

# Analysis of cognitive states during bodily exploration of mathematical concepts in visually impaired children

Erica Volta  
*InfoMus Lab - DIBRIS Department*  
University of Genova  
Genova, Italy  
erica.volta@edu.unige.it

Radoslaw Niewiadomski  
*Istituto Italiano di Tecnologia*  
Genova, Italy  
radoslaw.niewiadomski@iit.it

Temitayo Olugbade  
*UCLIC*  
University College of London  
London, UK  
temitayo.olugbade.13@ucl.ac.uk

Carla Gilio  
*Istituto Chiossone*  
Genova, Italy  
gilio@chiossone.it

Elena Cocchi  
*Istituto Chiossone*  
Genova, Italy  
cocchi@chiossone.it

Nadia Berthouze  
*UCLIC*  
University College of London  
London, UK  
n.berthouze@ucl.ac.uk

Monica Gori  
*U-VIP*  
*Istituto Italiano di Tecnologia*  
Genova, Italy  
monica.gori@iit.it

Gualtiero Volpe  
*InfoMus Lab - DIBRIS Department*  
University of Genova  
Genova, Italy  
gualtiero.volpe@unige.it

**Abstract**—When developing children interaction systems, such as serious games in educational technology context, it is important to take into account and address relevant cognitive and emotional child’s experiences that may influence learning outcomes. Some works were done to analyze and automatically recognize these cognitive and affective states from nonverbal expressive behaviors. However, there is a lack of knowledge about visually impaired children and their body language to convey those states during learning tasks. In this paper, we present an analysis of nonverbal expressive behaviors of both blind and low-vision children, aiming at understanding what type of body communication can be an indicator of two cognitive states: engagement and confidence. In the study we consider the data collected along the EU-ICT H2020 weDRAW Project, while children were asked to solve mathematical tasks with their body. For such dataset, we propose a list of 31 nonverbal behaviors, annotated both by visually impaired rehabilitators and naive observers. In the last part of the paper, we propose a preliminary study on automatic recognition of engagement and confidence states from 2D positional data. The classification results are up to 0.71 (F-score) on three class classification task.

**Index Terms**—visually impaired children, engagement, confidence, learning, cognition, nonverbal behaviors, classification, machine learning

## I. INTRODUCTION

Nonverbal communication is the first stage of communication development [39], representing a fundamental part of what people use to convey information when they interact and communicate with each other [22]. Since the visual modality is crucial to develop social and communication abilities, visually impaired children may show different nonverbal behaviors [44]. In this paper, we focus on nonverbal indicators of cognitive states in blind and low impaired children in mathematical

task-oriented settings. The work is realized in the framework of the weDRAW Project that aimed at developing adaptive multisensory technologies to enhance comprehension of mathematical concepts in primary school children. According to the project objectives, a unique technology design will suit both typically developed and visual- or learning- impaired (e.g. blind, or dyslexic ) children’s needs. In this framework, a set of serious games has been developed to teach children the basic concepts of mathematics. Such systems would benefit from an adaptive feedback based on child’s specific learning needs and her involvement in the task, e.g., with automatic measurement of her/his cognitive engagement and confidence. While several works exist on the recognition of cognitive states (e.g., engagement in [25], [34]) they do not focus on nonverbal behaviors of visually impaired subjects. In next sections, Section II, Section III, Section V, starting from state-of-the-art on nonverbal communication in visually impaired children and from weDRAW Project dataset, we describe relevant nonverbal cues of engagement and confidence for this population. We then introduce the annotation procedure we followed in this study in Section VI, and we present our preliminary work on automatic classification of these states from video in Section VII.

## II. BACKGROUND: GESTURES AND UNCONSTRAINED BODY MOVEMENT IN VISUALLY IMPAIRED CHILDREN

The level of visual functioning can greatly influence child early development. A visual disability may therefore lead to developmental delays, especially if an early intervention does not take place [47]. Developmental delays can have a negative effect on child’s participation both in rehabilitation and educational settings. In addition, poorer immediate problem-solving



Fig. 1. Picture of a blind child exploring angles with his arms during the weDRAW data collection

[12] and mathematical skills [28] have been found in children with a visual impairment.

