory overhead  $\rho$ .  $Q_{worst}$  is taken place when the trace data from **T2** are only firstly written to the K-V store. The expected  $Q_{worst}$  is calculated by  $\rho \cdot S_b + (1 - \rho) \cdot S_q$ .

#### The Performance of Par-BF

- We record the average read throughput during running the three data traces T1, T2, and T3
- The IOPS of Par-BF outperforms that of DBF and SBF, from 6X to 10X and from 2X to 4X, respectively

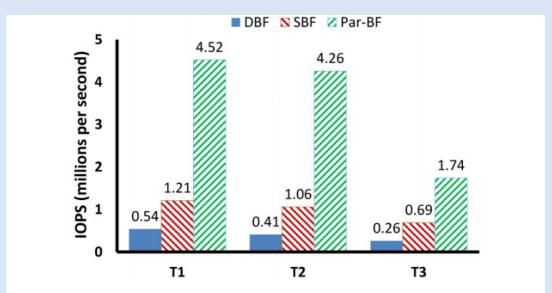


Figure 6: The throughput comparisons between DBF, SBF, and Par-BF through running T1, T2, and T3. The initialized r = 0.5, s = 2, and  $f(1) = fpp_e$  of SBF.

## **Garbage Collection**

- The memory overhead of both DBF and Par-BF is less than that of SBF by about 0.18GB
- the GC process which is only supported by union operation between homogenous sub-BFs makes the memory space more efficient, such as reducing the memory overhead by 0.45X in T2

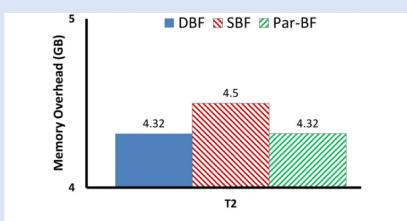


Figure 7: The memory overhead of using data trace **T2** by the three BF policies.

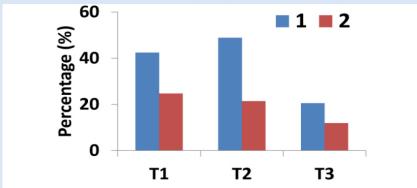


Figure 8: The comparison on percentage of chunk access in each trace (Type "1" denotes "do GC" and type "2" denotes "do NOT GC").

## Summary and Future work

Table I: The comparison results of SBF, DBF, and Par-BF.

Property	DBF	SBF	Par-BF	
Query method	Linear probing	Linear probing	Parallel probing	
Algebra operations	Supported	Not Supported	Supported	
FPP	Uncontrollable	Convergent	Controllable	
Initializations	Empirical	Empirical	Calculated	
Performance	Very Low	Low	High	

#### **Future Work:**

- 1 Model improvement
- 2 Experiments with scientific computing applications
- 3 Experiments with different thread number when using different CPU cores

# Thanks Questions?

## Limiting the k value in range

- If the maximum space overhead is limited by M', the inequality  $k \leq \frac{M'}{1.44 \cdot C}$  must be satisfied
- $F_{max}$  must be greater than the expected fpp of a sub-BF,  $fpp_e$ , thus, the inequality  $F_{max} = \frac{Q_{worst} S_e \cdot S_b}{S_q} \approx \frac{Q_{worst}}{S_q} \geq fpp_e = 0.5^k$

$$log_{0.5}(\frac{Q_{worst} - s_e \cdot S_b}{S_q}) \leq k \leq \frac{M'}{1.44 \cdot C} \tag{10}$$
 Performance Memory space requirement limitation