# Exponential Weights on the Hypercube in Polynomial Time

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#### Abstract

We study a general online linear optimization problem(OLO). At each round, a subset of objects from a fixed universe of n objects is chosen, and a linear cost associated with the chosen subset is incurred. To measure the performance of our algorithms, we use the notion of regret which is the difference between the total cost incurred over all iterations and the cost of the best fixed subset in hindsight. We consider Full Information and Bandit feedback for this problem. This problem is equivalent to OLO on the  $\{0,1\}^n$ hypercube. The Exp2 algorithm and its bandit variant are commonly used strategies for this problem. It was previously unknown if it is possible to run Exp2 on the hypercube in polynomial time.

In this paper, we present a polynomial time algorithm called PolyExp for OLO on the hypercube. We show that our algorithm is equivalent Exp2 on  $\{0,1\}^n$ , Online Mirror Descent(OMD), Follow The Regularized Leader(FTRL) and Follow The Perturbed Leader(FTPL) algorithms. We show Poly-Exp achieves expected regret bound that is a factor of  $\sqrt{n}$  better than Exp2 in the full information setting under  $L_{\infty}$  adversarial losses. Because of the equivalence of these algorithms, this implies an improvement on Exp2's regret bound in full information. We also show matching regret lower bounds. Finally, we show how to use PolyExp on the  $\{-1,+1\}^n$  hypercube, solving an open problem in Bubeck et al (COLT 2012).

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#### 1 Introduction

Consider the following abstract game which proceeds as a sequence of T rounds. In each round t, a player has to choose a subset  $S_t$  from a universe U of n objects. Without loss of generality, assume  $U = \{1, 2, ..., n\} = [n]$ . Each object  $i \in U$  has an associated loss  $c_{t,i}$ , which is unknown to the player and may be chosen by an adversary. On choosing  $S_t$ , the player incurs the cost  $c_t(S_t) = \sum_{i \in S_t} c_{t,i}$ . In addition the player receives some feedback about the costs of this round. The goal of the player is to choose the subsets such that the total cost incurred over a period of rounds is close to to the total cost of the best subset in hindsight. This difference in costs is called the regret of the player. Formally, regret is defined as:

$$\mathcal{R}_{T} = \sum_{t=1}^{T} c_{t}(S_{t}) - \min_{S \subseteq U} \sum_{t=1}^{T} c_{t}(S)$$

We can re-formulate the problem as follows. The  $2^n$  subsets of U can be mapped to the vertices of the  $\{0,1\}^n$  hypercube. The vertex corresponding to the set S is represented by its characteristic vector  $X(S) = \sum_{i=1}^n 1\{i \in S\}e_i$ . From now on, we will work with the hypercube instead of sets and use losses  $l_{t,i}$  instead of costs. In each round, the player chooses  $X_t \in \{0,1\}^n$ . The loss vector  $l_t$  is be chosen by an adversary and is unknown to the player. The loss of choosing  $X_t$  is  $X_t^{\top}l_t$ . The player receives some feedback about the loss vector. The goal is to minimize regret, which is now defined as:

$$\mathcal{R}_T = \sum_{t=1}^{T} X_t^{\top} l_t - \min_{X \in \{0,1\}^n} \sum_{t=1}^{T} X^{\top} l_t$$

This is the Online Linear Optimization (OLO) problem on the hypercube. As the loss vector  $l_t$  can be set by an adversary, the player has to use some randomization in its decision process in order to avoid being foiled by the adversary. At each round t = 1, 2, ..., T, the player chooses an action  $X_t$  from the decision set  $\{0,1\}^n$ , using some internal randomization. Simultaneously, the adversary chooses a loss vector  $l_t$ , without access to the internal randomization of the player. Since the player's strategy is randomized and the adversary could be adaptive, we consider the expected regret of the player as a measure of the player's performance. Here the expectation is with respect to the internal randomization of the player and the adversary's randomization.

We consider two kinds of feedback for the player.

- 1. Full Information setting: At the end of each round t, the player observes the loss vector  $l_t$ .
- 2. Bandit setting: At the end of each round t, the player only observes the scalar loss incurred  $X_t^{\top} l_t$ .

In order to make make quantifiable statements about the regret of the player, we need to restrict the loss vectors the adversary may choose. Here we assume that  $||l_t||_{\infty} \leq 1$  for all t, also known as the  $L_{\infty}$  assumption.

There are three major strategies for online optimization, which can be tailored to the problem structure and type of feedback. Although, these can be shown to be equivalent to each other in some form, not all of them may be efficiently implementable. These strategies are:

- 1. Exponential Weights (EW)[10, 14]
- 2. Follow The Leader (FTL)[12]
- 3. Online Mirror Descent (OMD) [15].

For problems of this nature, a commonly used EW type algorithm is Exp2 [2, 3, 6]. For the specific problem of Online Linear Optimization on the hypercube, it was previously unknown if the Exp2 algorithm can be efficiently implemented [6]. So, previous works have resorted to using OMD algorithms for problems of this kind. The main reason for this is that Exp2 explicitly maintains a probability distribution on the decision set. In our case, the size of the decision set is  $2^n$ . So a straightforward implementation of Exp2 would need exponential time and space.

#### 1.1 Our Contributions

We use the following key observation: In the case of linear losses the probability distribution of Exp2 can be factorized as a product of n Bernoulli distributions. Using this fact, we design an efficient polynomial time algorithm called PolyExp for sampling sampling from and updating these distributions.