Nonverbal behaviors in visually impaired children were expected to be semantically different from those of typically developing ones. For these reasons, considering the state-of-the-art, it is relevant to research to what extent visual impairment may affect the development of nonverbal communication patterns and the ability to produce such patterns in various social interactions. For instance, head orientation, proxemics and distance from the objects (e.g. walls) might have different meaning [44] when displayed by visually impaired individuals. Iverson and Golden-Meadow [24], for example, discussed gestures used by congenitally blind children who never saw gestures before nor experienced their communicative functions. Results showed that visually impaired children produced gestures but not in all situations as it was for sighted and blindfolded ones. The study suggested that gestures provide speaker with functions that are independent by the listeners.

### III. ENGAGEMENT AND CONFIDENCE BEHAVIORS IN CHILDREN

Important developmental and social changes occur in children starting from the age of 6. Through these years, they contribute to create a personal identity, a self-concept, and an orientation toward achievement that will be relevant for shaping their success in school, work, and life. In this work, we investigate confidence and engagement in primary school children with visual impairments during embodied mathematical tasks solving. The educational literature shows (see [36] for a review) that in interactive learning task-oriented environment it is crucial to be able to recognize these two cognitive states in order to avoid the potentially negative outcomes of learning experience. The lack of engagement, or low self-confidence might lead to negative emotions such as boredom or anxiety [9] and, even to the complete abandon of the task. Below, we provide the definitions of the two states as they were given to the annotators:

*Engagement* can be considered a cognitive construct, based on the interrelation between behavior, cognition and emotion.

In young children, it can be deduced interacting with teachers, other peers and materials in a way that is appropriate from a developmental and contextual point of view [29], [46]. In learning studies, engagement is often defined as the amount of energy that the student devotes to learning experience. In literature, research highlighted three different types of students' engagement: cognitive, emotional, and behavioral [17]. Cognitive engagement is related to how much students invested cognitive efforts and resources in learning; the emotional one considered students' motivation and commitment; instead behavioral engagement deals with students on-task behaviors. [33].

On the other hand, *confidence* results from the appreciation of one's own abilities or qualities. Scientific literature [13], [38] has corroborated Erikson's idea [14] that feelings of competence and personal esteem are of central importance to a child's well-being [23]. For example, children who do not consider themselves competent in academic, social or other fields (such as athletics, music, theatre or scouting) during their elementary school years report depression and social isolation more often than their peers [11]. Self-confidence is closely related to the task for which the solution is being sought and can also be observed in short intervals of time.

Cognitive engagement has a great impact on learning outcomes and this is why it is such considered also in e-learning technology research [15]. Analogously, self-confidence is one of the states that teachers used to monitor children learning outcomes [19].

### IV. AUTOMATIC RECOGNITION OF ENGAGEMENT AND CONFIDENCE

Several works were proposed in the literature to computationally address the level of engagement from nonverbal behaviors [27]. Most of them focused on engagement detection or estimation in human-human [16], human-virtual [31] agent or human-robot [3] dyadic or group interactions from gaze [31], back-channels [41] and facial expressions [20]. Frank and colleagues [16] proposed the Engagement Classification Framework composed of six states from "disengagement" to "involved action". Their framework implementation detects the 3 levels of engagement from 3D data by detecting a set of features of the upper body movements such as hand vertical positions and speed, leaning and body direction as well as specific postures. In [26], a multimodal approach was proposed to detect levels of engagement, using nonverbal features extracted from audio and visual data, and using rank learning. Finally, recent works included the application of deep learning techniques to compute intensity of engagement from video in e-learning tasks (see, e.g., papers of the Engagement in the Wild track of EmotiW 2018 Challenge at ICMI conference<sup>1</sup>).

In the context of single-user activity, Ge and colleagues [18] proposed model for engagement / disengagement detection in autistic children from body movements. They detected child's concentration on a given task (e.g. playing a game

<sup>1</sup><https://sites.google.com/view/emotiw2018>

on a tablet) by extracting a set of features from kinematics data obtained from a RGB-D camera and applying machine learning techniques. Several features were computed using angles and distances between child's joints and an object of interest (e.g., table).

Using standard algorithms such as SVM, Random Forest, and AdaBoost they achieved a recognition rate up to 97% for two-class pattern recognition problem. Shaker and Shaker [43] detected the level of engagement from nonverbal cues in a context of single-user video game. They extracted several low-level visual features, and combined them with high-level facial expressions labels. Next, they apply Neuroevolutionary Preference Learning (NPL) to obtain the accuracy of 96%.

