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**HARMONIC SUPERSPACE FORMALISM AND
THE CONSISTENT CHIRAL ANOMALY *†**

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HARMONIC SUPERSPACE FORMALISM AND THE CONSISTENT CHIRAL ANOMALY

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The harmonic superspace formalism has been used to construct the consistent chiral anomaly in $N = 1, d = 6$ supersymmetric Yang-Mills theory. The expressions of the gauge anomaly Δ_μ^\dagger and of the supersymmetric anomaly Δ_{SUSY}^\dagger are given together with the consistent condition.

The consistent chiral anomaly in $N = 1, d = 4$ supersymmetric Yang-Mills theory has been studied intensively. For higher dimension, due to the difficulties to get an unconstrained superspace formulation, it has been studied only in the Wess-Zumino gauge by Itoyama *et al*¹⁾, who have found an $N = 1, d = 6$ nontrivial supersymmetric anomaly. The aim of this work is to get the $N = 1, d = 6$ supersymmetric consistent anomalies by using the harmonic superspace formulation^{2),3)}.

For six dimensions, the use of the $d = 6$ $SU(2)$ Majorana-Weyl spinors^{4),5)} leads to a manifestly $SU(2)$ covariant formulation, which is naturally incorporated into the harmonic superspace formalism.

The $N = 1, d = 6$ harmonic superspace is parametrized by

$$\{z^M, u_i^\pm\} \quad (1)$$

in the central basis, where $z^M = (x^m, \theta_\alpha^i)$, ($m = 0, \dots, 5, i = 1, 2, \alpha = 1, \dots, 4$) parametrize the ordinary superspace, u_i^\pm , the harmonic variables, parametrize the coset space.

The SUSY transformation is given by

$$\begin{aligned} \delta x^m &= \frac{i}{2} \epsilon_i^\alpha \Sigma_{\alpha\beta}^m \theta^{\beta i} \\ \delta \theta_{\alpha i} &= \epsilon_{\alpha i} \\ \delta u_i^\pm &= 0 \end{aligned} \quad (2)$$

where $\Sigma_{\alpha\beta}^m$ are 4×4 antisymmetric matrices.

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We can pass from the central basis $\{z^M, u_i^\pm\}$ to the analytic basis, defined by

$$A.B. : \{z_A^M = (x_A^m, \theta_\alpha^+, \theta_\alpha^-), u_i^\pm\}, \quad (3)$$

where the new independent variables are related to the old ones as follows

$$\begin{aligned} x_A^m &= (x^m + \frac{i}{2} \theta_{(i}^\alpha \Sigma_{\alpha\beta}^m \theta_{j)}^\beta) u^{+i} u^{-j}, \\ \theta^{\pm\alpha} &= u^{\pm i} \theta_i^\alpha \end{aligned} \quad (4)$$

In the analytic basis, the $N = 1, d = 6$ SUSY is realized as

$$\begin{aligned} \delta x_A^m &= \frac{i}{2} (\epsilon_i^\alpha \Sigma_{\alpha\beta}^m \theta^{+\beta}) u^{-i} \quad \delta \theta_\alpha^+ = \epsilon_\alpha^i u_i^+ \\ \delta \theta_\alpha^- &= \epsilon_\alpha^i u_i^- \quad \delta u_i^\pm = 0. \end{aligned} \quad (5)$$

Since $x_A^m, \theta_\alpha^+, u_i^\pm$, form a subset closed under $N = 1, d = 6$ SUSY transformations, we get the analytic subspace,

$$\{z_A^M = (x_A^m, \theta_\alpha^+), u_i^\pm\}. \quad (6)$$

In the analytic basis, the harmonic derivative D^{++} becomes

$$D^{++} = u^{i+} \frac{\partial}{\partial u^{i-}} = \frac{\partial}{\partial u^{i-}} + \frac{i}{2} \theta^{+\alpha} \Sigma_{\alpha\beta}^m \theta^{+\beta} \frac{\partial}{\partial x^m} + \theta_\alpha^+ \frac{\partial}{\partial \theta_\alpha^-} \quad (7)$$

and the spinor derivatives are decomposed into D^\pm parts:

$$D_\alpha^+ = \frac{\partial}{\partial \theta^{-\alpha}}, \quad D_\alpha^- = \frac{\partial}{\partial \theta^{+\alpha}} + i \Sigma_{\alpha\beta}^m \theta^{-\beta} \frac{\partial}{\partial x_A^m} \quad (8)$$

The fact that D_α^+ are reduced to simple derivatives with respect to θ^- reflects the existence of the invariant analytic subspace. Therefore in the analytic basis, we can define superfields which do

not depend on θ^- and are analytic automatically,

$$F^{(a)}(x_A, \theta^+, u^\pm), \quad D_\alpha^+ F^{(a)} \equiv 0. \quad (9)$$

The unconstrained off-shell formulation just relies on the use of the real analytic superfields.