We show that PolyExp is equivalent to Exp2. In addition, we show that PolyExp is equivalent to OMD with entropic regularization and Bernoulli sampling. This

allows us to analyze PolyExp's using powerful analysis techniques of OMD. We also show that PolyExp is equivalent to a Follow The Regularized Leader(FTRL) and a Follow The Perturbed Leader(FTPL) algorithms.

This kind of equivalence is rare. To the best of our knowledge, the only other scenario where this kind of equivalence holds is on the probability simplex for the so called experts problem.

In our paper, we focus on the  $L_{\infty}$  assumption. In the full information setting, directly analyzing Exp2 gives a regret bound of  $O(n^{3/2}\sqrt{T})$ . Using the equivalence to OMD, we show that PolyExp's regret bound is  $n\sqrt{T}$ . In the bandit setting however, PolyExp does not improve Exp2's analysis. These results are summarized by the table below.

| $L_{\infty}$      |                      |                           |
|-------------------|----------------------|---------------------------|
|                   | Full Information     | Bandit                    |
| Exp2 <sup>1</sup> | $O(n^{3/2}\sqrt{T})$ | $O(n^2\sqrt{T})$          |
| PolyExp           | $O(n\sqrt{T})$       | $O(n^2\sqrt{T})$          |
| Lowerbound        | $\Omega(n\sqrt{T})$  | $\Omega(n^{3/2}\sqrt{T})$ |

However, since we show that Exp2 and PolyExp are equivalent, they must have the same regret bound. This implies an improvement on Exp2's regret bound in full information.

**Proposition 1.** For the Online Linear Optimization problem on the  $\{0,1\}^n$  Hypercube, Exp2, OMD, FTRL, FTPL and PolyExp are equivalent. Moreover, under  $L_{\infty}$  adversarial losses, these algorithms have the following regret:

- 1. Full Information:  $O(n\sqrt{T})$
- 2. Bandit:  $O(n^2\sqrt{T})$ .

We also have the following lower bounds.

**Proposition 2.** For the Online Linear Optimization problem on the  $\{0,1\}^n$  Hypercube with  $L_{\infty}$  adversarial losses, the regret of any algorithm is at least:

- 1. Full Information:  $\Omega\left(n\sqrt{T}\right)$
- 2. Bandit:  $\Omega(n^{3/2}\sqrt{T})$ .

Finally, in [6], the authors state that it is not known if it is possible to sample from the exponential weights distribution in polynomial time for  $\{-1,+1\}^n$  hypercube. We show how to use PolyExp on  $\{0,1\}^n$  for  $\{-1,+1\}^n$ . We show that the regret of such an algorithm on  $\{-1,+1\}^n$  will be a constant factor away

<sup>&</sup>lt;sup>1</sup>direct analysis

from the regret of the algorithm on  $\{0,1\}^n$ . Thus, we can use PolyExp to obtain a polynomial time algorithm for  $\{-1,+1\}^n$  hypercube.

We present the proofs of equivalence and regret of PolyExp within the main body of the paper. The remaining proofs are deferred to the appendix.

#### 1.2 Relation to Previous Works

In previous works on OLO [9, 13, 2, 8, 6, 3] the authors consider arbitrary subsets of  $\{0,1\}^n$  as their decision set. This is also called as Online Combinatorial optimization. In our work, the decision set is the entire  $\{0,1\}^n$  hypercube. Moreover, the assumption on the adversarial losses are different. Most of the previous works use the  $L_2$  assumption [6, 9, 8] and some use the  $L_{\infty}$  assumption [13, 2].

The Exp2 algorithm has been studied under various names, each with their own modifications and improvements. In its most basic form, it corresponds to the Hedge algorithm from [10] for full information. For combinatorial decision sets, it has been studied by [13] for full information. In the bandit case, several variants of Exp2 exist based on the exploration distribution used. These were studied in [9, 8] and [6]. It has been proven in [2] that Exp2 is provably sub optimal for some decision sets and losses.

Follow the Leader kind of algorithms were introduced by [12] for the full information setting, which can be extended to the bandit settings in some cases.

Mirror descent style of algorithms were introduced in [15]. For online learning, several works [1, 13, 6, 3] consider OMD style of algorithms. Other algorithms such as Hedge, FTRL and FTPL etc can be shown to be equivalent to OMD with the right regularization function and purturbation distribution. In fact, [18] show that OMD can always achieve a nearly optimal regret guarantee for a general class of online learning problems.

Under the  $L_{\infty}$  assumption, [13] and [2] present lower bounds that match our lower bounds. However, they prove that there exists a subset  $S \subset \{0,1\}^n$  and a sequence of losses on S such that the regret is at least some lower bound. So, these results are not directly applicable in our case. So, we derive lower bounds specific for the entire hypercube, showing that there exists a sequence of losses on  $\{0,1\}^n$  such that the regret is at least some lower bound.

We refer the readers to the books by [7], [5], [17], [11] and lectures by [16], [4] for a comprehensive survey of online learning algorithms.

## 2 Algorithms and Equivalences

In this section, we describe and analyze the Exp2, OMD with Entropic regularization and Bernoulli Sampling, and PolyExp algorithms and prove their equivalence.