Computational approaches of confidence level are more rare. Most frequently researchers focused similar topics such as on leadership detection in multi-user scenarios, e.g., social games [4], and self-efficacy in physical rehabilitation [35]. We are not unaware, at this stage, of any existing model for the recognition of confidence level from full body cues in context of single-user task in education (for physical rehabilitation context, see [35]).

## V. THE WEDRAW DATASET

Body movements play multiple roles in weDRAW project: first, it is a means both for the child and the teacher to explore, construct and understand some arithmetical and geometrical concepts; second: it allows an observer (either the teacher or the technology) to gain insights on child's cognitive and affective processes that affect learning. In particular, in this paper we only focus on its second aspect, i.e., a communication channel allowing humans to express and perceive implicit high-level messages, such emotional and cognitive states or social boundaries. Thus, it is out of the scope of this paper to recognize whether the child was able to perform correctly the task through the appropriate choice of gestures and poses.

### A. Dataset and Participant Profile

For the purpose of the work we created, with the participation of visually impaired children, the VI-weDraw dataset which comprises body movement data, captured during mathematical problem-solving specifically designed for the experimental setting. The tasks were based on project premises and comprised: angles, symmetry and reflection, considered as a type of isometric transformation of shapes. The dataset consists of two synchronized video recordings (frontal and lateral) with corresponding audio data. All the children recruited for the experiment were studying in Genoa and participating in a rehabilitation programme at Chiossone Institute in Genoa at the time of the data collection. We collected the data from 3 blind and 14 low-vision children. The visual acuity of the collective group ranged from no perception of the light to visual acuity of 1/20 from an eye. To understand the level of cognitive impairment, the verbal IQ (QIV) and performance IQ (QIP) items of the Weschler Intelligence Scale for Children (WISC-IV) [45] were used as well as the IAG and the Griffiths-III [21] tests. Collectively, the cognitive tests

showed that 3 of the 17 children had levels of cognitive impairments.

### B. The mathematical problem-solving tasks

Following the procedure described in [37] with typical developing children, the data collection session started with an exploration of static representation of angles using child's arms, whose movements were supported with sonification technology. Sounds were realized using a tonal scale played by strings instruments, and the pitch was mapped to the inner angle (along the vertical plane) between child's arms. It was played in real-time, according to child's arms aperture (see Fig. 1).

In this activity, the child was trained to additionally use proprioceptive feedbacks and tactile information from a flat wall, used as a reference. Child's arms extended outwards ipsilaterally (and against the wall) to form 180 degrees angle. Extending one arm outward ipsilaterally and the other contralaterally the children formed 0 degrees angle while extending one arm outward ipsilaterally and the other in the anterior they created 90 degrees angle. For each child the task was first explained by the instructor, who helped their exploration of angles 0 degrees angle, 90 degrees angle and 180 degrees angle as described above. Next, they were encouraged to explore sounds feedbacks of their own. Finally, it was asked to the child to represent 45 degrees angle and 135 degrees angle. In the second task, each child was asked to represent 45 degrees angle (and 135 degrees angle) by rotating their body about the vertical axis. Differently from [37], the children were also trained to use proprioceptive and tactile feedbacks with a flat wall as reference: standing with the back flat against the wall represents 90 degrees angle. This additional proprioceptive and tactile exploration was suggested by the Blind psychotherapist working in the project.

## VI. ANNOTATION AND LABELING

From the video data, we extracted the episodes in which each child answered to given mathematical problems. We collected in this way 92 episodes with total duration of 12 minutes and 10 seconds. All the episodes were presented in random order and without audio information. Although in the literature there are findings suggesting that for learning related tasks, also untrained observers can provide reliable ratings, we decided firstly to ask to four experts (co-authors of this paper) to annotate each episode. The group was composed of one rehabilitation specialist from Chiossone Institute for visually impaired people, and three experts in movement analysis from University of Genoa. They used a 1-to-5 Likert scale, with 3 as neutral state, for each of the degrees of confidence and engagement. Each vote was a result of the informal consensus between all the experts. Meanwhile, they also discussed and jointly reported the nonverbal behaviors observed. The same experts propose a list of the 31 observed nonverbal behaviors (see Tab. I). For the second turn of annotations, we chose 20 episodes from the initial 92, which in the above mentioned ranking were annotated as representing high/low engagement