The exterior differential d in the harmonic super-space can be split as follows

$$d = \hat{d} + D + \hat{D}$$

where $\hat{d} = e^{\alpha\beta} \partial_{\alpha\beta}$, $D = e^{\alpha i} D_{\alpha i}$, $\hat{D} = e^a D_a$, with $D_a = (D^{++}, D^{--})$. The rigid vielbeins e^A are 1-superforms, with the property

$$de^A = t_{BC}^A e^C e^B$$

$$t_{\alpha i, \beta j}^{\gamma l} = -i \epsilon_{ij} \delta_{[\alpha\beta]}^{\gamma l}.$$

From the constraints $F_{\alpha\beta}^{++} = 0$, $F^{++,-} = 0$ we can solve for φ_α^+ and φ^{++} , φ^{--}

$$\varphi_\alpha^+ = e^{-U} D_\alpha^+ e^U$$

$$\varphi^{++} = e^{-V} D^{++} e^V$$

$$\varphi^{--} = e^{-V} D^{--} e^V$$

From $F_\alpha^{+++} = 0$ we can get the important relation

$$D_\alpha^+ V^{++} = 0 \quad (10)$$

$$V^{++} = e^U e^{-V} D^{++} (e^V e^{-U})$$

As φ_A have been obtained, the gauge transformations can be expressed as

$$e^U \rightarrow e^X e^U e^K, \quad D_\alpha^+ X = 0, \quad (11)$$

$$e^V \rightarrow e^Y e^V e^K, \quad D^{++} Y = 0. \quad (12)$$

where K is the gauge transform parameter. By using a K gauge transformation the V can be set to zero, $V = 0$, and hence $\varphi^{++} = \varphi^{--} = 0$. Now (10) becomes $V^{++} = e^U D^{++} e^{-U}$ which can be reduced to

$$(D^{++} + V^{++}) e^U = 0 \quad (13)$$

Equation (13) can be solved to express the prepotential U in terms of the unconstrained analytic superfield V^{++} .

The gauge transformations can be expressed by the exterior differential operator in gauge group space^(6,7)

$$s = \sum_i dt_i \frac{\partial}{\partial t_i} \quad (14)$$

where t^i are all parameters the gauge group elements may depend on.

The following notations are introduced to express the gauge transformed quantities

$$e^v = e^X e^V e^K$$

$$e^u = e^X e^U e^K$$

$$\phi = e^{-K} \varphi e^K + e^{-K} d e^K$$

$$\mathcal{F} = d\phi + \phi\phi$$

We denote $c = e^{-K} s e^K$, $c' = e^X s e^{-X}$ where c, c' are \mathcal{G} -valued 1-forms in t space.

We can get

$$s e^v = s(e^X e^V e^K) = -c' e^v + e^v c \quad (15)$$

$$s e^u = s(e^X e^U e^K) = -c' e^u + e^u c \quad (16)$$

$$s\phi = [\phi, c] - dc$$

$$sc = -c^2 \quad (17)$$

which coincide with B.R.S. transformations.

The transgression formula⁽⁶⁾ is therefore still true, and we consider the following for $d = 6$,

$$Tr(\mathcal{F}\mathcal{F}\mathcal{F}\mathcal{F}) = (d+s)\Omega \quad (18)$$

$$\Omega = \int_0^1 dt$$

$$str((\phi+c), \hat{\mathcal{F}}_1, \hat{\mathcal{F}}_2, \hat{\mathcal{F}}_3) = t(d+s)(\phi+c) + t^2(\phi+c)(\phi+c) \quad (19)$$

The operator S_{SUSY} corresponding to rigid supersymmetry is defined by acting on superfields ψ integrated over space-time,

$$S_{SUSY} \int_x \psi = \int_x \epsilon^A D_A \psi = \int_x (\epsilon^{\alpha i} D_{\alpha i}) \psi \quad (20)$$

where $\epsilon^A = (\epsilon^{\gamma\gamma'}, \epsilon^{\alpha i}, \epsilon^a) \equiv (0, \epsilon^{\alpha i}, 0)$ are parameters with the same commuting properties as dx^A , i.e., the spinor like $\epsilon^{\alpha i}$ are commuting among themselves. The reason we put $\epsilon^a = 0$ is that supersymmetry is realized with $\delta u_i^\pm = 0$; also we may set the space-time like $\epsilon^{\gamma\gamma'} = 0$ because they occur under space-time integration. Due to the commuting property of $\epsilon^{\alpha i}$, S_{SUSY} is nilpotent when acting on space-time integrals of superfields,

$$S_{SUSY}^2 = 0 \quad (21)$$

To construct consistent SUSY anomaly, we start from the transgression formula (19). The 7-superform