#### 2.1 Exp2

Algorithm: Exp2

**Parameters:** Learning Rate  $\eta$ 

Let  $w_1(X) = 1$  for all  $X \in \{0,1\}^n$ . For each round  $t = 1, 2, \dots, T$ :

- 1. Sample  $X_t$  as below. Play  $X_t$  and incur the loss  $X_t^{\top}l_t$ .
  - (a) Full Information:  $X_t \sim p_t(X) = \frac{w_t(X)}{Z_t}$ , where  $Z_t = \sum_{Y \in \{0,1\}^n} w_t(Y)$
  - (b) Bandit:  $X_t \sim q_t(X) = (1 \gamma)p_t(X) + \gamma \mu(X)$ . Here  $\mu$  is the exploration distribution.
- 2. See Feedback and construct  $\tilde{l}_t$ .
  - (a) Full Information:  $\tilde{l}_t = l_t$ .
  - (b) Bandit:  $\tilde{l}_t = P_t^{-1} X_t X_t^{\top} l_t$ , where  $P_t = \mathbb{E}_{X \sim q_t}[XX^{\top}]$
- 3. Update for all  $X \in \{0,1\}^n$

$$w_{t+1}(X) = \exp\left(-\eta \sum_{\tau=1}^{t} X^{\top} \tilde{l}_{\tau}\right) \text{ or equivalently}$$

$$w_{t+1}(X) = \exp(-\eta X^{\top} \tilde{l}_{t}) w_{t}(X)$$

The loss vector used to update Exp2 must satisfy the condition that  $\mathbb{E}_{X_t}[\tilde{l}_t] = l_t$ . In the bandit case, the estimator was first proposed by [9]. Here,  $\mu$  is the exploration distribution and  $\gamma$  is the mixing coefficient. We use uniform exploration over  $\{0,1\}^n$ .

Exp2 has several computational drawbacks. First, it uses  $2^n$  parameters to maintain the distribution  $p_t$ . Sampling from this distribution in step 1 and updating it step 3 will require exponential time. For the bandit settings, even computing  $\tilde{l}_t$  will require exponential time. We state the following regret bounds by analyzing Exp2 directly. The proofs are in the appendix. Later, we prove that these can be improved. These regret bounds are under the  $L_{\infty}$  assumption.

**Theorem 3.** In the full information setting, if  $\eta = \sqrt{\frac{\log 2}{nT}}$ , Exp2 attains the regret bound:

$$E[\mathcal{R}_T] \le 2n^{3/2} \sqrt{T \log 2}$$

**Theorem 4.** In the bandit setting, if  $\eta = \sqrt{\frac{\log 2}{9n^2T}}$  and  $\gamma = 4n^2\eta$ , Exp2 with uniform exploration on  $\{0,1\}^n$  attains the regret bound:

$$\mathbb{E}[\mathcal{R}_T] \le 6n^2 \sqrt{T \log 2}$$

#### 2.2 PolyExp

Algorithm: PolyExp

**Parameters:** Learning Rate  $\eta$ 

Let  $x_{i,1} = 1/2$  for all  $i \in [n]$ . For each round t = 1, 2, ..., T:

- 1. Sample  $X_t$  as below. Play  $X_t$  and incur the loss  $X_t^{\top} l_t$ .
  - (a) Full information:  $X_{i,t} \sim Bernoulli(x_{i,t})$
  - (b) Bandit: With probability  $1-\gamma$  sample  $X_{i,t} \sim Bernoulli(x_{i,t})$  and with probability  $\gamma$  sample  $X_t \sim \mu$
- 2. See Feedback and construct  $\tilde{l}_t$ 
  - (a) Full information:  $\tilde{l}_t = l_t$
  - (b) Bandit:  $\tilde{l}_t = P_t^{-1} X_t X_t^{\top} l_t$ , where  $P_t = (1 \gamma) \Sigma_t + \gamma \mathbb{E}_{X \sim \mu} [XX^{\top}]$ . The matrix  $\Sigma_t$  is  $\Sigma_t[i,j] = x_{i,t} x_{j,t}$  if  $i \neq j$  and  $\Sigma_t[i,i] = x_i$  for all  $i,j \in [n]$
- 3. Update for all  $i \in [n]$ :

$$x_{i,t+1} = \frac{1}{1 + \exp(\eta \sum_{\tau=1}^{t} \tilde{l}_{i,\tau})} \text{ or equivalently}$$

$$x_{i,t+1} = \frac{x_{i,t}}{x_{i,t} + (1 - x_{i,t}) \exp(\eta \tilde{l}_{i,t})}$$

To get a polynomial time algorithm, we replace the sampling and update steps with polynomial time operations. PolyExp uses n parameters represented by the vector  $x_t$ . Each element of  $x_t$  corresponds to the mean of a Bernoulli distribution. It uses the product of these Bernoulli distributions to sample  $X_t$  and uses the update equation mentioned in step 3 to obtain  $x_{t+1}$ .

In the Bandit setting, we can sample  $X_t$  by sampling from  $\prod_{i=1}^n Bernoulli(x_{t,i})$  with probability  $1-\gamma$  and sampling from  $\mu$  with probability  $\gamma$ . As we use the uniform distribution over  $\{0,1\}^n$  for exploration, this is equivalent to sampling from  $\prod_{i=1}^n Bernoulli(1/2)$ . So we can sample from  $\mu$  in polynomial time. The matrix  $P_t = \mathbb{E}_{X \sim q_t}[XX^\top] = (1-\gamma)\Sigma_t + \gamma\Sigma_{\mu}$ . Here  $\Sigma_t$  and  $\Sigma_{\mu}$  are the covariance matrices when  $X \sim \prod_{i=1}^n Bernoulli(x_{t,i})$  and  $X \sim \prod_{i=1}^n Bernoulli(1/2)$  respectively. It can be verified that  $\Sigma_t[i,j] = x_{i,t}x_{j,t}, \Sigma_{\mu}[i,j] = 1/4$  if  $i \neq j$  and  $\Sigma_t[i,i] =$ 

 $x_i, \Sigma_{\mu}[i,i] = 1/2$  for all  $i,j \in [n]$ . So  $P_t^{-1}$  can be computed in polynomial time.