TABLE I  
THE LIST OF NONVERBAL BEHAVIORS AND THEIR FREQUENCIES OF APPEARANCE IN THE DATASET

Movement quality			Posture			Gesture		
<i>Id</i>	<i>Cues</i>	<i>%</i>	<i>Id</i>	<i>Cues</i>	<i>%</i>	<i>Id</i>	<i>Cues</i>	<i>%</i>
1	Focused, direct movement	34.44	10	Gaze down	38.99	21	Exp. of positive emotions (e.g. laughter)	18.33
2	Jerky movement	25.00	11	Tendency to act	25.00	22	Nervous smile or laughter	13.99
3	Hesitating movement	22.78	12	Listening predisposition	25.00	12	Open mouth	10.00
4	Fluid movement	21.11	13	Body as a reference point	20.00	21	Nodding during tasks resolution	7.88
5	Impulsive movement	20.00	14	Gaze contact with the interlocutor	18.33	25	Grabbing clothes	7.88
6	Inhibited movement	17.22	15	Withdraw from action	16.77	26	Rocking	7.88
7	Not goal-oriented movement	16.77	16	Outward-facing gaze	13.99	27	Lips biting	6.77
8	Slow movement	15.00	17	A loss of posture alignment	13.33	28	Deictic gestures	5.00
9	Misalignment		18	A loss of balance		29	Hands kept together	5.00
	of different body planes	11.11		(feet support instability)	13.32	30	Hands hold behind back	4.44
			19	Posture openness	8.89	31	Touching face or mouth	0
			20	Legs are moved while body is still	7.78			

and high/low confidence. Three experts (one psychomotrician and two specialists in orientation and mobility for visually impairments) and six non-experts annotated all 20 episodes displayed in random order. We decided to perform a second annotation of both experts and non experts to be able to consider whether particular patterns could be differently recognize by these two groups of annotators, meanwhile we expected the same types of observations by these three experts compared to those of the first round annotation. They were asked to indicate the relevant nonverbal behaviors from the list presented in Tab. I, and the perceived level of child's engagement and confidence (defined as above), using a Likert scale 1-5.

To measure the inter-rater agreement on perceived engagement and confidence, we computed two-ways random ICC average agreement of the Likert values. Results are 0.5291 for engagement and 0.4662 for confidence. We believe these results are acceptable considering the number of annotators, as well as the fact that only some of them were experts.

For what concerns the nonverbal behaviors annotation, we firstly computed frequency with which each cue was selected as relevant. The nonverbal behaviors 1) related to gaze direction, 2) movements qualities, such as directness, hesitation or jerkiness, 3) involvement or retraction from the action, and preparation to listen were frequently chosen as relevant annotating the dataset (see Tab. I).

To understand the relation between behaviors and the targeted cognitive states we computed annotation frequency of each behavior in only videos ranked as "high engagement" and "high confidence". We used the median value for each cognitive state (for engagement equal to 4 and for confidence to 3) as a threshold separating the episodes rated "high" from "low" ones. Next, for each behavior, we computed annotation frequency separately for videos above and below these thresholds. The most frequent behavior for each state can be read in Tab. II (high engagement), and Tab. III (high confidence). As it can be seen, only two of them are presented in both the states: *focused movement* and *tendency to act*. Thus, they can be indicators of both high engagement and confidence.

We used the same approach to find nonverbal cues of low engagement and confidence. Results in Tab. IV and V

showed that low level engagement and confidence are mostly expressed with *gaze down*, *jerky* and *hesitating movement* and *non goal-oriented movement*. Interestingly, some cues appear frequently for low levels of both cognitive states (e.g., *gaze down*, or *jerky movement*). As can be seen from the Tab. III-V some cues were frequently annotated 1) for both cognitive states 2) in high and low level of the same cognitive state. This might give to the Reader the impression that these cues are not discriminative. There can be, however, few possible explanations for this observation.

Regarding case 1), it is possible that such cues, e.g. *focused movement*, are relevant for a cognitive state only if they co-occur with some other behaviors. The sharing of specific cues between low confidence and engagement may also be explained by the fact that the two states often co-occur. Indeed frequently, low level of self-confidence tends to influence engagement and participation in task, especially considering the learning tasks and children's young age [13].

Regarding case 2), it is important to notice that some of the cues are binary (e.g., *appearance of laughter as expression of positive emotion*) while others can be considered as a continuous cues (e.g., *fluid movement*). In the case of continuous cues, it might be that different "degrees" of such a cue can be associated with different levels of the corresponding cognitive state. This example shows a shortcoming of our annotation schema, as so far we have not used the continuous scales for the annotation of the nonverbal behaviors. Thus, future works are needed to address this shortcoming.

