Modularity in Computer Assisted Reasoning Systems

Alessandro Agostini* LOMIT - Dipartimento di Matematica Universita degli Studi di Siena via del Capitano, 15 53100 Siena - Italy

1 Problem being addressed

An important problem in the domain of automated reasoning is the development of mechanisms for the integration of disparate provers. The components of a prover may be based on different logics, they may have different domain models, they may use different representations of information and reasoning strategies, and they may have different interaction capabilities. The need for composing complex provers from existing modules, and to add new modules to existing provers is motivated by the desire of not having to build from scratch a new prover for each new problem or variation of an old problem. Multilogic provers are needed in many formalization problems, such as hardware and software verification. Multi-logic provers are also needed in complex applications which require embedding of reasoning modules inside other systems. Some examples are: program transformation systems, including synthesis; partial evaluation and compiling: planning systems: intelligent agents: and natural language systems.

2 Thesis objectives

Our ultimate goal is to provide a framework and a methodology which will allow users, and not only developers, to construct complex reasoning systems by composing existing modules, or to add new modules to existing systems. These modules and systems might be based on different logics; have different domain models; use different vocabularies and data structures: use different reasoning strategies. The thesis proposal makes two main contributions towards our goal. First, it proposes a formal notation (FB-Hypersequents) for presenting the syntax and semantics of reasoning theories of Open Mechanized Reasoning Systems (OMRSs) as stated in [Giunchiglia et a/., 1994]. Second, it developes the theory underlying the control component - which consists of a set of inference strategies - of OMRSs . This development is motivated by an analysis of (logical) consequence relation in general, and especially its possible relations with computational issues. Some of the problems that the thesis proposal addresses are general problem of

•Also Mechanized Reasoning Group DISA, Universita di Trento, Via Inama, 1 - 38100 Trento, Italy.

modularization, composability, and interoperability that are not specific to the domain of automated reasoning. As the ideas and techniques become better developed, we expect that general principles will emerge that can be used in other research areas.

3 Proposed work plan

We are in the middle of a long term project [Giunchiglia et a/.. 19941 which still needs to be developed in many The thesis is organized into two main In the first phase we define the forwork phases. mal framework for representing the syntax and semantics of reasoning theories of OMRSs. In particular, we (1) define the language and the central notion of FB-hypersequent, its syntax and semantics; For doing this, we expect to use some previous works on formal bidirectional natural deduction such as [Agostini, 1992; 1993]; (2) extend FB-hypersequents to formalize the sequent systems inside reasoning theories, and illustrate, with examples, the uniformity of our framework for a diversity of logics (reasoning theories); (3) add a semantical component to our framework and provide for a notion of model for reasoning theories.

In the second phase we study the computational properties of reasoning theories as formalized in the first phase by FB-hypersequents. These properties provide for the amount of computational information needed by reasoning systems to guide search proof, and in some case to reduce the search space.

References

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