#### 2.3 Equivalence of Exp2 and PolyExp

We prove that running Exp2 is equivalent to running PolyExp.

**Theorem 5.** Under linear losses  $\tilde{l}_t$ , Exp2 on  $\{0,1\}^n$  is equivalent to PolyExp. At round t, The probability that PolyExp chooses X is  $\prod_{i=1}^n (x_{i,t})^{X_i} (1-x_{i,t})^{(1-X_i)}$  where  $x_{i,t} = (1 + \exp(\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau}))^{-1}$ . This is equal to the probability of Exp2 choosing X at round t, ie:

$$\prod_{i=1}^{n} (x_{i,t})^{X_i} (1 - x_{i,t})^{(1 - X_i)} = \frac{\exp(-\eta \sum_{\tau=1}^{t-1} X^{\top} \tilde{l}_{\tau})}{Z_t}$$

where 
$$Z_t = \sum_{Y \in \{0,1\}^n} \exp(-\eta \sum_{\tau=1}^{t-1} Y^{\top} \tilde{l}_{\tau}).$$

At every round, the probability distribution  $p_t$  in Exp2 is the same as the product of Bernoulli distributions in PolyExp. Lemma 15 is crucial in proving equivalence between the two algorithms. In a strict sense, Lemma 15 holds only because our decision set is the entire  $\{0,1\}^n$  hypercube. The vector  $\tilde{l}_t$  computed by Exp2 and PolyExp will be same. Hence, Exp2 and PolyExp are equivalent. Note that this equivalence is true for any sequence of losses as long as they are linear.

### 2.4 Online Mirror Descent

We present the OMD algorithm for linear losses on general finite decision sets. Our exposition is adapted from [5] and [17]. Let  $\mathcal{X} \subset \mathbb{R}^n$  be an open convex set and  $\bar{\mathcal{X}}$  be the closure of  $\mathcal{X}$ . Let  $\mathcal{K} \in \mathbb{R}^d$  be a finite decision set such that  $\bar{\mathcal{X}}$  is the convex hull of  $\mathcal{K}$ . The following definitions will be useful in presenting the algorithm.

**Definition 6.** Legendre Function: A continuous function  $R: \bar{\mathcal{X}} \to \mathbb{R}$  is Legendre if

1. R is strictly convex and has continuous partial derivatives on  $\mathcal{X}$ .

2. 
$$\lim_{x \to \bar{\mathcal{X}}/\mathcal{X}} \|\nabla R(x)\| = +\infty$$

**Definition 7.** Legendre-Fenchel Conjugate: Let  $R: \bar{\mathcal{X}} \to \mathbb{R}$  be a Legendre function. The Legendre-Fenchel conjugate of R is:

$$R^{\star}(\theta) = \sup_{x \in \mathcal{X}} (x^{\top}\theta - R(x))$$

**Definition 8.** Bregman Divergence: Let R(x) be a Legendre function, the Bregman divergence  $D_R : \bar{\mathcal{X}} \times \mathcal{X} \to \mathbb{R}$  is:

$$D_R(x||y) = R(x) - R(y) - \nabla R(y)^{\top} (x - y)$$

**Algorithm:** Online Mirror Descent with Regularization R(x)

**Parameters:** Learning Rate  $\eta$ 

Pick  $x_1 = \arg\min_{x \in \bar{\mathcal{X}}} R(x)$ . For each round t = 1, 2, ..., T:

- 1. Let  $p_t$  be a distribution on  $\mathcal{K}$  such that  $\mathbb{E}_{X \sim p_t}[X] = x_t$ . Sample  $X_t$  as below and incur the loss  $X_t^{\top} l_t$ 
  - (a) Full information:  $X_t \sim p_t$
  - (b) Bandit: With probability  $1 \gamma$  sample  $X_t \sim p_t$  and with probability  $\gamma$  sample  $X_t \sim \mu$ .
- 2. See Feedback and construct  $\tilde{l}_t$ 
  - (a) Full information:  $\tilde{l}_t = l_t$
  - (b) Bandit:  $\tilde{l}_t = P_t^{-1} X_t X_t^{\top} l_t$ , where  $P_t = (1 \gamma) \mathbb{E}_{X \sim p_t} [XX^{\top}] + \gamma \mathbb{E}_{X \sim \mu} [XX^{\top}].$
- 3. Let  $y_{t+1}$  satisfy:  $y_{t+1} = \nabla R^* (\nabla R(x_t) \eta \tilde{l}_t)$
- 4. Update  $x_{t+1} = \arg\min_{x \in \bar{\mathcal{X}}} D_R(x||y_{t+1})$

#### 2.5 Equivalence of PolyExp and Online Mirror Descent

For our problem,  $\mathcal{K} = \{0,1\}^n$ ,  $\bar{\mathcal{X}} = [0,1]^n$  and  $\mathcal{X} = (0,1)^n$ . We use entropic regularization:

$$R(x) = \sum_{i=1}^{n} x_i \log x_i + (1 - x_i) \log(1 - x_i)$$

This function is Legendre. The OMD algorithm does not specify the probability distribution  $p_t$  that should be used for sampling. The only condition that needs to be met is  $\mathbb{E}_{X \sim p_t}[X] = x_t$ , i.e,  $x_t$  should be expressed as a convex combination of  $\{0,1\}^n$  and probability of picking X is its coefficient in the linear decomposition of  $x_t$ . An easy way to achieve this is by using Bernoulli sampling like in PolyExp. Hence, we have the following equivalence theorem:

**Theorem 9.** Under linear losses  $l_t$ , OMD on  $[0,1]^n$  with Entropic Regularization and Bernoulli Sampling is equivalent to PolyExp. The sampling procedure of PolyExp satisfies  $\mathbb{E}[X_t] = x_t$ . The update of OMD with Entropic Regularization is the same as PolyExp.