TABLE II  
CUES ASSOCIATED WITH HIGH-LEVEL OF ENGAGEMENT ANNOTATION, EXPRESSED IN FREQUENCY ABOVE MEDIAN VALUE.

<i>id</i>	<i>Nonverbal Cues</i>	<i>% Annotation Frequency</i>
1	Focused, direct movement	25.56
11	Tendency to act	18.99
12	Listening predisposition	17.22
4	Fluid movement	16.11
21	Expressing positive emotions (e.g. laughter)	15.00

Considering these preliminary results and the final aim of

TABLE III  
CUES ASSOCIATED WITH HIGH-LEVEL OF CONFIDENCE ANNOTATION,  
EXPRESSED IN FREQUENCY ABOVE MEDIAN VALUE.

id	Nonverbal Cues	% Annotation Frequency
1	Focused, direct movement	31.66
11	Tendency to act	21.77
10	Gaze down	21.11
12	Listening predisposition	15.66
5	Impulsive movement	15.00

TABLE IV  
CUES ASSOCIATED WITH LOW-LEVEL OF ENGAGEMENT ANNOTATION,  
EXPRESSED IN FREQUENCY BELOW MEDIAN VALUE.

id	Nonverbal Cues	% Annotation Frequency
10	Gaze down	19.44
2	Jerky movement	13.89
15	Withdraw from the action	12.78
3	Hesitating movement	10.56
7	Not goal-oriented movement	10.56

the work, it is interesting to highlight that cues as gaze, generally considered as one of the fundamental cue in video detection of children and students engagement [40], [42], had a relevant role for human annotators also in the context of visually impaired people, especially in the case of low engagement and confidence. Literature on early-social cognitive development, deeply analyzed the use of gaze, starting from infancy, as a privileged cue of social interaction and others' attention and intention. When *mutual gazed* occurs, according to theorists [30], it is a sign of social engagement and mutual interaction, while *following gaze* is considered a sign of understanding others' attention. *Gaze alternation*, in dyadic or group interaction, is used to assessed joint attention [1]. Those cues were largely considered, for example, in understanding engagement in autistic children [10]. From the literature, we know that blind children have difficulties on detecting patterns of social interactions, meanwhile sighted people surrounded them may have difficulties assessing where a blind child focuses her attention, since there is neither visual orienting and pointing, and gazing and facial expressions are more neutral [5]. For this reason, we may suppose that the absence of such common patterns of joint attention and engagement, leded annotators (who were in majority non-experts), to consider still position of gaze, looking down, as a cue of both lack of

TABLE V  
CUES ASSOCIATED WITH LOW-LEVEL OF CONFIDENCE ANNOTATION,  
EXPRESSED IN FREQUENCY BELOW MEDIAN VALUE.

id	Nonverbal Cues	% Annotation Frequency
10	Gaze down	19.44
3	Hesitating movement	14.44
2	Jerky movement	13.33
6	Inhibited movement	10.00
7	Not goal-oriented movement	10.00

engagement and self-confidence, as this is how it is perceived by typical development people in social interaction contexts. To check this hypothesis (and be able to perform comparative analysis between non-experts and experts), we need, however, to collect more annotation from experts.

## VII. AUTOMATED CLASSIFICATION

### A. Features extraction

To check whether it is possible to detect the levels of engagement and confidence from visual data in the context of single-user task we performed a series of preliminary experiments with standard machine learning techniques on the dataset presented in Section V. Due to small number of the annotated episodes, we subdivided them into smaller segments of fixed duration of 50 frames (corresponding to 1 second), obtaining 758 segments. The labels for each of the two states were not balanced. The same shortcoming was observed after the sub-segmentation. Thus, we decided to regroup the rates: 1) levels 3 and 4 on the engagement scale were regrouped into high level engagement, 2) levels 1 and 2 on the confidence scale were regrouped into low engagement level. We obtained in this way, 294 segments for high engagement, 176 for medium and 288 for low engagement and 172 segments for high confidence, 317 for medium and 269 segments for low confidence. 15 features were extracted from 2D positional data obtained by applying OpenPose [7] to the frontal view recordings. The features are computed on 1) front head, 2) left and right elbow, 3) left and right knee, 4) Cervical vertebrae (C7). First eight features compute low-level kinematics features: *Right* and *Left Arm Position Variances*, *Velocities*, *Kinetic Energies*, *Head Velocity* and *Kinetic Energy*. *Head Side Leaning* is computed as a difference between the x coordinate of the head and the mean of the x coordinates of the upper limbs. The algorithm by [32] is used to compute *Right Arm and Left Arm Stability*, [2] to compute *Arms Fluidity Index* and [8] to compute *Closure Area*. *Body Symmetry Index* is the sum of: 1) the sum of absolute differences between X (resp. Y) coordinates of the upper body limbs and C7, 2) the absolute difference of the head and C7 X coordinates. Finally *Foot Symmetry* is computed as the distance between the X coordinates of the child lower body limbs and C7 X coordinate. It is important to state that these features cover only a subset of the cues listed in Tab. III- V. The kinematics features are low-level components of various expressive qualities (first column of Tab. I), such as fluidity or impulsivity, [6]. The remaining features correspond to some of observed postures and gestures (second and third column of Tab. I), e.g., loss of balance (19), posture openness (20).