Ω can be split according to the powers of c , and by the number of factors of the vielbeins e^A with different dimensions, i.e., $q_1, q_2, (7-p) - q_1, -q_2$, which denote the number of the factors of the spinor-like vielbeins, e^{a_i} , the harmonic-like vielbeins e^a , and the space-time like vielbein $e^{\tau\tau'}$ respectively. Therefore, equation (18) contains different sets of identities, one for each sector. We depict the following,

$$p = 0, q_1 = 2, q_2 = 0 :$$

$$\text{str}(\mathcal{F}\mathcal{F}\mathcal{F}\mathcal{F})_{\delta,2,0} = d\omega_{\delta,2,0}^0 + [D\omega_{\delta,1,0}^0]_{\delta,2,0} \quad (22)$$

$$p = 1, q_1 = 0, q_2 = 0 :$$

$$0 = s\omega_{\delta,1,0}^0 + \hat{d}\omega_{\delta,1,0}^1 + [D\omega_{\delta,0,0}^1]_{\delta,1,0} \quad (23)$$

$$p = 2, q_1 = 0, q_2 = 0 : 0 = s\omega_{\delta,0,0}^1 + \hat{d}\omega_{\delta,0,0}^2 \quad (24)$$

After some calculation, we can get the final result,

$$s\Delta_S^\dagger = 0 \quad (25)$$

$$S_{SUSY}\Delta_{SUSY}^\dagger = 0 \quad (26)$$

$$s\Delta_{SUSY}^\dagger + S_{SUSY}\Delta_S^\dagger = 0 \quad (27)$$

where

$$\Delta_S^\dagger = \int_{\mathbb{R}^4} \omega_{\delta,0,0}^1$$

$$\Delta_{SUSY}^\dagger = \int_{\mathbb{R}^4} i_\epsilon \hat{\omega}_{\delta,1,0}$$

The notation $i_\epsilon \chi_m$ denotes the interior product of the m -superforms χ_m with respect to ϵ^M , where

$$\epsilon^M = \epsilon^A e_A^M \quad (28)$$

and e_A^M are the inverse vielbeins,

$$i_\epsilon \chi_m = \epsilon^{A_1} e^{A_2} \dots e^{A_m} \chi_{A_m} \dots A_1$$

Equations (25), (26) and (27) are the consistency conditions and $\Delta_S^\dagger, \Delta_{SUSY}^\dagger$ are the gauge anomaly and supersymmetric anomaly respectively. $\Delta_S^\dagger, \Delta_{SUSY}^\dagger$ can be expressed by

$$\Delta_S^\dagger = 12 \int_{\mathbb{R}^4} \int_0^1 dt (1-t) [\text{str}(cd\phi \underline{\mathcal{F}}t \underline{\mathcal{F}}t)]_{\epsilon=0} \quad (29)$$

$$\Delta_{SUSY}^\dagger = -12 \int_{\mathbb{R}^4} \int_0^1 dt$$

$$\text{str} \left\{ \epsilon^a \left[\phi(\mathcal{F}_i)_{\alpha_i} \underline{\mathcal{F}}_i \underline{\mathcal{F}}_i - \frac{1}{3} \phi_\alpha \underline{\mathcal{F}}_i \underline{\mathcal{F}}_i \underline{\mathcal{F}}_i - \frac{i}{64} (\mathcal{F}_{\alpha_i} \underline{\mathcal{F}}_{\alpha_j} \epsilon^{i_1 i_2} \delta^{[\alpha_2, \alpha_1]} \mathcal{F}_{\alpha_1 i_1}) \right] \right\}_{\epsilon=0} \quad (30)$$

where

$$\begin{aligned} \phi &= e^{\tau\tau'} \phi_{\tau\tau'}, \\ \mathcal{F}_{\alpha_i} &= e^{\tau\tau'} \mathcal{F}_{\alpha_i \tau\tau'}, \\ \underline{\mathcal{F}} &= e^{(\tau\tau')_1} e^{(\tau\tau')_2} \mathcal{F}_{(\tau\tau')_2 (\tau\tau')_1}, \\ \delta^{[\alpha_2, \alpha_1]} &= e^{\tau\tau'} \delta_{\tau\tau'}^{[\alpha_2, \alpha_1]}. \end{aligned} \quad (31)$$

and similar definitions for \mathcal{F}_i and $(\mathcal{F}_i)_{\alpha_i}$.

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