In the bandit case, if we use Bernoulli sampling,  $\mathbb{E}_{X \sim p_t}[XX^{\top}] = \Sigma_t$ .

#### 2.6 Regret of PolyExp via OMD analysis

Since OMD and PolyExp are equivalent, we can use the standard analysis tools of OMD to derive a regret bound for PolyExp. These regret bounds are under the  $L_{\infty}$  assumption.

**Theorem 10.** In the full information setting, if  $\eta = \sqrt{\frac{\log 2}{T}}$ , PolyExp attains the regret bound:

$$E[\mathcal{R}_T] \le 2n\sqrt{T\log 2}$$

We have shown that Exp2 on  $\{0,1\}^n$  with linear losses is equivalent to PolyExp. We have also shown that PolyExp's regret bounds are tighter than the regret bounds that we were able to derive for Exp2 in full information. This naturally implies an improvement for Exp2's regret bounds as it is equivalent to Poly-Exp and must attain the same regret. However, in the bandit case PolyExp does not improve Exp2's regret bound. So, it has the same regret as Exp2 stated in Theorem 5.

#### 2.7 Follow The Leader

PolyExp can be shown to be equivalent to a Follow The Regularized Leader(FTRL) and a Follow The Perturbed Leader(FTPL) algorithm. The FTRL algorithm can be easily deduced from the OMD algorithm as the Bregman projection step in OMD is not necessary in the case of entropic regularization. Hence, to derive the FTRL algorithm, we replace steps 3 and 4 in OMD with the following update step:

$$x_{t+1} = \arg\min_{x \in [0,1]^n} \left[ \eta \sum_{\tau=1}^t \tilde{l}_{\tau}^{\top} x + R(x) \right]$$

In the FTPL algorithm, we draw a random vector v from some fixed distribution at each time step. We then choose the point which minimizes the sum of all previous losses and the perturbation vector v, by solving a simple linear optimization problem.

$$X_{t+1} = \arg\min_{x \in \{0,1\}^n} \left[ \eta \sum_{\tau=1}^t \hat{l}_{\tau}^{\top} x + v^{\top} x \right]$$

The FTPL algorithm is quite easy to implement in the full information setting as it folds the update and sampling steps into one computationally efficient step.

In the bandit setting however, we need to know the distribution  $p_t(X)$ , which is defined as follows:

$$p_t(X) = \Pr\left(X = \arg\min_{\{0,1\}^n} \left[ \eta \sum_{\tau=1}^t \hat{l}_{\tau}^{\top} x + v^{\top} x \right] \right)$$

This distribution may not always be computable.

We choose F(x) to be the product of logistic distributions, ie distributions with CDF  $\Pr(x \leq \theta) = (1 + \exp(-\theta))^{-1}$ . In this case, we show that this FTPL is equivalent to PolyExp. Also, the distribution  $p_t(X)$  has a simple closed form and  $\mathbb{E}_{X \sim p_t}[XX^{\top}] = \Sigma_t$ .

**Algorithm:** Follow the Perturbed Leader with Cumulative Distribution Function F(x)

**Parameters:** Learning Rate  $\eta$ 

Pick  $X_1 = \arg\min_{X \in \{0,1\}^n} v^\top x$ , where v is drawn from distribution having CDF F(x). For each round t = 1, 2, ..., T:

- 1. (a) Full information: Play  $X_t$ 
  - (b) Bandit: With probability  $1 \gamma$  play  $X_t$  and with probability  $\gamma$  play  $X_t \sim \mu$ .
- 2. See Feedback and construct  $\tilde{l}_t$ 
  - (a) Full information:  $\tilde{l}_t = l_t$
  - (b) Bandit:  $\tilde{l}_t = P_t^{-1} X_t X_t^{\top} l_t$ , where  $P_t = (1 \gamma) \mathbb{E}_{X \sim p_t} [XX^{\top}] + \gamma \mathbb{E}_{X \sim \mu} [XX^{\top}]$ .
- 3. Update

$$X_{t+1} = \arg\min_{x \in \{0,1\}^n} \left[ \eta \sum_{\tau=1}^t \tilde{l}_{\tau}^{\top} x + v^{\top} x \right]$$

**Theorem 11.** Under linear losses  $\tilde{l}_t$ , FTRL with Entropic regularization and Bernoulli sampling, and FTPL with iid Logistic perturbations are equivalent to PolyExp.

# 3 Comparison of Exp2's and PolyExp's regret proofs

Consider the results we have shown so far. We proved that PolyExp and Exp2 on the hypercube are equivalent. So logically, they should have the same regret bounds. But, our proofs say that PolyExp's regret is  $O(\sqrt{n})$  better than Exp2's regret. What is the reason for this apparent discrepancy?