Next, three aggregation operators (average, maximum, and minimum) were applied to the values computed on the single observations. Thus, a 45-feature vector was used for each segment. Finally, the data was normalized using the z-normalization method.

## B. Classification

We performed a set of machine learning experiments to automatically classify 3 levels of confidence and engagement (low, medium, high) from video data. We explored a set of traditional machine learning algorithms: Support Vector Machine with polynomial (SVM-poll) and radial basis kernel (SVM-rbf), Random Forest (RF), BayesNet (BN), and Multi-Layer Perceptron (MLP). The experiments were performed using feature reduction techniques and dimensionality reduction technique:

- PCA - 16 principal components extracted from the data (obtained with a threshold of 95% of variance covered),
- Greedy - 12 features obtained from Greedy Stepwise Search combined with Correlation-based Feature Selection.

We have used 10-fold validation procedure. The results for the three-class classification task are shown in Table VI. All experiments were performed in Weka 3.8 software <sup>2</sup>.

## C. Discussion

As can be seen in Table VI, the best results were obtained with Random Forest and Greedy feature reduction. In general, the results are not perfect, but it has to be taken into account that the experiments were performed on noisy 2D data extracted using OpenPose. Some of the tasks given to the children required the rotation of the whole body, leading to a lack of 2D data during child's rotation. We believe that the results could improve using 3D positional data (e.g., from Kinect or Notch). The other important shortcoming of this experiment to be noticed is that we have not implemented so far the algorithms to compute features for all relevant cues from Tab. III- V. By implementing the remaining cues we hope in future to improve the classification results.

TABLE VI  
RESULTS (IN TERMS OF F-SCORE) FOR 3-CLASS CLASSIFICATION TASK

	Engagement		Confidence	
	PCA	Greedy	PCA	Greedy
SVM-rbf	0.63	0.63	0.6	0.62
SVM-poll	0.61	0.56	0.56	0.57
RF	0.65	0.73	0.61	0.7
MLP	0.57	0.54	0.49	0.5
BayesNet	0.52	0.6	0.47	0.56

## VIII. CONCLUSIONS AND FUTURE STEPS

In accordance to the the main theme of this year conference which is Affective Computing for ALL (AC4ALL), in this paper we focused on the specific group of users of AC technology. We hope that this work may help include such specific-needs users to beneficiaries of the AC technologies. In particular, we analyzed full-body indicators of engagement and confidence in visually impaired primary school children. A two steps annotation was performed by expert and non expert annotators to identify a set of nonverbal cues of engagement

and confidence. We also proposed a preliminary classification models of engagement and confidence levels from a set of cues extracted from 2D positional data.

The main contributions of the paper are:

- to the authors knowledge, this is the first analysis of the nonverbal full-body cues of cognitive states in visually impaired children, and a first attempt to create a model of descriptors of nonverbal full-body communication for visually impaired children in learning context
- it is one of the first attempts to automatically classify the confidence levels in context of the single-user learning tasks

As future steps, we plan to perform a similar analysis of nonverbal behaviors in the same context on control group of sighted children to further understand differences and commonalities in nonverbal behaviors compared to visually impaired ones. As part of future works, then, we will record more children's data, and extend, through other rounds of human annotation, the nonverbal behaviors model. Even if first results of the automatic classification are promising, we will extract more features to improve the results, as well as we will test different machine learning techniques. The other possible extensions involve the multimodal data collection and classification. For this purpose we consider using low-intrusive wearable sensors that can be used to collect the data of children activity without violate their privacy, such as IMU and EMG sensors.

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