The answer lies in the choice of  $\eta$  and the application of the inequality  $e^{-x} \leq 1 + x - x^2$  in our proofs. This inequality is valid when  $x \geq -1$ . When analyzing Exp2, x is  $\eta X^{\top} l_t = \eta L_t(X)$ . So, to satisfy the constraints  $x \geq -1$  we enforce that  $|\eta L_t(X)| \leq 1$ . Since  $|L_t(X)| \leq n$ ,  $\eta \leq 1/n$ . When analyzing PolyExp, x is  $\eta l_{t,i}$  and we enforce that  $|\eta l_{t,i}| \leq 1$ . Since we already assume  $|l_{t,i}| \leq 1$ , we get that  $\eta \leq 1$ . PolyExp's proof technique allows us to find a better  $\eta$  and achieve a better regret bound.

#### 4 Lower bounds

We state the following lower bounds that establish the least amount of regret that any algorithm must incur. The lower bounds match the upper bounds of PolyExp

proving that it is regret optimal. The proofs of the lower bounds can be found in the appendix.

**Theorem 12.** For any learner there exists an adversary producing  $L_{\infty}$  losses such that the expected regret in the full information setting is:

$$\mathbb{E}\left[\mathcal{R}_T\right] = \Omega\left(n\sqrt{T}\right).$$

**Theorem 13.** For any learner there exists an adversary producing  $L_{\infty}$  losses such that the expected regret in the Bandit setting is:

$$\mathbb{E}\left[\mathcal{R}_T\right] = \Omega\left(n^{3/2}\sqrt{T}\right).$$

## 5 $\{-1,+1\}^n$ Hypercube Case

Full information and bandit algorithms which work on  $\{0,1\}^n$  can be modified to work on  $\{-1,+1\}^n$ . The general strategy is as follows:

- 1. Sample  $X_t \in \{0,1\}^n$ , play  $Z_t = 2X_t \mathbf{1}$  and incur loss  $Z_t^{\top} l_t$ .
  - (a) Full information:  $X_t \sim p_t$
  - (b) Bandit:  $X_t \sim q_t = (1 \gamma)p_t + \gamma\mu$
- 2. See feedback and construct  $\tilde{l}_t$ 
  - (a) Full information:  $\tilde{l}_t = l_t$
  - (b) Bandit:  $\tilde{l}_t = P_t^{-1} Z_t Z_t^{\top} l_t$  where  $P_t = \mathbb{E}_{X \sim q_t}[(2X \mathbf{1})(2X \mathbf{1})^{\top}]$
- 3. Update algorithm using  $2\tilde{l}_t$

**Theorem 14.** Exp2 on  $\{-1, +1\}^n$  using the sequence of losses  $l_t$  is equivalent to PolyExp on  $\{0, 1\}^n$  using the sequence of losses  $2\tilde{l}_t$ . Moreover, the regret of Exp2 on  $\{-1, 1\}^n$  will equal the regret of PolyExp using the losses  $2\tilde{l}_t$ .

Hence, using the above strategy, PolyExp can be run in polynomial time on  $\{-1,1\}^n$  and since the losses are doubled its regret only changes by a constant factor.

#### 6 Conclusions

For linear losses, we show that the Exp2 algorithm can be run on the hypercube in polynomial time using PolyExp. We also show equivalences to OMD, FTRL and FTPL. We improve Exp2's regret bound in full information using OMD's analysis, showing that it is minimax optimal. In the bandit setting, the regret bound could not be improved using this analysis. It remains to show how to achieve the minimax optimal regret in the bandit setting under  $L_{\infty}$  losses.

#### 7 Proofs

#### 7.1 Equivalence to Exp2

**Lemma 15.** For any sequence of losses  $l_t$ , the following is true for all t = 1, 2, ..., T:

$$\prod_{i=1}^{n} (1 + \exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})) = \sum_{Y \in \{0,1\}^n} \exp(-\eta \sum_{\tau=1}^{t-1} Y^{\top} \tilde{l}_{\tau})$$

Proof. Consider  $\prod_{i=1}^{n} (1 + \exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau}))$ . It is a product of n terms, each consisting of 2 terms, 1 and  $\exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})$ . On expanding the product, we get a sum of  $2^n$  terms. Each of these terms is a product of n terms, either a 1 or  $\exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})$ . If it is 1, then  $Y_i = 0$  and if it is  $\exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})$ , then  $Y_i = 1$ . So.

$$\begin{split} \prod_{i=1}^{n} (1 + \exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})) &= \sum_{Y \in \{0,1\}^n} \prod_{i=1}^{n} \exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})^{Y_i} \\ &= \sum_{Y \in \{0,1\}^n} \prod_{i=1}^{n} \exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau}Y_i) \\ &= \sum_{Y \in \{0,1\}^n} \exp(-\eta \sum_{\tau=1}^{t-1} Y^\top \tilde{l}_\tau) \end{split}$$

**Theorem 5.** Under linear losses  $\tilde{l}_t$ , Exp2 on  $\{0,1\}^n$  is equivalent to PolyExp. At round t, The probability that PolyExp chooses X is  $\prod_{i=1}^n (x_{i,t})^{X_i} (1-x_{i,t})^{(1-X_i)}$  where  $x_{i,t} = (1 + \exp(\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau}))^{-1}$ . This is equal to the probability of Exp2 choosing X at round t, ie:

$$\prod_{i=1}^{n} (x_{i,t})^{X_i} (1 - x_{i,t})^{(1 - X_i)} = \frac{\exp(-\eta \sum_{\tau=1}^{t-1} X^{\top} \tilde{l}_{\tau})}{Z_t}$$

where  $Z_t = \sum_{Y \in \{0,1\}^n} \exp(-\eta \sum_{\tau=1}^{t-1} Y^{\top} \tilde{l}_{\tau}).$ 

*Proof.* The proof is via straightforward substitution of the expression for  $x_{i,t}$  and applying Lemma 15.

$$\begin{split} &\prod_{i=1}^{n} (x_{i,t})^{X_i} (1-x_{i,t})^{(1-X_i)} = \prod_{i=1}^{n} \frac{\left(\exp(\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})\right)^{1-X_i}}{1+\exp(\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})} \\ &= \prod_{i=1}^{n} \frac{\exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})^{X_i}}{1+\exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau})} \\ &= \frac{\prod_{i=1}^{n} \exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau}X_i)}{\prod_{i=1}^{n} (1+\exp(-\eta \sum_{\tau=1}^{t-1} \tilde{l}_{i,\tau}))} \\ &= \frac{\exp(-\eta \sum_{\tau=1}^{t-1} X^{\top} \tilde{l}_{i,\tau})}{\sum_{Y \in \{0,1\}^n} \exp(-\eta \sum_{\tau=1}^{t-1} Y^{\top} \tilde{l}_{\tau})} \end{split}$$

#### 7.2 Equivalence to OMD

**Lemma 16.** The Fenchel Conjugate of  $R(x) = \sum_{i=1}^{n} x_i \log x_i + (1-x_i) \log(1-x_i)$  is:

$$R^{\star}(\theta) = \sum_{i=1}^{n} \log(1 + \exp(\theta_i))$$

*Proof.* Differentiating  $x^{\top}\theta - R(x)$  wrt  $x_i$  and equating to 0:

$$\theta_i - \log x_i + \log(1 - x_i) = 0$$

$$\frac{x_i}{1 - x_i} = \exp(\theta_i)$$

$$x_i = \frac{1}{1 + \exp(-\theta_i)}$$

Substituting this back in  $x^{\top}\theta - R(x)$ , we get  $R^{\star}(\theta) = \sum_{i=1}^{n} \log(1 + \exp(\theta_i))$ . It is also straightforward to see that  $\nabla R^{\star}(\theta)_i = (1 + \exp(-\theta_i))^{-1}$ 

**Theorem 9.** Under linear losses  $\tilde{l}_t$ , OMD on  $[0,1]^n$  with Entropic Regularization and Bernoulli Sampling is equivalent to PolyExp. The sampling procedure of PolyExp satisfies  $\mathbb{E}[X_t] = x_t$ . The update of OMD with Entropic Regularization is the same as PolyExp.

*Proof.* It is easy to see that  $E[X_{i,t}] = \Pr(X_{i,t} = 1) = x_{i,t}$ . Hence  $E[X_t] = x_t$ .

The update equation is  $y_{t+1} = \nabla R^*(\nabla R(x_t) - \eta \tilde{l}_t)$ . Evaluating  $\nabla F$  and using  $\nabla R^*$  from Lemma 16:

$$y_{t+1,i} = \frac{1}{1 + \exp(-\log(x_{t,i}) + \log(1 - x_{t,i}) + \eta \tilde{l}_{t,i})}$$

$$= \frac{1}{1 + \frac{1 - x_{t,i}}{x_{t,i}} \exp(\eta \tilde{l}_{t,i})}$$

$$= \frac{x_{t,i}}{x_{t,i} + (1 - x_{t,i}) \exp(\eta \tilde{l}_{t,i})}$$

Since  $0 \le (1 + \exp(-\theta))^{-1} \le 1$ , we have that  $y_{i,t+1}$  is always in [0,1]. Bregman projection step is not required. So we have  $x_{i,t+1} = y_{i,t+1}$  which gives the same update as PolyExp.

#### 7.3 Equivalence to FTRL and FTPL

**Theorem 11.** Under linear losses  $\tilde{l}_t$ , FTRL with Entropic regularization and Bernoulli sampling, and FTPL with iid Logistic perturbations are equivalent to PolyExp.

*Proof.* Using  $R(x) = \sum_{i=1}^{n} x_i \log x_i + (1 - x_i) \log(1 - x_i)$  in FTRL, we can solve the optimization problem

exactly:

$$\nabla_i \left( \eta \sum_{\tau=1}^t l_\tau^\top x + R(x) \right) = \eta \sum_{\tau=1}^t l_{i,\tau} + \log \frac{x_i}{1 - x_i} = 0$$

$$\implies x_i = \frac{1}{1 + \exp(\eta \sum_{\tau=1}^t l_{i,\tau})}$$

This is the same update equation as PolyExp.

For FTPL, the optimization problem outputs  $X_i = 1$  if  $\eta \sum_{\tau=1}^{t} l_{i,\tau} + v_i \leq 0$  and  $X_i = 0$  otherwise. As v is a vector of iid random variables, we can conclude that  $X_{i,t+1}$  are also independent. We have that:

$$\Pr(X_{i,t+1} = 1) = \Pr(\eta \sum_{\tau=1}^{t} l_{i,\tau} + v_i \le 0)$$

$$= \Pr(v_i \le -\eta \sum_{\tau=1}^{t} l_{i,\tau})$$

$$= \frac{1}{1 + \exp(\eta \sum_{\tau=1}^{t} l_{i,\tau})}$$

To obtain the last equality, we use the fact that  $v_i$  is drawn from the Logistic distribution. We can see this is equal to the probability of picking  $X_{i,t+1} = 1$  in the PolyExp algorithm.

#### 7.4 PolyExp Full Information Regret Proof

**Lemma 17** (see Theorem 5.5 in [5]). For any  $x \in \bar{\mathcal{X}}$ , OMD with Legendre regularizer R(x) with domain  $\bar{\mathcal{X}}$  and  $R^*$  is differentiable on  $\mathbb{R}^n$  satisfies:

$$\sum_{t=1}^{T} x_{t}^{\top} l_{t} - \sum_{t=1}^{T} x^{\top} l_{t} \leq \frac{R(x) - R(x_{1})}{\eta} + \frac{1}{\eta} \sum_{t=1}^{T} D_{R^{\star}} (\nabla R(x_{t}) - \eta l_{t} || \nabla R(x_{t}))$$

**Lemma 18.** If  $|\eta l_{t,i}| \leq 1$  for all  $t \in [T]$  and  $i \in [n]$ , OMD with entropic regularizer  $R(x) = \sum_{i=1}^{n} x_i \log x_i + (1-x_i) \log(1-x_i)$  satisfies for any  $x \in [0,1]^n$ ,:

$$\sum_{t=1}^{T} x_t^{\top} l_t - \sum_{t=1}^{T} x^{\top} l_t \le \frac{n \log 2}{\eta} + \eta \sum_{t=1}^{T} x_t^{T} l_t^2$$

*Proof.* We start from Lemma 17. Using the fact that  $x \log(x) + (1-x) \log(1-x) \ge -\log 2$ , we get  $R(x) - R(x_1) \le n \log 2$ . Next we bound the Bregmen term using Lemma 16

$$D_{R^{\star}}(\nabla R(x_t) - \eta l_t || \nabla R(x_t)) = R^{\star}(\nabla R(x_t) - \eta l_t)$$
$$- R^{\star}(\nabla R(x_t)) + \eta l_t^{\top} \nabla R^{\star}(\nabla R(x_t))$$

Using that fact that  $\nabla R^* = (\nabla R)^{-1}$ , the last term is  $\eta x_t^{\mathsf{T}} l_t$ . The first two terms can be simplified as:

$$R^{*}(\nabla R(x_{t}) - \eta l_{t}) - R^{*}(\nabla R(x_{t}))$$

$$= \sum_{i=1}^{n} \log \frac{1 + \exp(\nabla R(x_{t})_{i} - \eta l_{t,i})}{1 + \exp(\nabla R(x_{t})_{i})}$$

$$= \sum_{i=1}^{n} \log \frac{1 + \exp(-\nabla R(x_{t})_{i} + \eta l_{t,i})}{\exp(\eta l_{t,i})(1 + \exp(-\nabla R(x_{t})_{i})}$$

Using the fact that  $\nabla R(x_t)_i = \log x_i - \log(1 - x_i)$ :

$$= \sum_{i=1}^{n} \log \frac{x_{t,i} + (1 - x_{t,i}) \exp(\eta l_{t,i})}{\exp(\eta l_{t,i})}$$
$$= \sum_{i=1}^{n} \log(1 - x_{t,i} + x_{t,i} \exp(-\eta l_{t,i}))$$

Using the inequality:  $e^{-x} \le 1 - x + x^2$  when  $x \ge -1$ . So when  $|\eta l_{t,i}| \le 1$ :

$$\leq \sum_{i=1}^{n} \log(1 - \eta x_{t,i} l_{t,i} + \eta^2 x_{t,i} l_{t,i}^2)$$

Using the inequality:  $\log(1-x) \le -x$ 

$$\leq -\eta x_t^\top l_t + \eta^2 x_t^\top l_t^2$$

The Bregman term can be bounded by  $-\eta x_t^{\top} l_t + \eta^2 x_t^{\top} l_t^2 + \eta x_t^{\top} l_t = \eta^2 x_t^{\top} l_t^2$  Hence, we have:

$$\sum_{t=1}^{T} x_t^{\top} l_t - \sum_{t=1}^{T} x^{\top} l_t \le \frac{n \log 2}{\eta} + \eta \sum_{t=1}^{T} x_t^{T} l_t^2$$

**Theorem 10.** In the full information setting, if  $\eta = \sqrt{\frac{\log 2}{T}}$ , PolyExp attains the regret bound:

$$E[\mathcal{R}_T] \le 2n\sqrt{T\log 2}$$

*Proof.* Applying expectation with respect to the randomness of the player to definition of regret, we get:

$$\mathbb{E}[\mathcal{R}_T] = \mathbb{E}[\sum_{t=1}^T X_t^\top l_t - \min_{X^* \in \{0,1\}^n} \sum_{t=1}^T X^{*\top} l_t]$$
$$= \sum_{t=1}^T x_t^\top l_t - \min_{X^* \in \{0,1\}^n} \sum_{t=1}^T X^{*\top} l_t$$

Applying Lemma 18, we get  $E[\mathcal{R}_T] \leq \frac{n \log 2}{\eta} + \eta \sum_{t=1}^T x_t^T l_t^2$ . Using the fact that  $|l_{i,t}| \leq 1$ , we get  $\sum_{t=1}^T x_t^T l_t^2 \leq nT$ .

$$\mathbb{E}[\mathcal{R}_T] \le \eta nT + \frac{n\log 2}{\eta}$$

Optimizing over the choice of  $\eta$ , we get that the regret is bounded by  $2n\sqrt{T \log 2}$  if we choose  $\eta = \sqrt{\frac{\log 2}{T}}$ .  $\square$ 

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